

Proposal Distribution

Proposal Distribution: Two basic approaches

- Choose a fixed proposal function
 - Independent Metropolis
- Random walk (local Metropolis)

$$\theta^* = \theta^{k-1} + Rz$$

◦ Two (of several) choices: $Z \sim N(0, 1)$

(i) $R = cI \Rightarrow \theta^* \sim N(\theta^{k-1}, cI)$

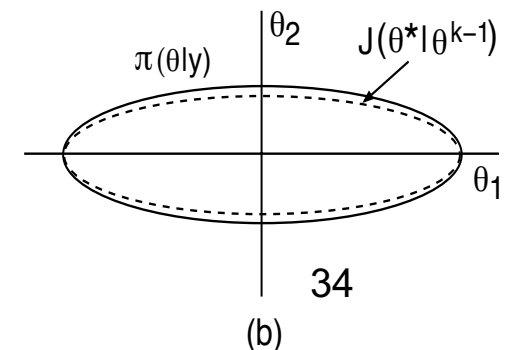
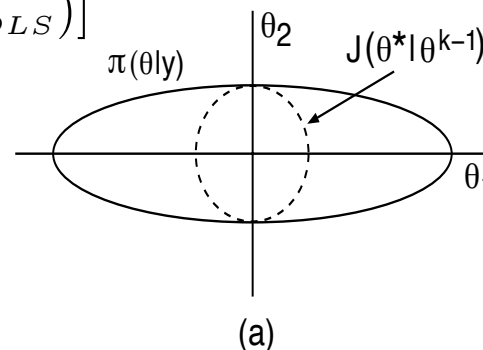
(ii) $R = \text{chol}(V) \Rightarrow \theta^* \sim N(\theta^{k-1}, V)$

where

$$V = \sigma_{OLS}^2 [\mathcal{X}^T(\theta_{OLS}) \mathcal{X}(\theta_{OLS})]^{-1}$$

$$\sigma_{OLS}^2 = \frac{1}{n-p} \sum_{i=1}^n [y_i - f_i(\theta_{OLS})]^2$$

Sensitivity Matrix



Metropolis Algorithm

Metropolis Algorithm: [Metropolis and Ulam, 1949]

1. Initialization: Choose an initial parameter value θ^0 that satisfies $\pi(\theta^0|y) > 0$.

2. For $k = 1, \dots, M$

(a) For $z \sim N(0, 1)$, construct the candidate

$$\theta^* = \theta^{k-1} + Rz$$

where R is the Cholesky decomposition of V or D . This ensures that

$$\theta^* \sim N(\theta^{k-1}, V) \text{ or } \theta^* \sim N(\theta^{k-1}, D).$$

(b) Compute the ratio

$$r(\theta^*|\theta^{k-1}) = \frac{\pi(\theta^*|y)}{\pi(\theta^{k-1}|y)} = \frac{\pi(y|\theta^*)\pi_0(\theta^*)}{\pi(y|\theta^{k-1})\pi_0(\theta^{k-1})}. \quad (1)$$

(c) Set

$$\theta^k = \begin{cases} \theta^* & , \text{ with probability } \alpha = \min(1, r) \\ \theta^{k-1} & , \text{ else.} \end{cases}$$

That is, we accept θ^* with probability 1 if $r \geq 1$ and we accept it with probability r if $r < 1$. 35

Metropolis-Hastings Algorithm

Metropolis-Hastings Algorithm: $J(\theta^*|\theta^{k-1})$ does not have to be symmetric

- **Acceptance Ratio:**
$$r(\theta^*|\theta^{k-1}) = \frac{\pi(\theta^*|y)/J(\theta^*|\theta^{k-1})}{\pi(\theta^{k-1}|y)/J(\theta^{k-1}|\theta^*)}$$
$$= \frac{\pi(y|\theta^*)\pi_0(\theta^*)J(\theta^{k-1}|\theta^*)}{\pi(y|\theta^{k-1})\pi_0(\theta^{k-1})J(\theta^*|\theta^{k-1})}.$$

Examples:

- Cauchy distribution: $J(\theta^*|\theta^{k-1}) = \frac{1}{\pi[1+(\theta^*)^2]}$
- $\chi^2(k)$ distribution: $J(\theta^*|\theta^{k-1}) = \kappa(\theta^*)^{k/2-1} e^{\theta^*/2}$

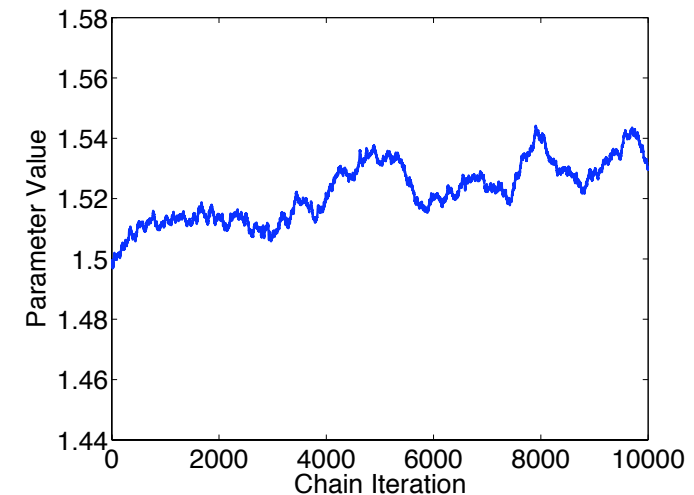
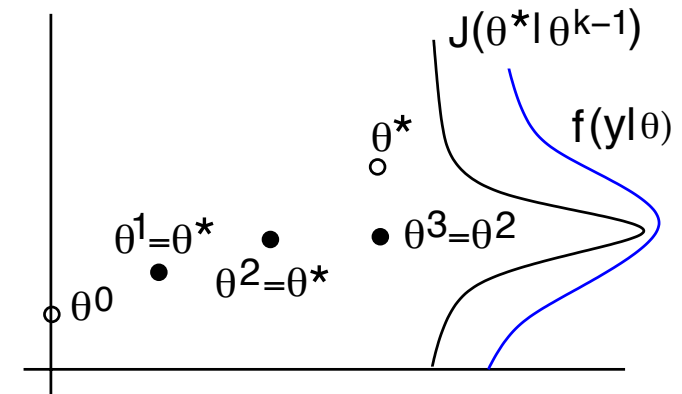
Note: Considered one of top 10 algorithms of 20th century

Random Walk Metropolis Algorithm for Parameter Estimation

1. Set number of chain elements M and design parameters n_s, σ_s
2. Determine $\theta^0 = \arg \min_{\theta} \sum_{i=1}^N [y_i - f_i(\theta)]^2$
3. Set $SS_{\theta^0} = \sum_{i=1}^N [y_i - f_i(\theta^0)]^2$
4. Compute initial variance estimate: $s_0^2 = \frac{SS_{\theta^0}}{n-p}$
5. Construct covariance estimate $V = s_0^2 [\mathcal{X}^T(\theta^0) \mathcal{X}(\theta^0)]^{-1}$ and $R = \text{chol}(V)$
6. For $k = 1, \dots, M$
 - (a) Sample $z_k \sim N(0, 1)$
 - (b) Construct candidate $\theta^* = \theta^{k-1} + Rz_k$
 - (c) Sample $u_{\alpha} \sim \mathcal{U}(0, 1)$
 - (d) Compute $SS_{\theta^*} = \sum_{i=1}^N [y_i - f_i(\theta^*)]^2$
 - (e) Compute

$$\alpha(\theta^* | \theta^{k-1}) = \min \left(1, e^{-[SS_{\theta^*} - SS_{\theta^{k-1}}] / 2s_{k-1}^2} \right)$$
 - (f) If $u_{\alpha} < \alpha$,
 Set $\theta^k = \theta^*$, $SS_{\theta^k} = SS_{\theta^*}$
 else
 Set $\theta^k = \theta^{k-1}$, $SS_{\theta^k} = SS_{\theta^{k-1}}$
 endif
 - (g) Update $s_k \sim \text{Inv-gamma}(a_{val}, b_{val})$ where

$$a_{val} = 0.5(n_s + n), \quad b_{val} = 0.5(n_s \sigma_s^2 + SS_{\theta^k})$$



Sampling Error Variance

Strategy: Treat error variance σ^2 as parameter to be sampled.

Definition: The property that the prior and posterior distributions have the same parametric form is termed *conjugacy*.

Note: The likelihood

$$f(\mathbf{y}, \theta | \sigma^2) = \frac{1}{(2\pi\sigma^2)^{n/2}} e^{-SS_\theta / 2\sigma^2}$$

has the conjugate prior

$$\pi_0(\sigma^2) \propto (\sigma^2)^{-(\alpha+1)} e^{\beta/\sigma^2}$$

The posterior is

$$\pi(\sigma^2 | \theta, \mathbf{y}) \propto (\sigma^2)^{-(\alpha+1+n/2)} e^{-(\beta+SS_\theta/2)/\sigma^2}$$

so that

$$\sigma^2 | (\mathbf{y}, \theta) \sim \text{Inv-gamma} \left(\alpha + \frac{n}{2}, \beta + \frac{SS_q}{2} \right)$$

or

$$\sigma^2 | (\mathbf{y}, \theta) \sim \text{Inv-gamma} \left(\frac{n_s + n}{2}, \frac{n_s \sigma_s^2 + SS_q}{2} \right)$$

Note:

- n_0 taken small;
e.g., $n_0 = 1$ or $n_0 = .01$
- Take $\sigma_s^2 = \mathbf{s}_{k-1}^2 = \frac{R_{k-1}^T R_{k-1}}{n-p}$

