

Chapter 9 - Uncertainty Propagation

1. Linear Models

$$\eta_i = XQ + \varepsilon$$

Example 1: Stress-strain model

$$\begin{aligned}\eta_i &= Ee_i + E_2 e_i^3, \quad i=1, \dots, n \\ &= f_i(Q) + \varepsilon_i\end{aligned}$$

Here

$$Q_1 = E, \quad Q_2 = E_2$$

and

$$\begin{bmatrix} \eta_1 \\ \vdots \\ \eta_n \end{bmatrix} = \begin{bmatrix} e_1 & e_1^3 \\ \vdots & \vdots \\ e_n & e_n^3 \end{bmatrix} \begin{bmatrix} E \\ E_2 \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$

Statistics: Take $\bar{f} = [\bar{f}_1, \bar{f}_2] = [\bar{E}, \bar{E}_2]$. Then

$$\mathbb{E}[f_i(Q)] = \bar{E}e_i + \bar{E}_2 e_i^3$$

$$\begin{aligned}\text{var}[f_i(Q)] &= \mathbb{E}[f_i^2(Q)] - \mathbb{E}^2[f_i(Q)] \\ &= \mathbb{E}[(Ee_i + E_2 e_i^3)^2] - (\bar{E}e_i + \bar{E}_2 e_i^3)^2 \\ &= \mathbb{E}[E^2 e_i^2 + 2E E_2 e_i^4 + E_2^2 e_i^6] \\ &\quad - \bar{E}^2 e_i^2 - 2\bar{E} \bar{E}_2 e_i^4 - \bar{E}_2^2 e_i^6 \\ &= e_i^2 \text{var}(E) + e_i^6 \text{var}(E_2) + 2e_i^4 \text{cov}(E, E_2)\end{aligned}$$



Note: Stress η_i (F/A)

$$\text{Strain } e_i = \lim_{\Delta x \rightarrow 0} \frac{\Delta u}{\Delta x}$$

$$= \frac{\partial u}{\partial x}$$

Note: $\mathbb{E}\left(\sum_{i=1}^n a_i X_i\right) = \sum_{i=1}^n a_i \mathbb{E}(X_i)$ (i)

$$\text{var}\left(\sum_{i=1}^n a_i X_i\right) = \sum_{i=1}^n a_i^2 \text{var}(X_i) + 2 \sum_{i < j} a_i a_j \text{cov}(X_i, X_j)$$

- See Chapter 4

Example 2: Linear Multiple Regression

$$\eta_i = Q_1 + \sum_{j=2}^p X_{ij} Q_j + \varepsilon_i$$

$$\Rightarrow \begin{bmatrix} \eta_1 \\ \vdots \\ \eta_n \end{bmatrix} = \begin{bmatrix} 1 & X_{12} & \dots & X_{1p} \\ \vdots & \vdots & & \vdots \\ 1 & X_{n2} & \dots & X_{np} \end{bmatrix} \begin{bmatrix} Q_1 \\ \vdots \\ Q_p \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$

Then

$$\mathbb{E}[f_i(Q)] = \bar{f}_i + \sum_{j=2}^p X_{ij} \bar{f}_j$$

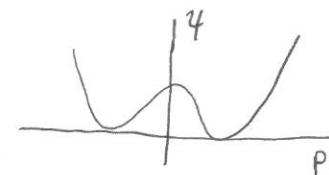
$$\begin{aligned}\text{var}[f_i(Q)] &= \text{var}(Q_1) + \sum_{j=2}^p [X_{ij}^2] \text{var}(Q_j) + 2X_{ij} \text{cov}(Q_1, Q_j) \\ &\quad + \sum_{1 < j < k} X_{ij} X_{ik} \text{cov}(Q_j, Q_k)\end{aligned}$$

for $i = 1, \dots, n$,

e.g. Height-weight data

$$f(Q) = Q_1 + Q_2 \left(\frac{x}{12}\right) + Q_3 \left(\frac{x}{12}\right)^2$$

e.g. $y = \alpha_1 P^2 + \alpha_2 P^4 + \alpha_3 P^6$



(ii)