Random Walk Metropolis

Example: We revisit the spring model

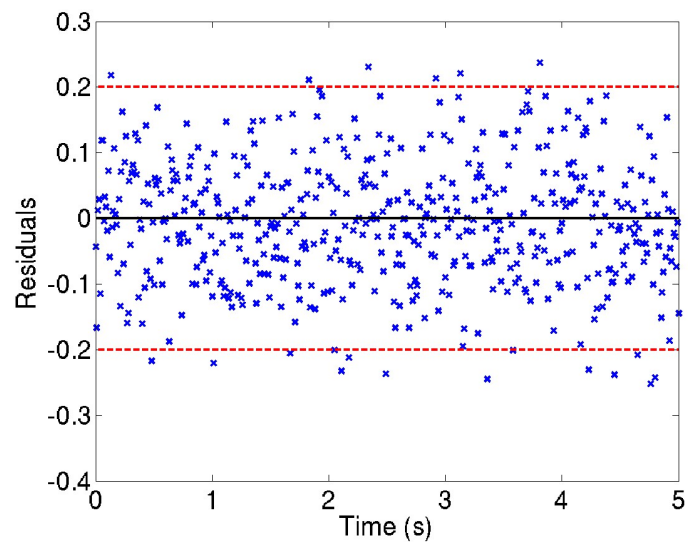
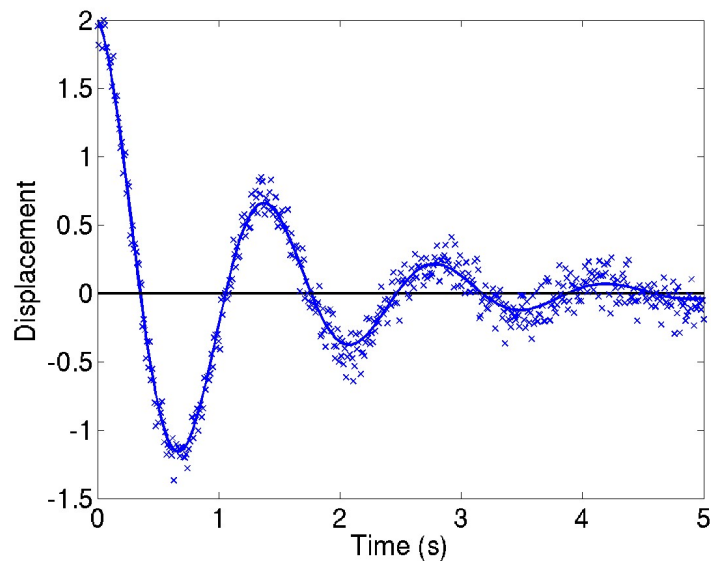
$$\ddot{z} + C\dot{z} + Kz = 0$$

$$z(0) = 2, \dot{z}(0) = -C$$

which has the solution

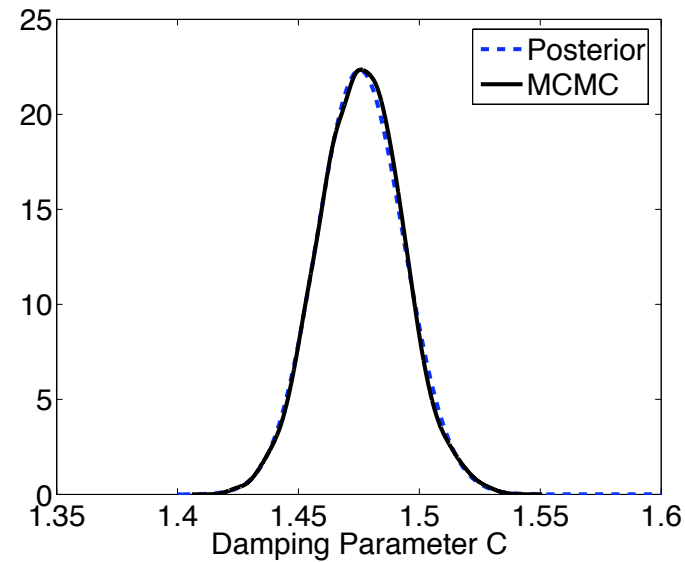
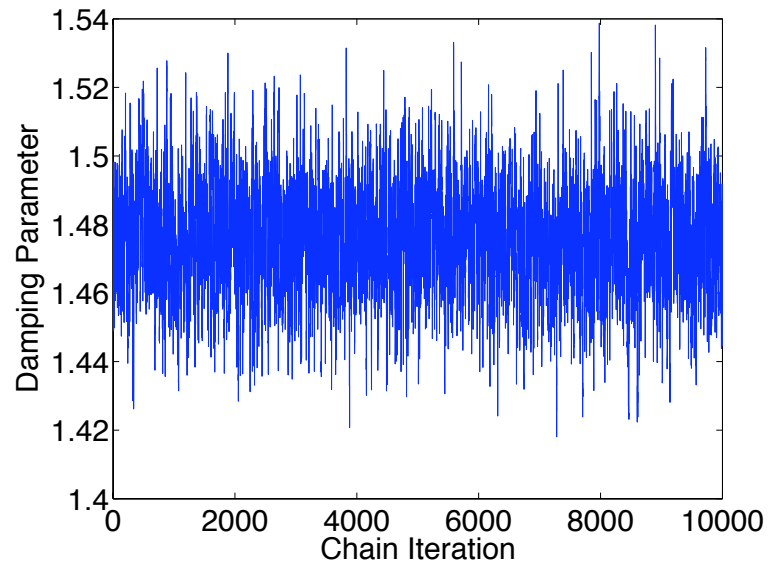
$$z(t) = 2e^{-Ct/2} \cos(\sqrt{K - C^2/4} \cdot t)$$

We assume that $\varepsilon_i \sim N(0, \sigma_0^2)$ where $\sigma_0 = 0.1$.



Random Walk Metropolis

Case i: Take $K = 20.5$ and $\theta = [C, \sigma^2]$

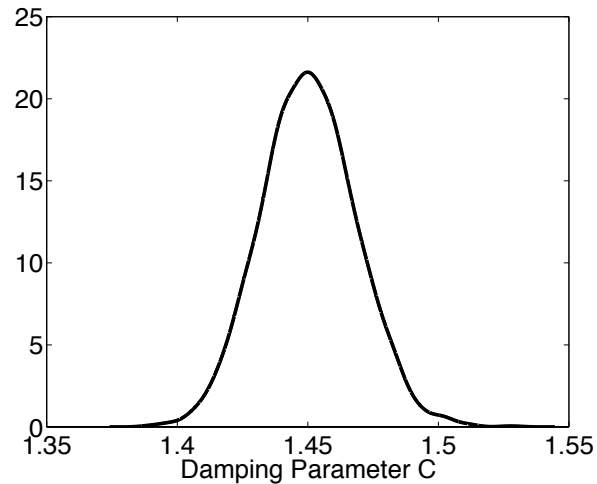
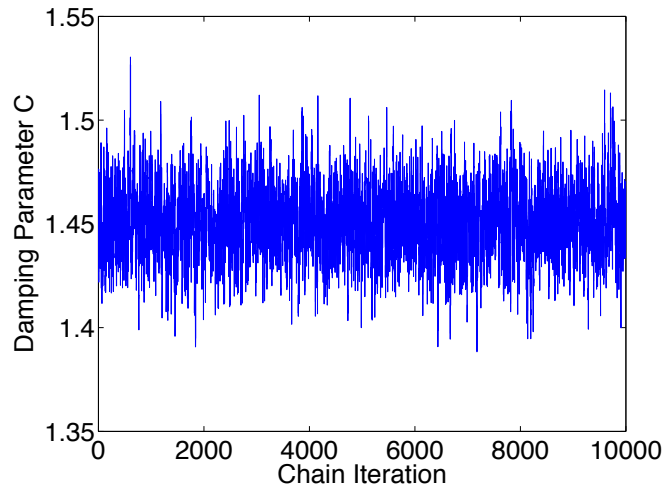


Note: Kernel density estimator (KDE) used to construct density.

Random Walk Metropolis

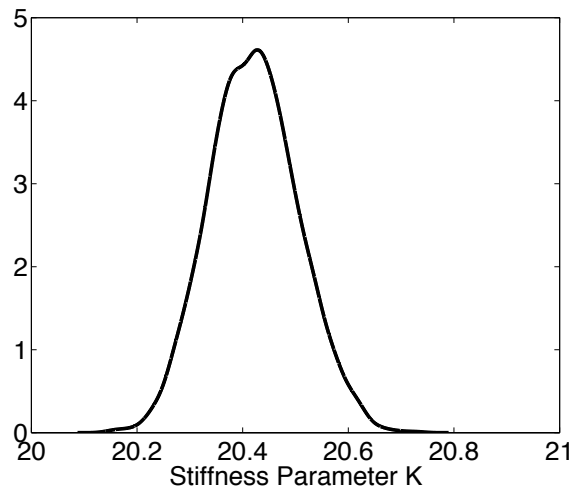
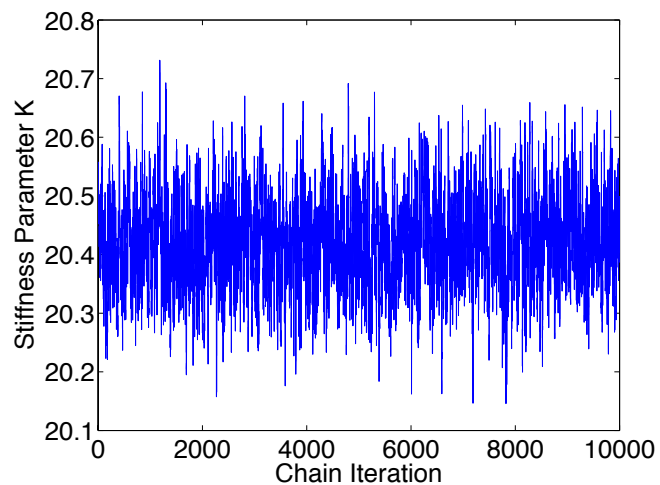
Case ii: Take $\theta = [C, K, \sigma^2]$ with $J(\theta^*|\theta^{k-1}) = N(\theta^{k-1}, V)$ and

$$V = \begin{bmatrix} 0.000345 & 0.000268 \\ 0.000268 & 0.007071 \end{bmatrix}$$



Note:

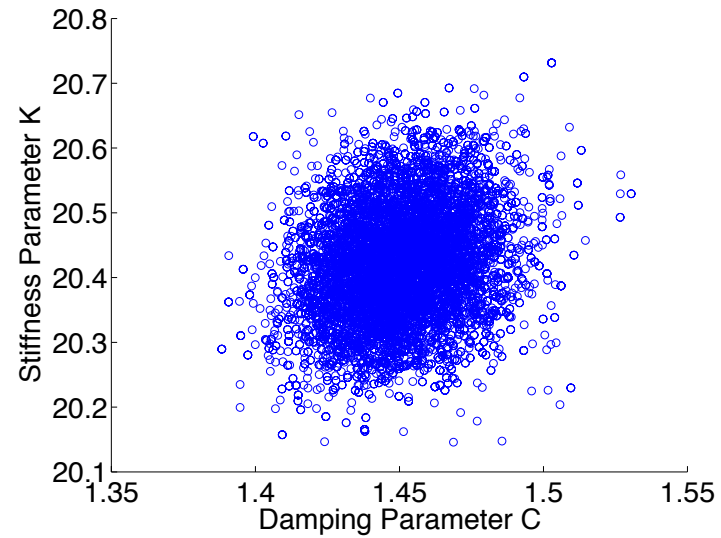
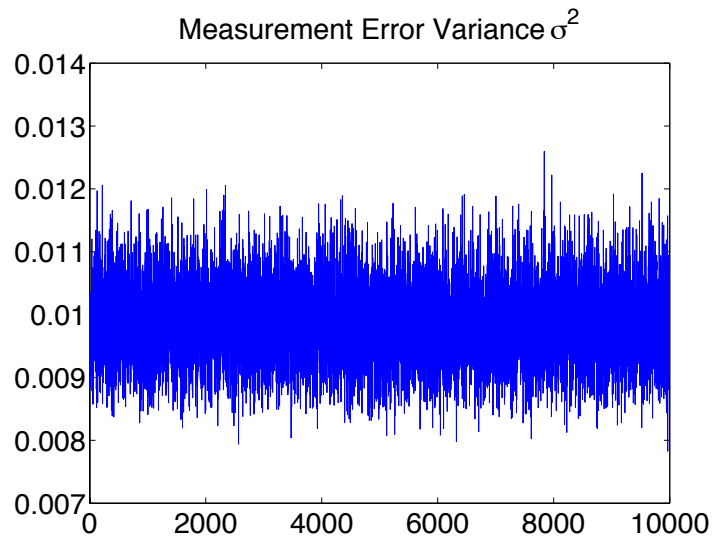
$$2\sigma_C \approx 0.04$$
$$\Rightarrow \sigma_C^2 \approx 0.4 \times 10^{-3}$$



$$2\sigma_K \approx 0.18$$
$$\Rightarrow \sigma_K^2 \approx 0.0081$$

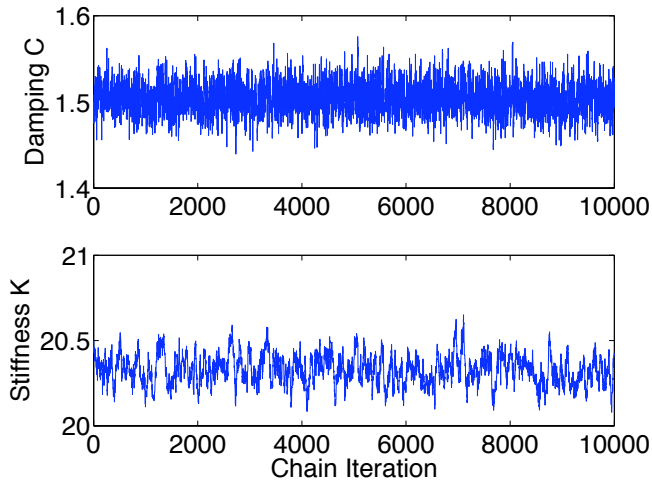
Random Walk Metropolis

Case ii: Measurement error variance and joint samples

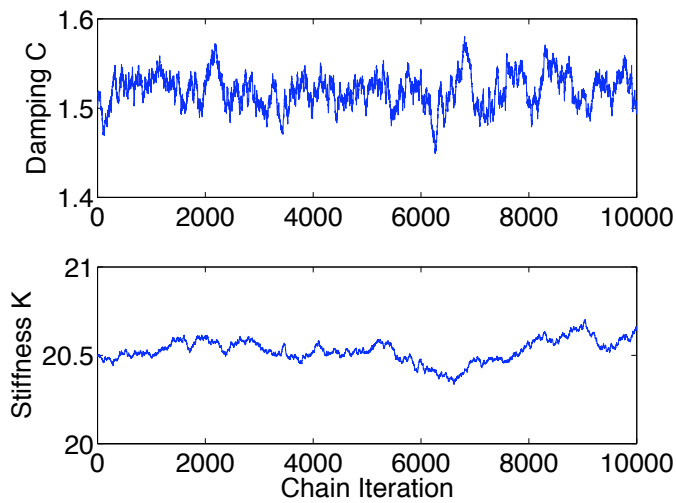


Random Walk Metropolis

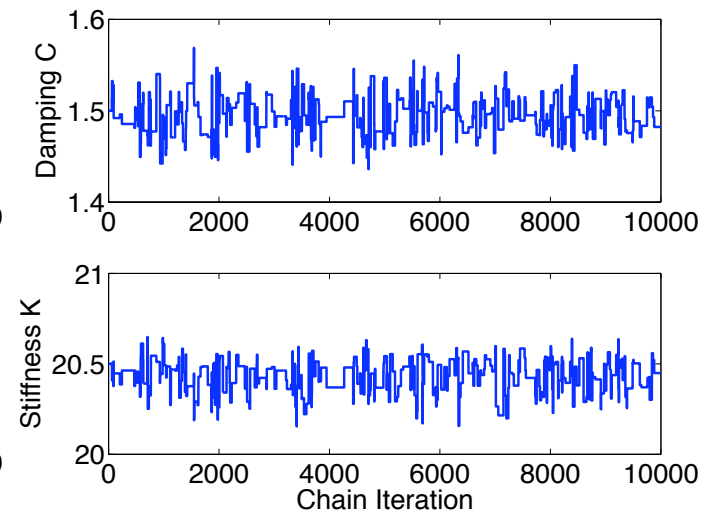
Case iii: Isotropic proposal function $J(\theta^*|\theta^{k-1}) = N(\theta^{k-1}, sI)$



$$s = 9 \times 10^{-4}$$



$$s = 9 \times 10^{-6}$$



$$s = 9 \times 10^{-2}$$

Stationary Distribution and Convergence Criteria

Here

$$\begin{aligned} p_{k-1,k} &= P(X_k = \theta^k | X_{k-1} = \theta^{k-1}) \\ &= P(\text{proposing } \theta^k) P(\text{accepting } \theta^k) \\ &= J(\theta^k | \theta^{k-1}) \alpha(\theta^k | \theta^{k-1}) \\ &= J(\theta^k | \theta^{k-1}) \min \left(1, \frac{\pi(\theta^k | y) J(\theta^{k-1} | \theta^k)}{\pi(\theta^{k-1} | y) J(\theta^k | \theta^{k-1})} \right) \end{aligned}$$

Detailed Balance Condition:

$$\begin{aligned} \pi_{k-1} p_{k-1,k} &= \pi_k p_{k,k-1} \\ \Rightarrow \pi(\theta^{k-1} | y) p_{k-1,k} &= \pi(\theta^k | y) p_{k,k-1} \end{aligned}$$

From relation

$$y \min(1, x/y) = \min(x, y) = x \min(1, y/x)$$

it follows that

$$\begin{aligned} \pi(\theta^{k-1} | y) p_{k-1,k} &= \pi(\theta^{k-1} | y) J(\theta^k | \theta^{k-1}) \min \left(1, \frac{\pi(\theta^k | y) J(\theta^{k-1} | \theta^k)}{\pi(\theta^{k-1} | y) J(\theta^k | \theta^{k-1})} \right) \\ &= \pi(\theta^k | y) J(\theta^{k-1} | \theta^k) \min \left(1, \frac{\pi(\theta^{k-1} | y) J(\theta^k | \theta^{k-1})}{\pi(\theta^k | y) J(\theta^{k-1} | \theta^k)} \right) \\ &= \pi(\theta^k | y) p_{k,k-1} \end{aligned}$$

Delayed Rejection Adaptive Metropolis (DRAM)

Adaptive Metropolis:

- Update chain covariance matrix as chain values are accepted.

$$V_k = s_p \text{cov}(q^0, q^1, \dots, q^{k-1}) + \varepsilon I_p$$

- *Diminishing adaptation and bounded convergence* required since no longer Markov chain.
- Employ recursive relations

$$\begin{aligned}\bar{\theta}^{k+1} &= \frac{1}{k+1} \sum_{i=0}^k \theta^i \\ &= \frac{k}{k+1} \cdot \frac{1}{k} \sum_{i=0}^{k-1} \theta^i + \frac{1}{k+1} \theta^k \\ &= \frac{k}{k+1} \bar{\theta}^k + \frac{1}{k+1} \theta^k\end{aligned}$$

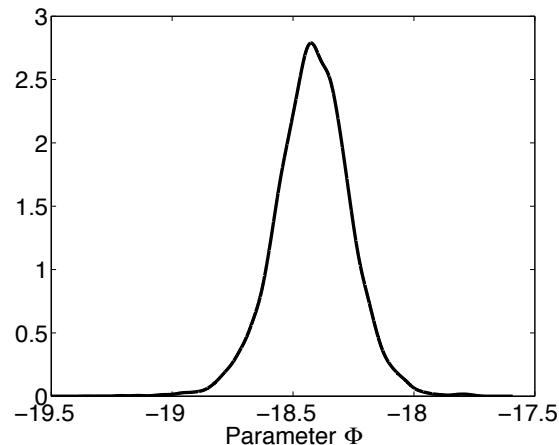
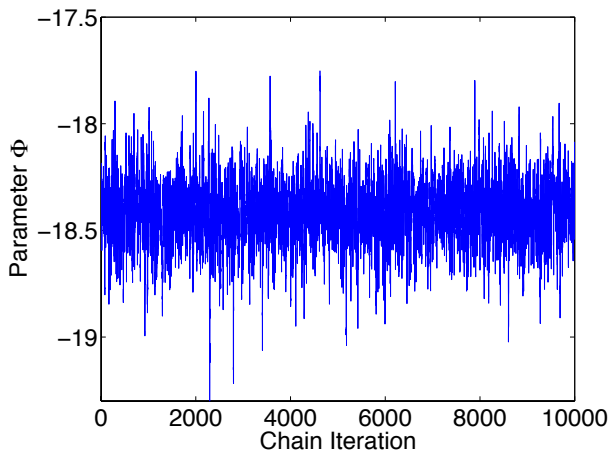
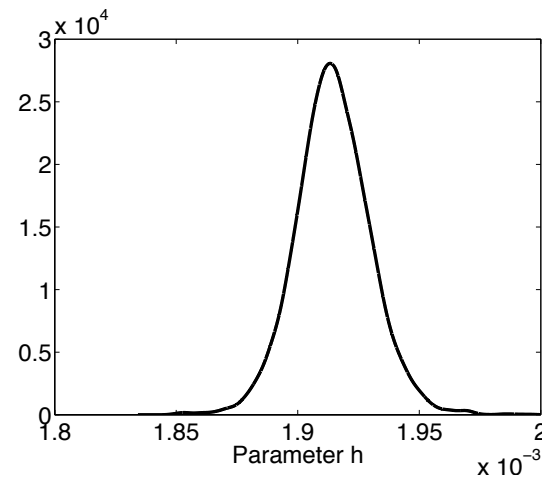
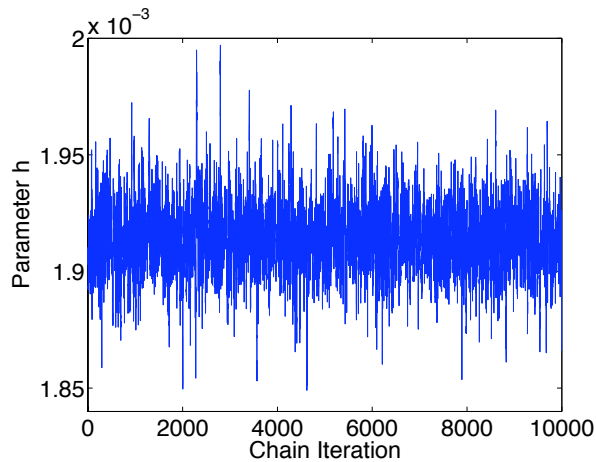
$$V_{k+1} = \frac{k-1}{k} V_k + \frac{s_p}{k} [k \bar{\theta}^{k-1} (\bar{\theta}^{k-1})^T - (k+1) \bar{\theta}^k (\bar{\theta}^k)^T + \theta^k (\theta^k)^T + \varepsilon I_p]$$