Bayesian Analysis: Data of Table 7.1

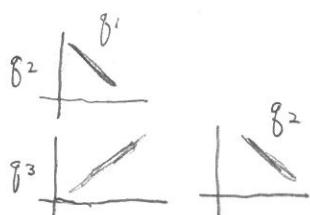
$$\bar{g} = [260.65, -87.74, 11.92]^T$$

$$V = \begin{bmatrix} \text{var}(Q_1) & \text{cov}(Q_1, Q_2) & \text{cov}(Q_1, Q_3) \\ \text{cov}(Q_2, Q_1) & \text{var}(Q_2) & \text{cov}(Q_2, Q_3) \\ \text{cov}(Q_3, Q_1) & \text{cov}(Q_3, Q_2) & \text{var}(Q_3) \end{bmatrix}$$

$$= \begin{bmatrix} 778.35 & -287.93 & 26.51 \\ -287.93 & 106.61 & -9.82 \\ 26.51 & -9.82 & 0.91 \end{bmatrix}$$

Note: Results from Bayesian inference differ somewhat from OLS results on page 138.
Sensitive to MCMC!

Note: Very correlated and V has small eigenvalues.



Now,

$$\text{IE}[f(Q)] = \bar{g}_1 + \left(\frac{x}{12}\right)\bar{g}_2 + \left(\frac{x}{12}\right)^2\bar{g}_3$$

$$\begin{aligned} \text{var}[f(Q)] &= \text{var}(Q_1) + \left(\frac{x}{12}\right)^2 \text{var}(Q_2) + \left(\frac{x}{12}\right)^4 \text{var}(Q_3) \\ &\quad + 2\left(\frac{x}{12}\right) \text{cov}(Q_1, Q_2) + 2\left(\frac{x}{12}\right)^2 \text{cov}(Q_1, Q_3) \\ &\quad + 2\left(\frac{x}{12}\right)^3 \text{cov}(Q_2, Q_3) \end{aligned}$$



Sampling-Based: Sample out of $p_Q(g)$ and $p_\varepsilon(\varepsilon)$.

Perturbation Methods: Take

$$\begin{aligned} Q &= \bar{g} + SQ \sim \text{Realization after 10^5} \\ &= [\bar{g}_1 + SQ_1, \dots, \bar{g}_P + SQ_P] \end{aligned}$$

Then

$$\begin{aligned} f(Q) &= f(\bar{g}) + \sum_{i=1}^P \frac{\partial f}{\partial Q_i} \Big|_{\bar{g}} \delta Q_i + N(0, 1) \\ &= \bar{y} + \sum_{i=1}^P S_i \delta Q_i. \end{aligned}$$

Consider $Q = [Q_1, \dots, Q_P]$ with joint pdf $p_Q(g)$. Then

$$E(Q_i) = \bar{g}_i$$

$$\begin{aligned} \text{var}(Q_i) &= \int_{\mathbb{R}^P} (g_i - \bar{g}_i)^2 p_Q(g) dg \\ &= \int_{\mathbb{R}^P} (\delta g_i)^2 p_Q(g) dg \end{aligned}$$

$$\begin{aligned} \text{cov}(Q_i, Q_j) &= \int_{\mathbb{R}^P} (g_i - \bar{g}_i)(g_j - \bar{g}_j) p_Q(g) dg \\ &= \int_{\mathbb{R}^P} \delta g_i \delta g_j dg \end{aligned}$$

$$\begin{aligned} \text{Note: } \text{IE}[f(Q)] &= \bar{y} \int_{\mathbb{R}^P} p_Q(g) dg + \sum_{i=1}^P S_i \int_{\mathbb{R}^P} (g_i - \bar{g}_i) p_Q(g) dg \\ &= \bar{y} \end{aligned}$$

$$\text{since } \int_{\mathbb{R}^P} (g_i - \bar{g}_i) p_Q(g) dg = \bar{g}_i - \bar{g}_i = 0$$