Delayed Rejection Adaptive Metropolis (DRAM)

Example: Heat model

$$\frac{d^2 T_s}{dx^2} = \frac{2(a+b)}{ab} \frac{h}{k} [T_s(x) - T_{amb}]$$

$$\frac{dT_s}{dx}(0) = \frac{\Phi}{k} \quad , \quad \frac{dT_s}{dx}(L) = \frac{h}{k} [T_{amb} - T_s(L)]$$



Bayesian Analysis

$$\sigma = 0.2604$$

$$\sigma_{\Phi} = 0.1552$$

$$\sigma_h = 1.5450 \times 10^{-5}$$

Frequentist Analysis

$$\sigma = 0.2504$$

$$\sigma_{\Phi} = 0.1450$$

$$\sigma_h = 1.4482 \times 10^{-5}$$

Delayed Rejection Adaptive Metropolis (DRAM)

Example: HIV model

$$\dot{T}_1 = \lambda_1 - d_1 T_1 - (1 - \varepsilon)k_1 VT_1$$

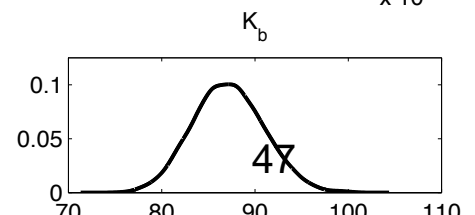
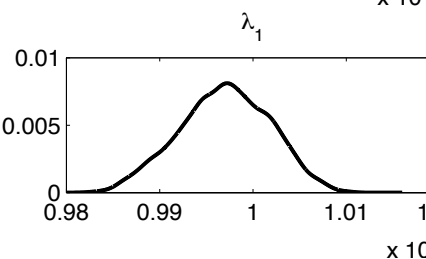
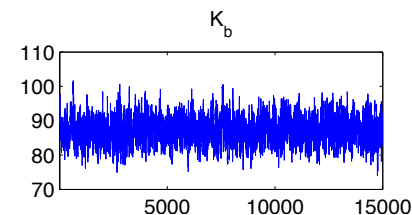
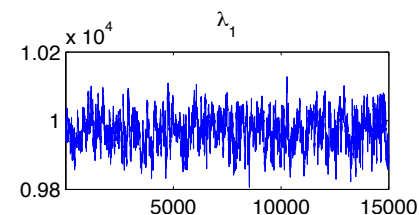
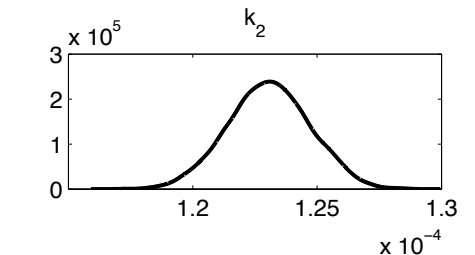
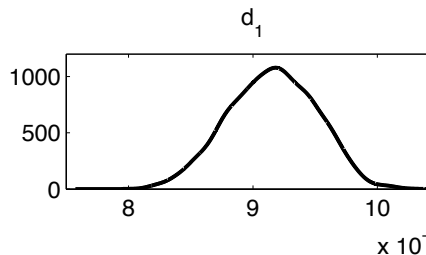
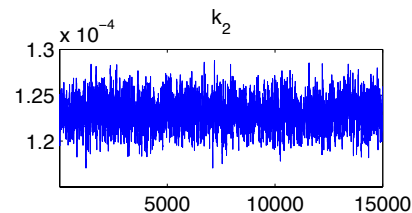
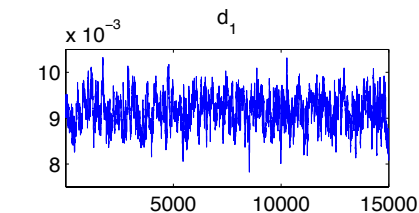
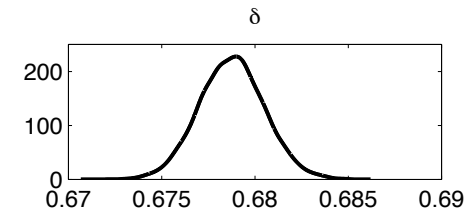
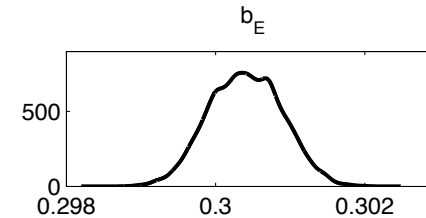
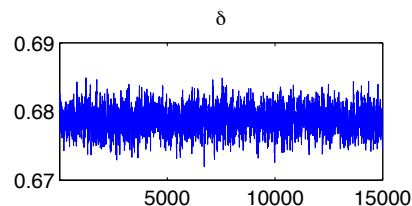
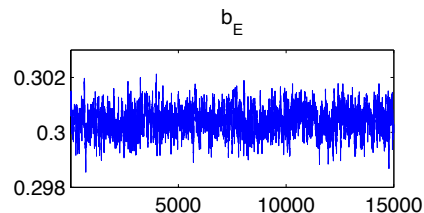
$$\dot{T}_2 = \lambda_2 - d_2 T_2 - (1 - f\varepsilon)k_2 VT_2$$

$$\dot{T}_1^* = (1 - \varepsilon)k_1 VT_1 - \delta T_1^* - m_1 ET_1^*$$

$$\dot{T}_2^* = (1 - f\varepsilon)k_2 VT_2 - \delta T_2^* - m_2 ET_2^*$$

$$\dot{V} = N_T \delta (T_1^* + T_2^*) - cV - [(1 - \varepsilon)\rho_1 k_1 T_1 + (1 - f\varepsilon)\rho_2 k_2 T_2] V$$

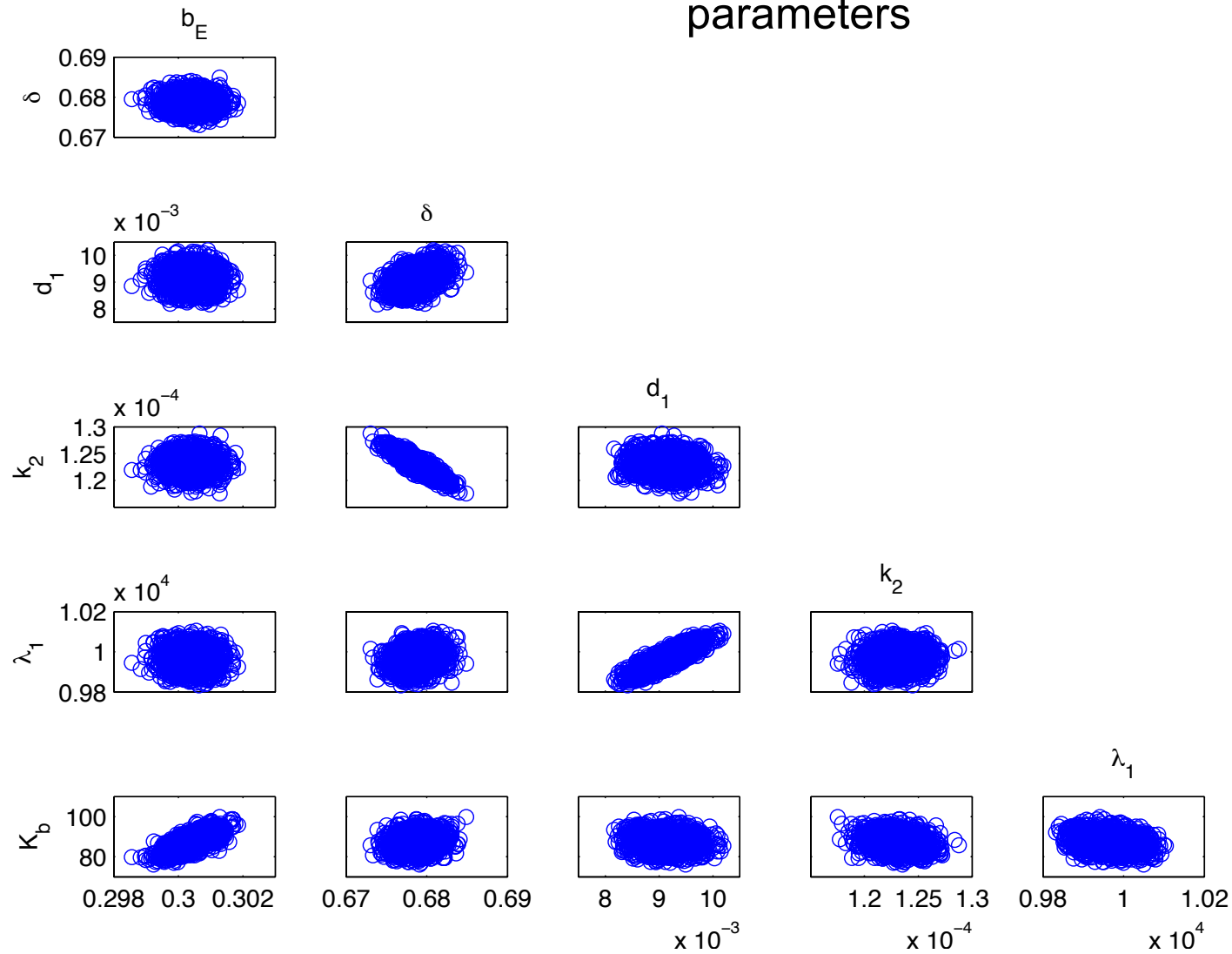
$$\dot{E} = \lambda_E + \frac{b_E (T_1^* + T_2^*)}{T_1^* + T_2^* + K_b} E - \frac{d_E (T_1^* + T_2^*)}{T_1^* + T_2^* + K_d} E - \delta_E E.$$



Delayed Rejection Adaptive Metropolis (DRAM)

Example: HIV model

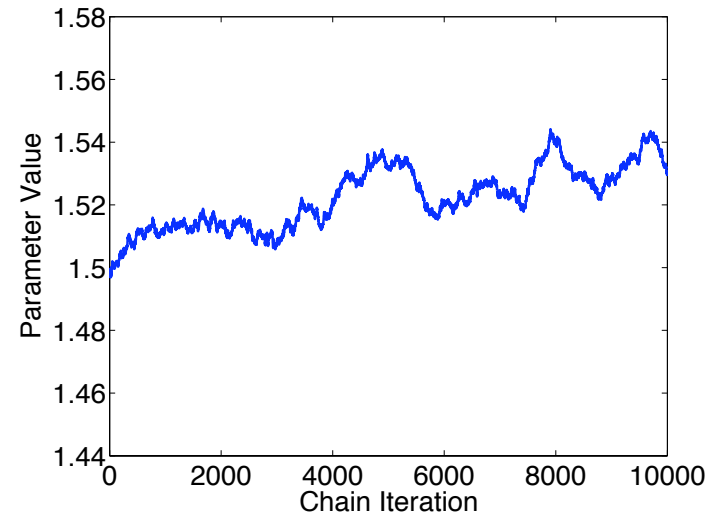
Note: Correlated versus nonidentifiable parameters



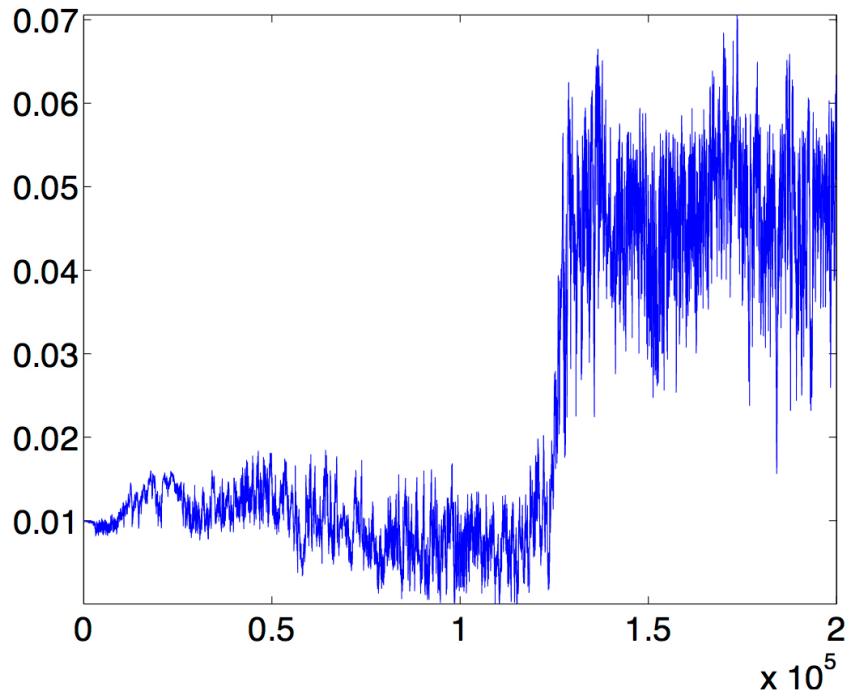
Chain Convergence (Burn-In)

Techniques:

- Visually check chains
- Statistical tests
- Often abused in the literature



Chain not converged



Chain for nonidentifiable parameter

Effects of Parameter Non-identifiability: Section 12.4.2

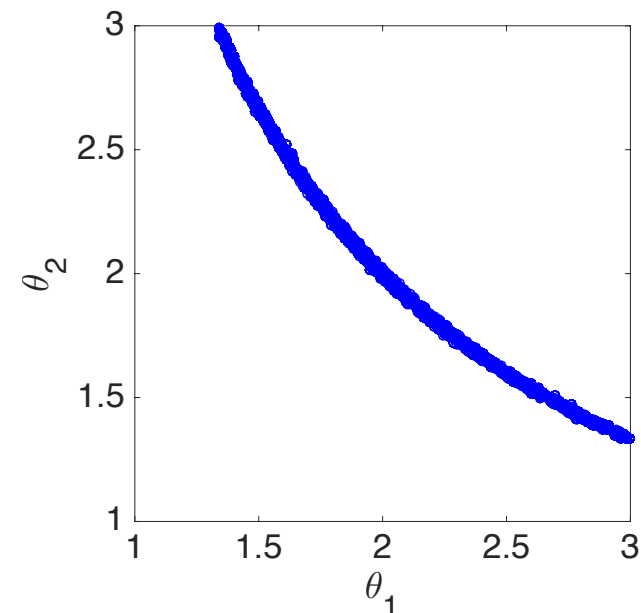
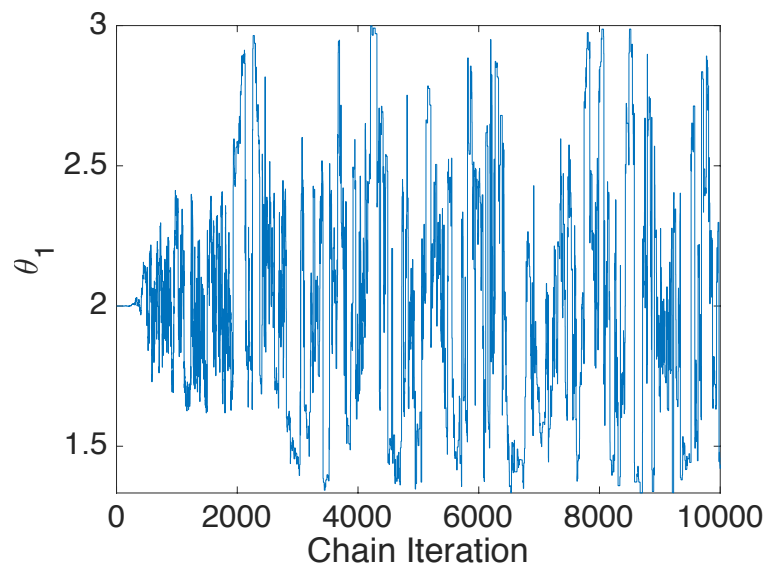
Example 12.13:

$$y_i = \theta_1 \theta_2 t_i + \varepsilon_i, \quad i = 1, \dots, n$$

Parameter values: $\theta_1 = \theta_2 = 2$

Times: $t_i \in [0, 1]$

Prior: $\mathcal{U}^2(4/3, 3)$



Note: Non-identifiable on manifold $h(\theta_{sub}) = 4 - \theta_1 \theta_2$

Effects of Parameter Non-identifiability: Section 12.4.2

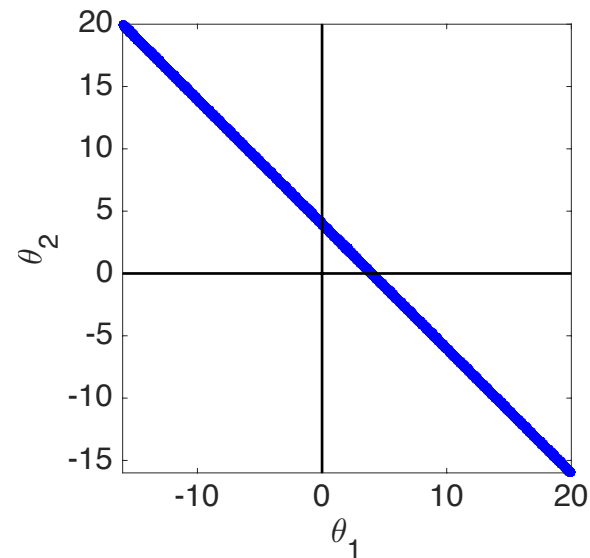
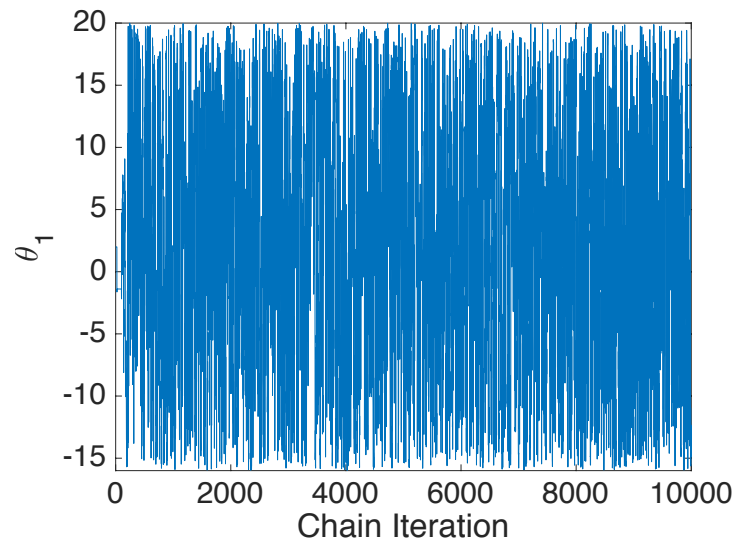
Example 12.13:

$$y_i = (\theta_1 + \theta_2)t_i + \varepsilon_i, \quad i = 1, \dots, n$$

Parameter values: $\theta_1 = \theta_2 = 2$

Times: $t_i \in [0, 1]$

Prior: $\mathcal{U}^2(-17, 20)$ so that $\theta_1 + \theta_2 = 4$ at endpoints.



Note: Non-identifiable on linear manifold $h(\theta_{sub}) = 4 - (\theta_1 + \theta_2)$

Large-Scale Example: Wetland Methane Emission Model

Example 12.22: [Susiluoto et al, "Calibrating the sqHIMMELI v.1.0 wetland methane emission model with hierarchical modeling and adaptive MCMC," Geoscientific Model Development, 11, pp.1199--1228, 2018].

Compartment Model:

$$\frac{\partial [CH_4]}{\partial t}(t, z) = -T_{CH_4} + R_{CH_4}^{exu} + R_{CH_4}^{peat} - R_{CH_4}^{oxid}$$

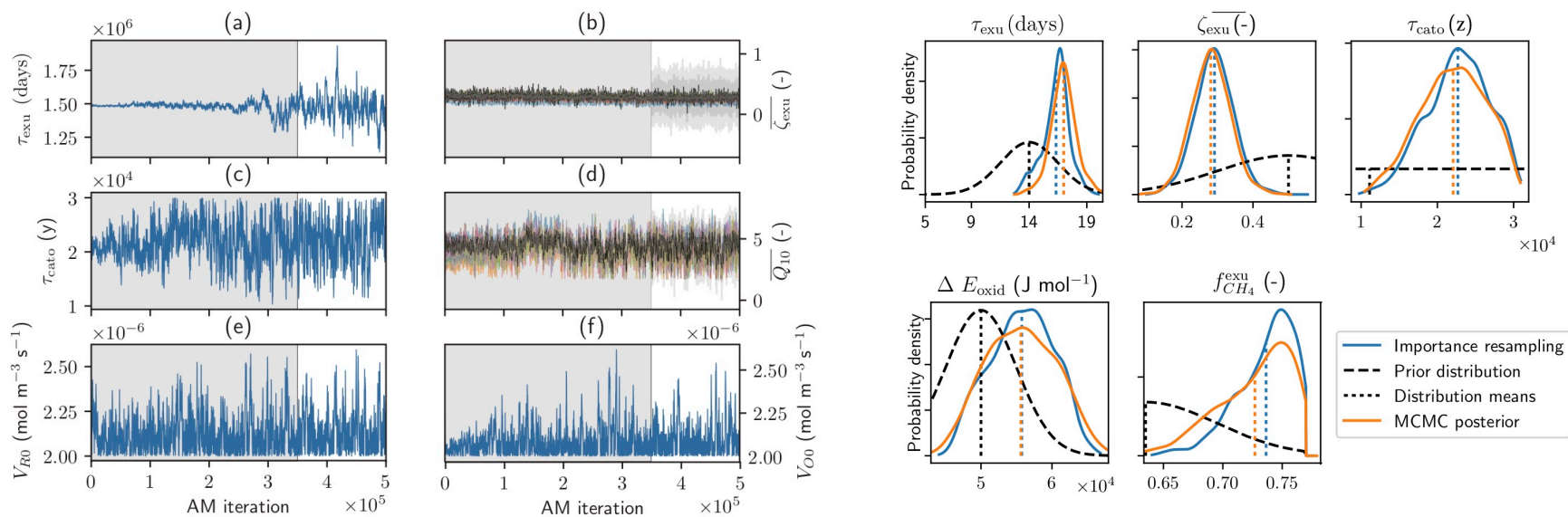
$$\frac{\partial [O_2]}{\partial t}(t, z) = -T_{O_2} - R_{aerob}^{peat} - R_{CO_2}^{exu} - 2R_{CH_4}^{oxid}$$

$$\frac{\partial [CO_2]}{\partial t}(t, z) = -T_{CO_2} + R_{CO_2}^{exu} + R_{CO_2}^{peat} + R_{CH_4}^{oxid} + R_{aerob}^{peat}$$

Representative Constitutive Relation:

$$R_{CH_4}^{peat}(z) = k_{cato}(z) g_{CH_4}^{Q_{10}} \frac{\rho_{cato} f_{C_{cato}}}{M_C}$$

Large-Scale Example: Wetland Methane Emission Model

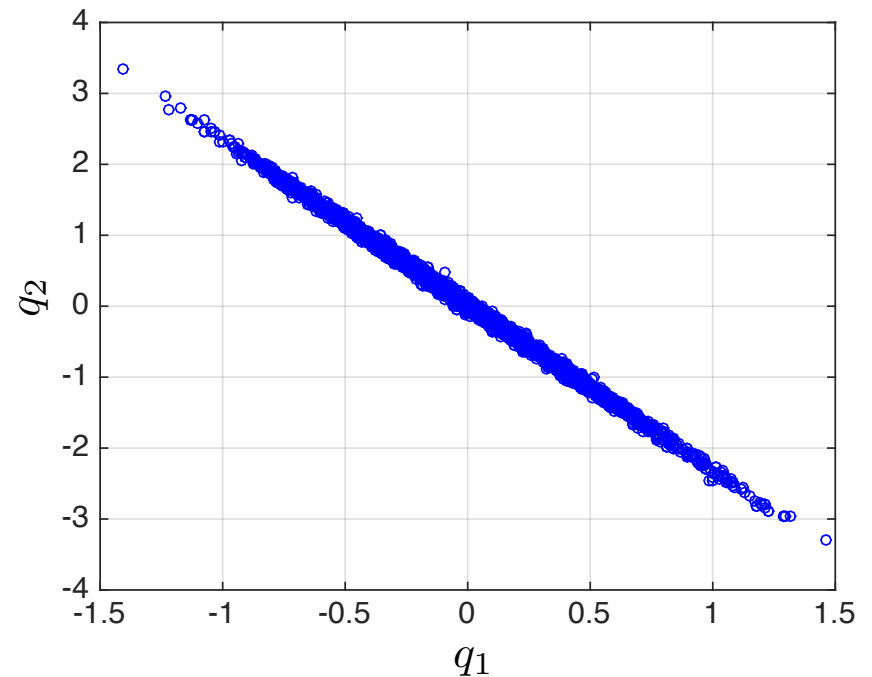
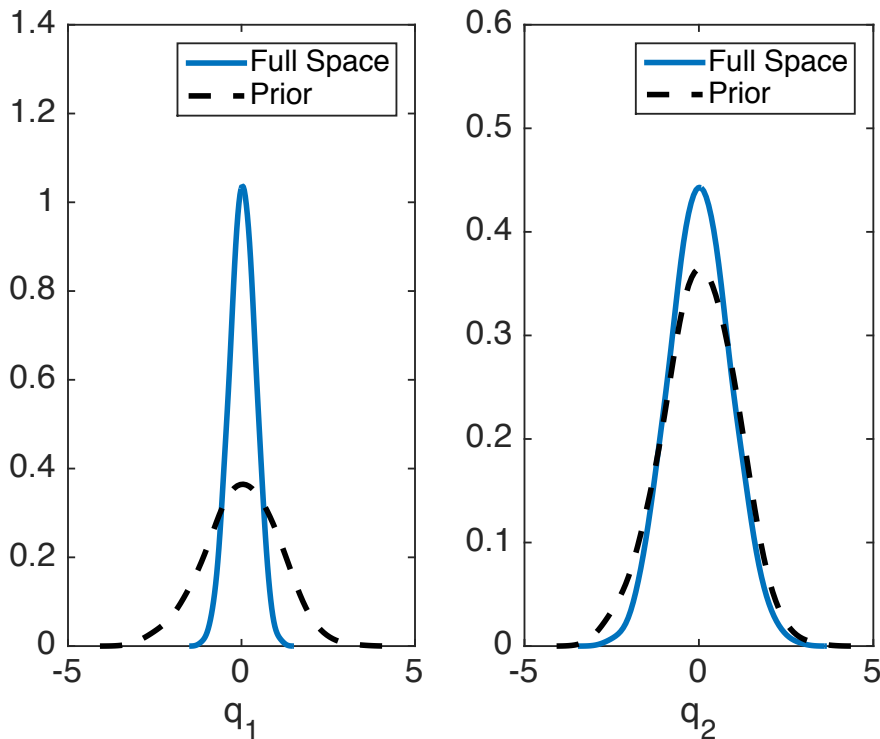
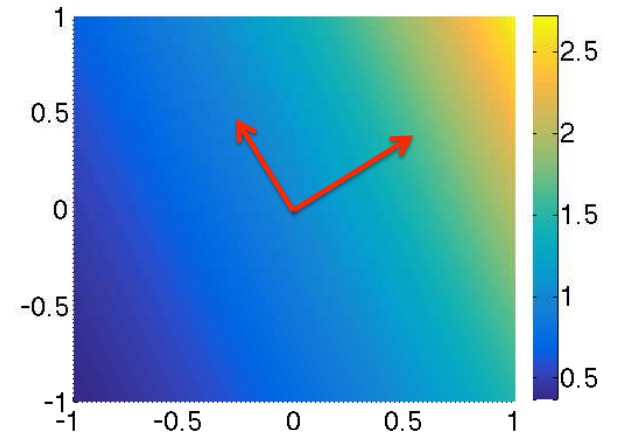


Bayesian Inference on Active Subspace

Example: $y = \exp(0.7\theta_1 + 0.3\theta_2)$

Full Space Inference:

- Parameters not jointly identifiable
- Result: Prior for 2nd parameter is minimally informed.
- Goal: Use active subspace to quantify parameter sensitivity and guide inference.



Bayesian Inference on Active Subspaces

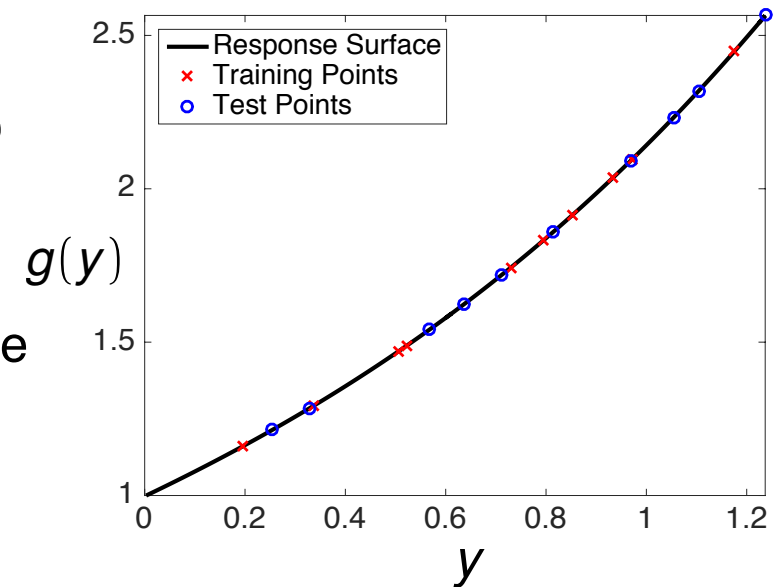
Example: $y = \exp(0.7\theta_1 + 0.3\theta_2)$

Active Subspace: For gradient matrix G , form SVD

$$G = U \Lambda V^T$$

Eigenvalue spectrum indicates 1-D active subspace with basis

$$U(:, 1) = [0.91, 0.39]$$

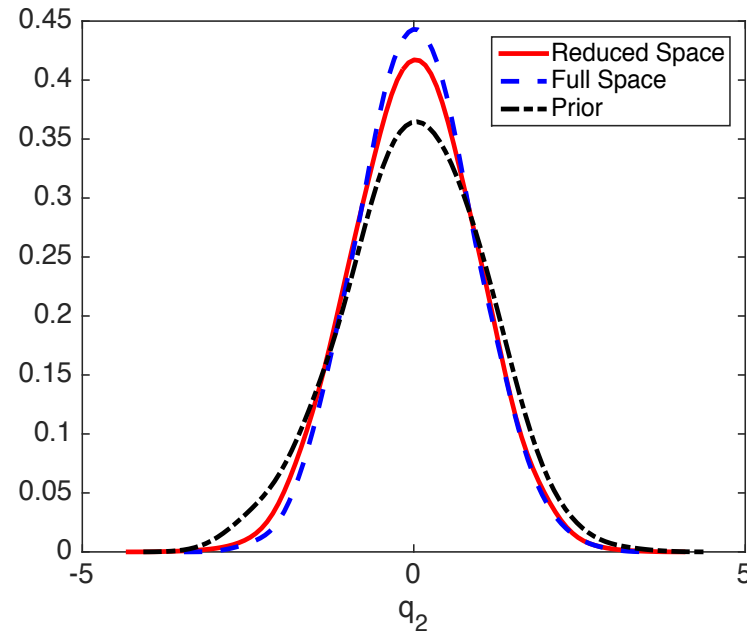
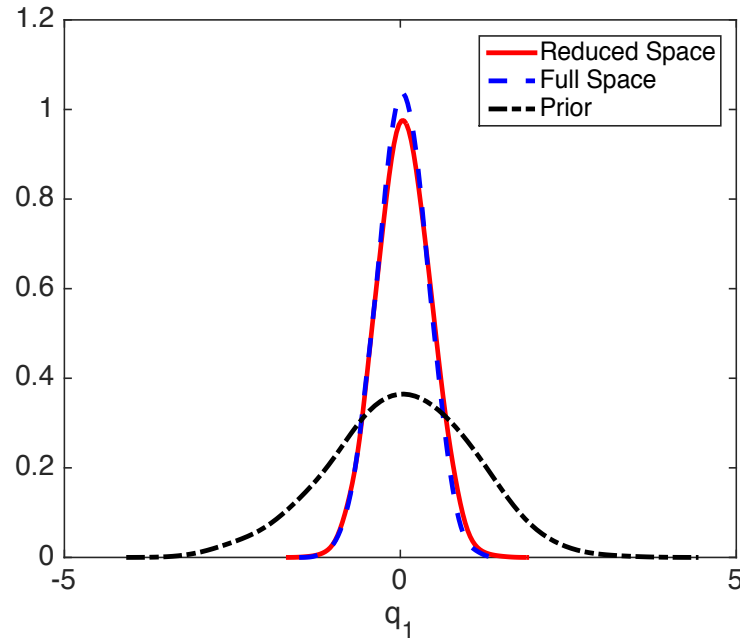


Strategy: Inference based on active subspace

- For values $\{\theta^j\}_{j=1}^N$, compute $y^j = U(:, 1)^T \theta^j$ and fit response surface
- Perform Bayesian inference for y
- Because model is “invariant” to $z = U(:, 2)^T \theta$, draw $\{z^j\} \sim N(0, 1)$
- Transform to $\theta^j = U(:, 1)y^j + U(:, 2)z^j$ to obtain posterior densities for physical parameters

Bayesian Inference on Active Subspaces

Results: Inference based on active subspace



Global Sensitivity: For active subspace of dimension n , consider vector of activity scores

$$\alpha_i(n) = \sum_{j=1}^n \lambda_j w_{i,j}^2, \quad i = 1, \dots, \rho$$

Present Example: Here $n = 1$ and $w_1^2 = U(:, 1) \cdot U(:, 1) = [0.91^2, 0.39^2]$

Conclusion: First parameter is more influential and better informed during Bayesian inference.

Bayesian Inference on Active Subspaces

Example: Family of elliptic PDE's

$$-\nabla_s \cdot (a(q, s, \ell) \nabla_s u(s, a(q, s, \ell))) = 1, \quad s = [0, 1]^2, \quad \ell = 1, \dots, n$$

with the random field representations

$$a(q, s, \ell) = a_{\min} + e^{\bar{a}(s, \ell) + \sum_{i=1}^p q_k^\ell \gamma_i \phi_i(s)}$$

Quantity of interest: e.g., strain along edge at n levels

$$f(\mathbf{q}^1, \dots, \mathbf{q}^n) \approx \sum_{\ell=1}^n \frac{1}{|\Gamma_2|} \int_{\Gamma_2} u(q, s, \ell) ds$$

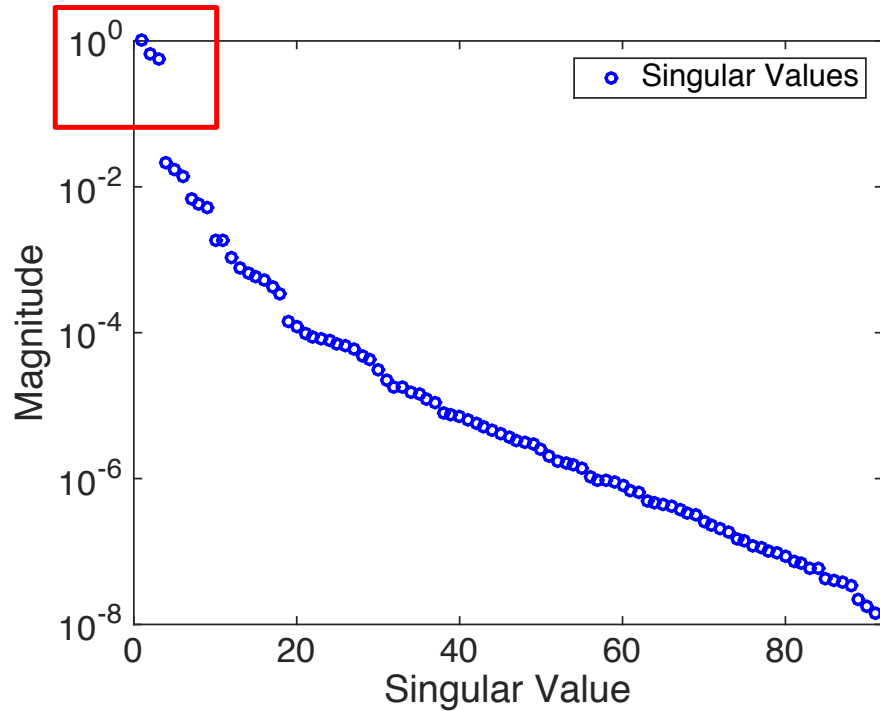


Problem Dimensions:

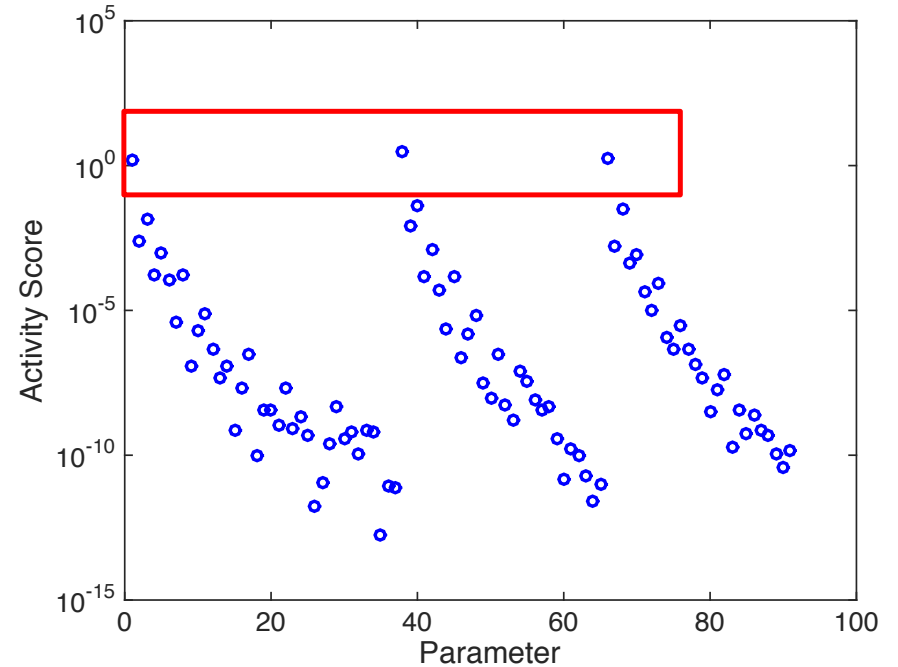
- Parameter dimension: $p = 91$
- Active subspace dimension: $n = 3$
- Finite element approximation

Bayesian Inference on Active Subspaces

Singular Values: Recall $n = 3$



Activity Scores: Quantify global sensitivity



Conclusion: Parameters 1, 38, 66 are most influential and will be primarily informed during Bayesian inference

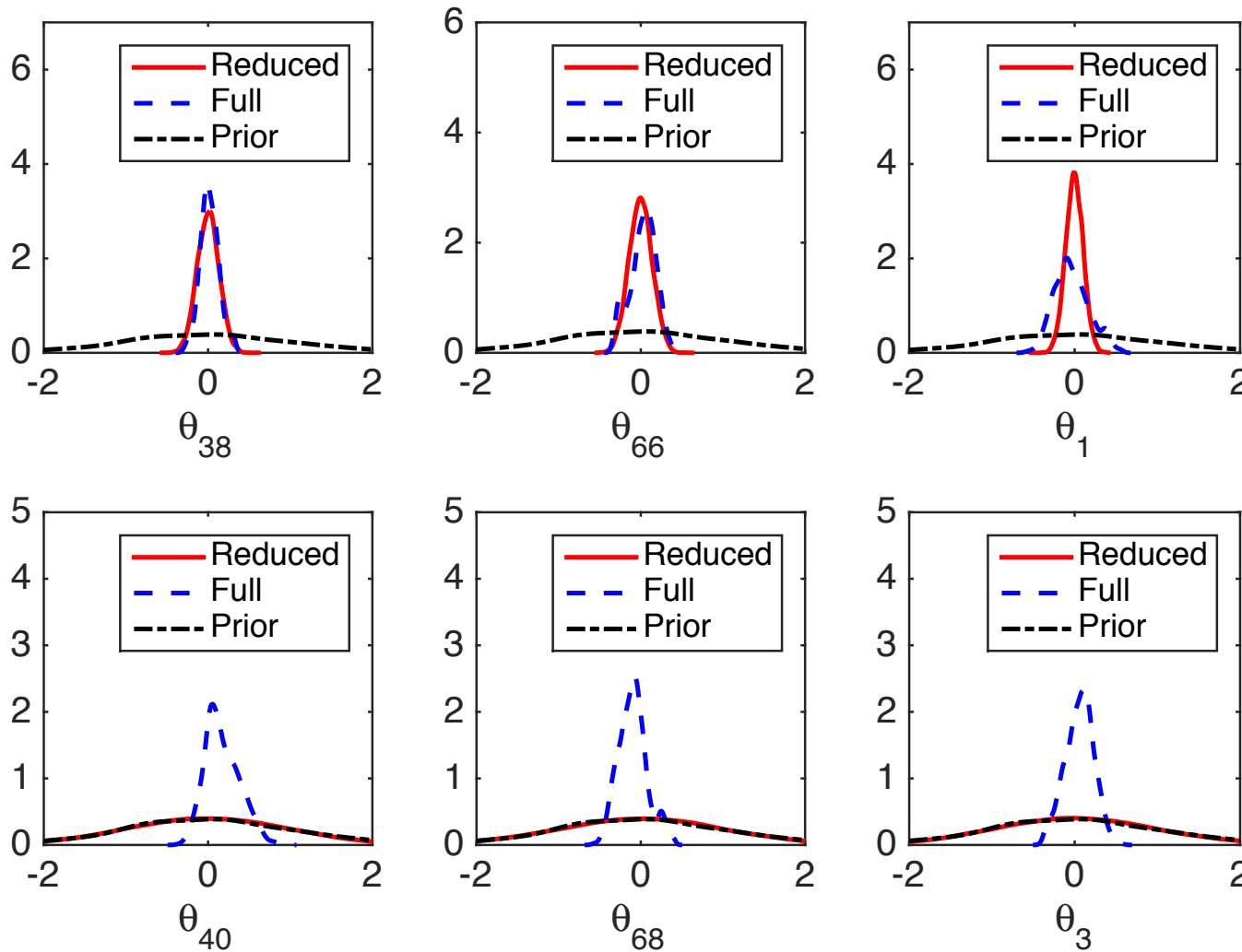
Bayesian Inference on Active Subspaces

Recall: Parameters 1, 38, 66 are most influential and will be primarily informed during Bayesian inference

Note:

Full space: 18 hours

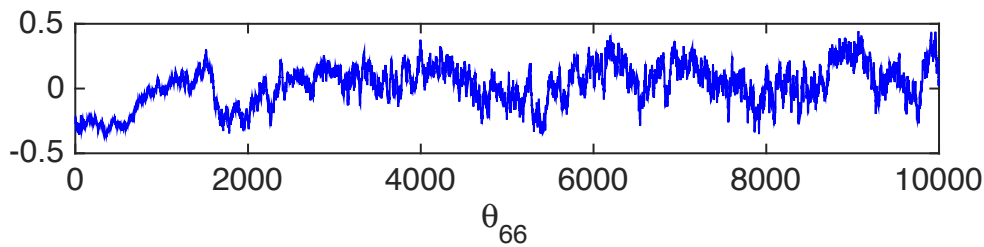
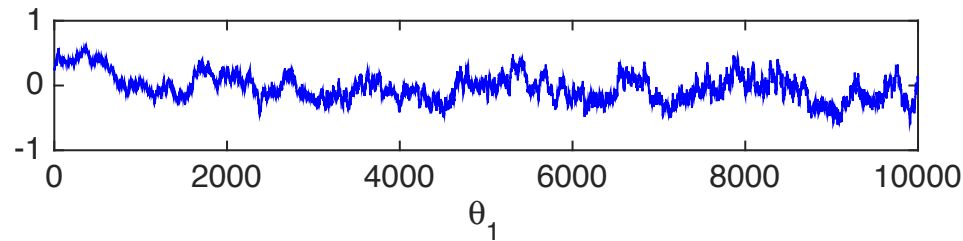
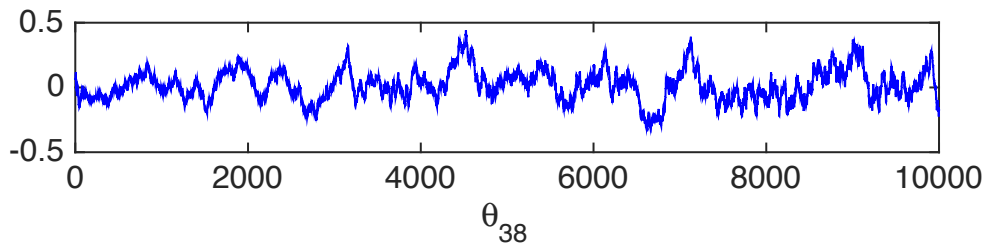
Reduced: 20 seconds



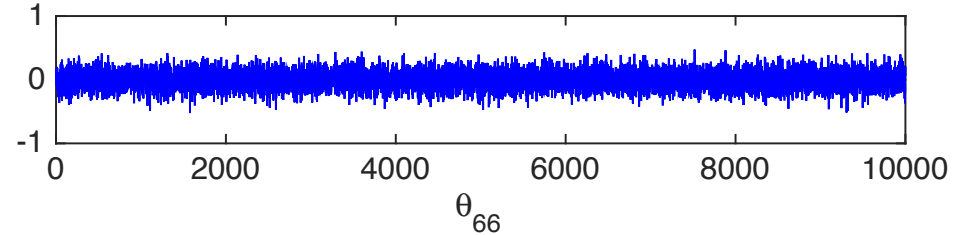
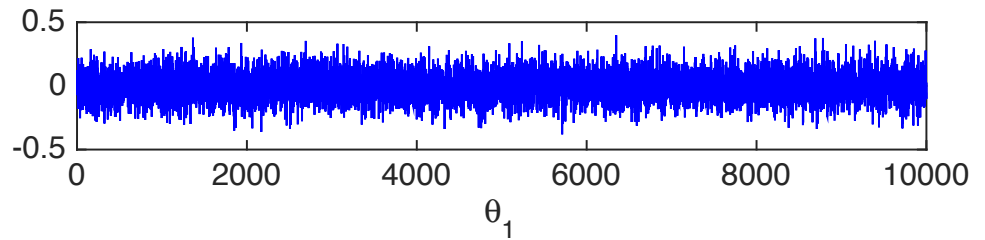
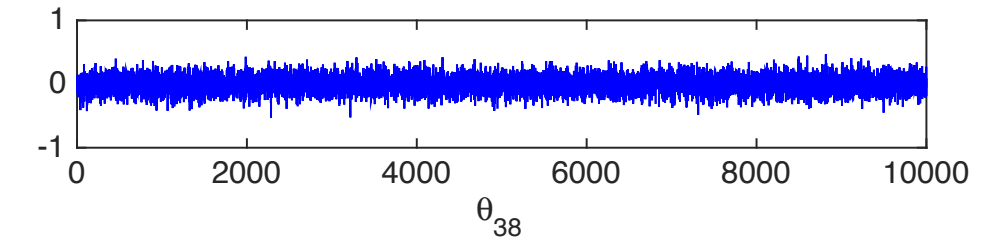
Bayesian Inference on Active Subspaces

Note:

- Chains for full space not converging well due to parameter nonidentifiability
- Hence full space inference is less reliable



Full Space



Active Subspace

Delayed Rejection Adaptive Metropolis (DRAM)

Websites

- http://www4.ncsu.edu/~rsmith/UQ_TIA/CHAPTER8/index_chapter8.html
- <http://helios.fmi.fi/~lainema/mcmc/>

Examples

- [Examples](#) on using the toolbox for some statistical problems.

Delayed Rejection Adaptive Metropolis (DRAM)

We fit the Monod model

$$y = \theta_1 \frac{1}{\theta_2 + 1} + \epsilon, \quad \epsilon \sim N(0, I\sigma^2)$$

to observations

x (mg / L COD): 28 55 83 110 138 225 375

y (1 / h): 0.053 0.060 0.112 0.105 0.099 0.122 0.125

First clear some variables from possible previous runs.

```
clear data model options
```

Next, create a data structure for the observations and control variables. Typically one could make a structure data that contains fields xdata and ydata.

```
data.xdata = [28 55 83 110 138 225 375]'; % x (mg / L COD)
```

```
data.ydata = [0.053 0.060 0.112 0.105 0.099 0.122 0.125]'; % y (1 / h)
```

Construct model

```
modelfun = @(x,theta) theta(1)*x./(theta(2)+x);
```

```
ssfun = @(theta,data) sum((data.ydata-modelfun(data.xdata,theta)).^2);
```

```
model.ssfun = ssfun;
```

```
model.sigma2 = 0.01^2;
```

Delayed Rejection Adaptive Metropolis (DRAM)

Input parameters

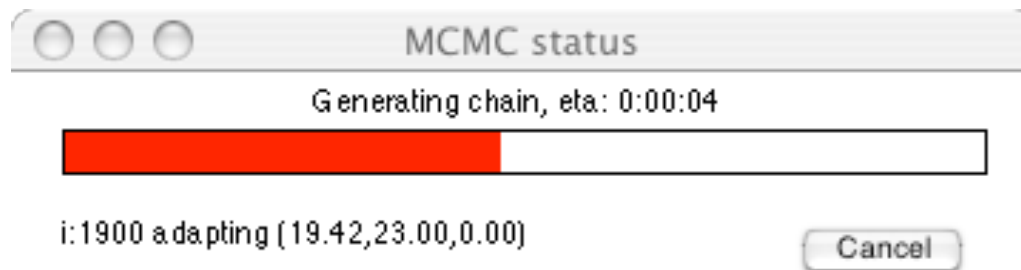
```
params = {  
  {'theta1', tmin(1), 0}  
  {'theta2', tmin(2), 0} };
```

and set options

```
options.nsimu = 4000;  
options.updatesigma = 1;  
options.qcov = tcov;
```

Run code

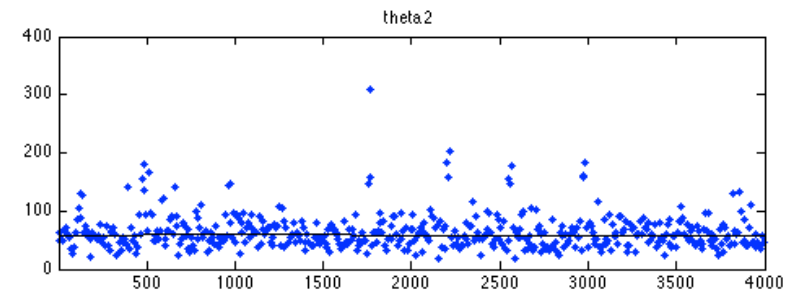
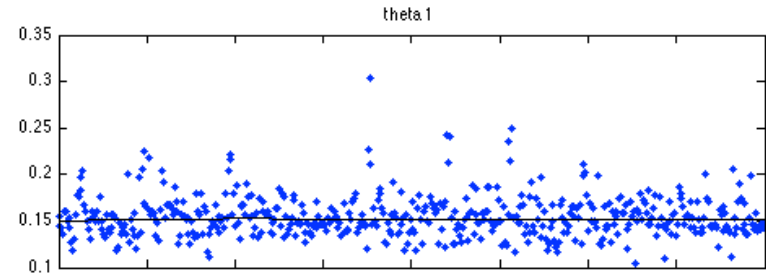
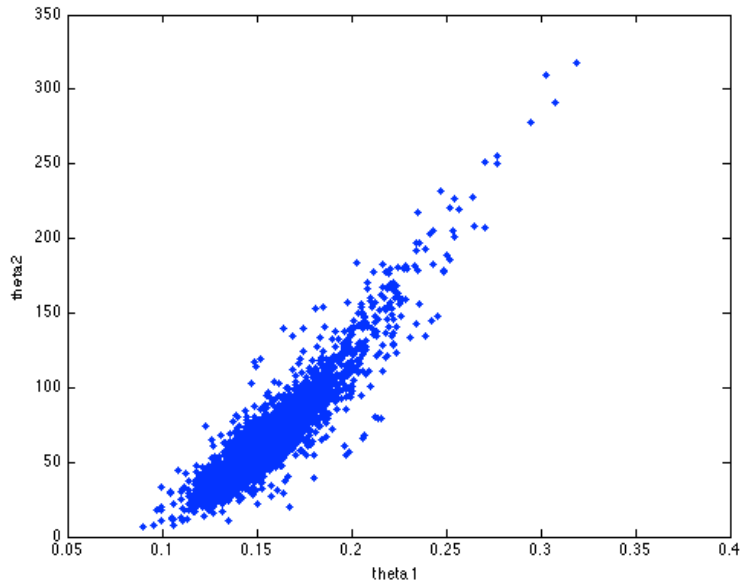
```
[res,chain,s2chain] = mcmcrun(model,data,params,options);
```



Delayed Rejection Adaptive Metropolis (DRAM)

Plot results

```
figure(2); clf  
mcmcplot(chain,[],res,'chainpanel');  
figure(3); clf  
mcmcplot(chain,[],res,'pairs');
```



Examples:

- Several available in MCMC_EXAMPLES
- ODE solver illustrated in algae example

Delayed Rejection Adaptive Metropolis (DRAM)

Construct credible and prediction intervals

```
figure(5); clf
out = mcmcpred(res,chain,[],x,modelfun);
mcmcpredplot(out);
hold on
plot(data.xdata,data.ydata,'s'); % add data points to the plot
xlabel('x [mg/L COD]');
ylabel('y [1/h]');
hold off
title('Predictive envelopes of the model')
```

