

Bayesian Techniques for Parameter Estimation

“He has Van Gogh’s ear for music,” *Billy Wilder*

Reading: Sections 4.6 and 4.8, Chapter 8

Statistical Inference

Goal: The goal in statistical inference is to make conclusions about a phenomenon based on observed data.

Frequentist: Observations made in the past are analyzed with a specified model. Result is regarded as confidence about state of real world.

- Probabilities defined as frequencies with which an event occurs if experiment is repeated several times.
- Parameter Estimation:
 - Relies on estimators derived from different data sets and a specific sampling distribution.
 - Parameters may be unknown but are fixed and deterministic.

Bayesian: Interpretation of probability is subjective and can be updated with new data.

- Parameter Estimation: Parameters are considered to be random variables having associated densities.

Bayesian Inference

Framework:

- Prior Distribution: Quantifies prior knowledge of parameter values.
- Likelihood: Probability of observing a data if we have a certain set of parameter values.
- Posterior Distribution: Conditional probability distribution of unknown parameters given observed data.

Joint PDF: Quantifies all combination of data and observations

$$\pi(q, v) = \pi(v|q)\pi_0(q)$$

Bayes' Relation: Specifies posterior in terms of likelihood, prior, and normalization constant

$$\pi(q|v_{obs}) = \frac{\pi(v_{obs}|q)\pi_0(q)}{\pi(v_{obs})} = \frac{\pi(v_{obs}|q)\pi_0(q)}{\int_{\mathbb{R}^p} \pi(v_{obs}|q)\pi_0(q)dq}$$

Problem: Evaluation of normalization constant typically requires high dimensional integration.

Bayesian Inference

Uninformative Prior: No *a priori* information parameters

e.g., $\pi_0(q) = 1$ with limits

Informative Prior: Use conjugate priors; prior and posterior from same distribution

$$\pi(q|v_{obs}) = \frac{\pi(v_{obs}|q)\pi_0(q)}{\pi(v_{obs})} = \frac{\pi(v_{obs}|q)\pi_0(q)}{\int_{\mathbb{R}^p} \pi(v_{obs}|q)\pi_0(q)dq}$$

Evaluation Strategies:

- Analytic integration --- Rare
- Classical Gaussian quadrature; e.g., p = 1 - 4
- Sparse grid quadrature techniques; e.g., p = 5 - 40
- Monte Carlo quadrature Techniques
- Markov chain methods

Bayesian Inference

Example: Υ_i : Result from i^{th} coin toss

$$\Upsilon_i(\omega) = \begin{cases} 0 & , \quad \omega = T \\ 1 & , \quad \omega = H \end{cases}$$

q : Probability of getting heads

Consider probability of observing series of tosses $v = [v_1, \dots, v_N]$ given the probability q

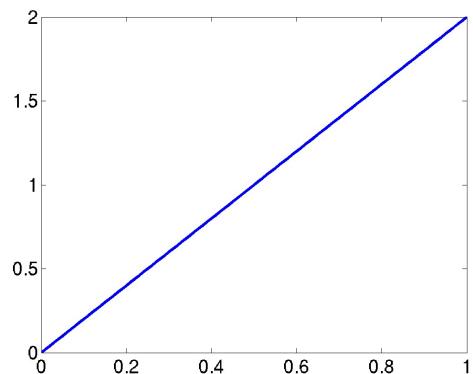
$$\begin{aligned}\pi(v|q) &= \prod_{i=1}^N q^{v_i} (1-q)^{1-v_i} \\ &= q^{\sum v_i} (1-q)^{N-\sum v_i} \\ &= q^{N_1} (1-q)^{N_0}\end{aligned}\quad \begin{array}{l} N_1: \text{Number of heads} \\ N_0: \text{Number of tails} \end{array}$$

Uninformative prior yields

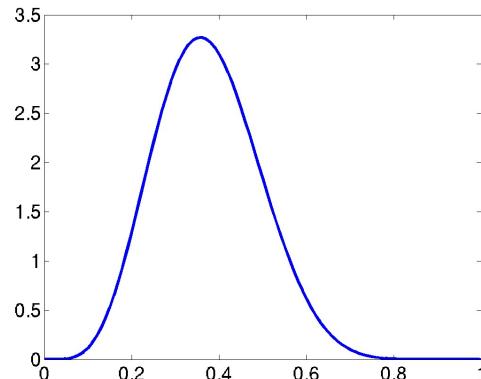
$$\pi(q|v) = \frac{q^{N_1} (1-q)^{N_0}}{\int_0^1 q^{N_1} (1-q)^{N_0} dq} = \frac{(N+1)!}{N_0! N_1!} q^{N_1} (1-q)^{N_0}.$$

Bayesian Inference

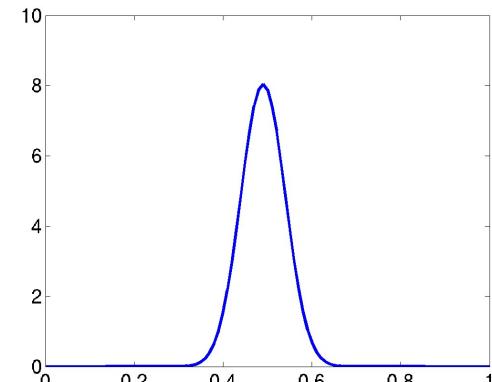
Example:



1 Head, 0 Tails



5 Heads, 9 Tails



49 Heads, 51 Tails

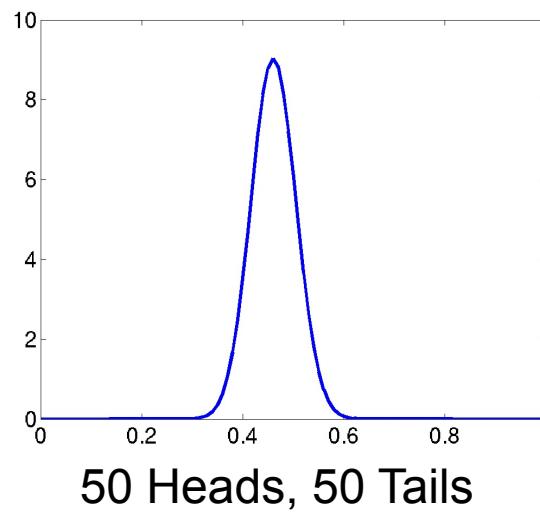
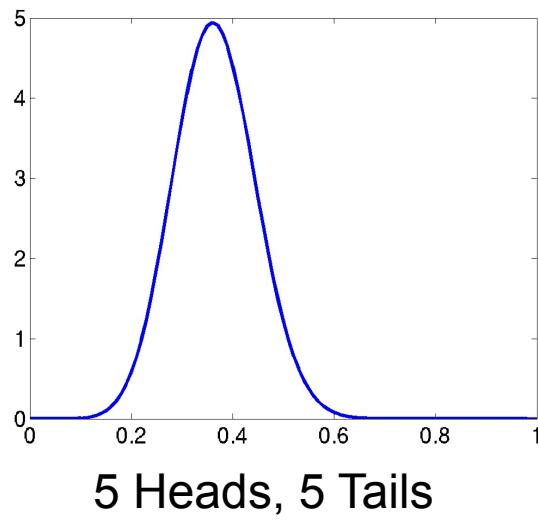
Note: For $N = 1$, frequentist theory would give probability 1 or 0

Bayesian Inference

Example: Now consider

$$\pi_0(q) = \frac{1}{\sigma\sqrt{2\pi}} e^{-(q-\mu)^2/2\sigma^2}$$

with $\mu = .3$ and $\sigma = .1$.



Note: Poor informative prior incorrectly influences results for a long time.

Parameter Estimation Problem

Assumption: Assume that measurement errors are iid and $\varepsilon_i \sim N(0, \sigma^2)$

Likelihood:

$$\pi(v|q) = L(q, \sigma|v) = \frac{1}{(2\pi\sigma^2)^{n/2}} e^{-SS_q/2\sigma^2}$$

where

$$SS_q = \sum_{i=1}^n [v_i - f_i(q)]^2$$

is the sum of squares error.

Parameter Estimation: Example

Example: Consider the spring model

$$\ddot{z} + C\dot{z} + Kz = 0$$

$$z(0) = 2, \dot{z}(0) = -C$$

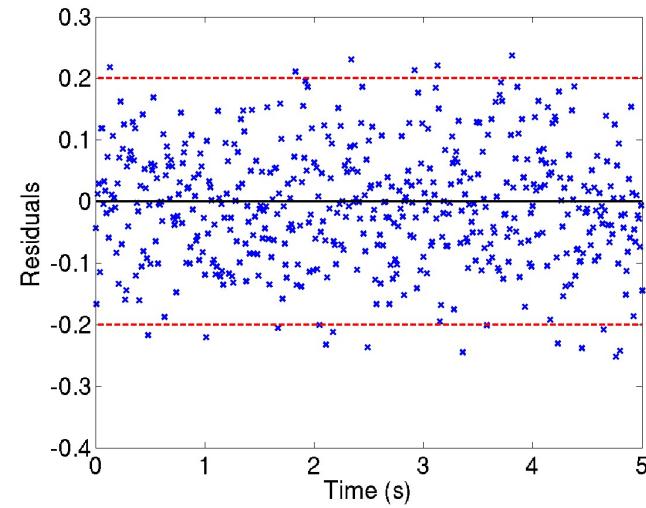
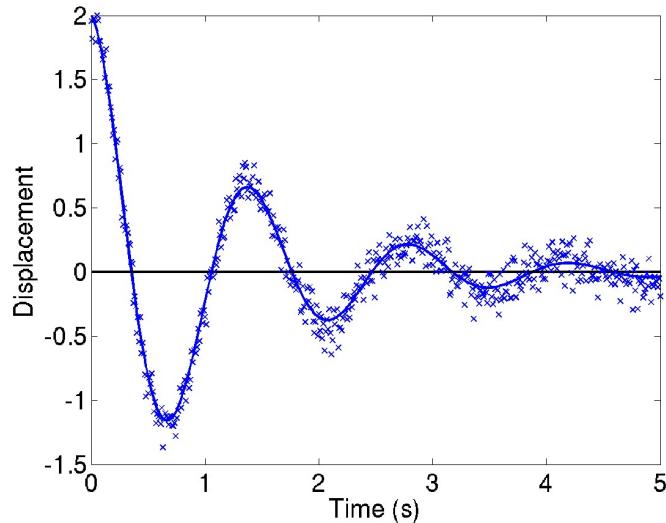
Note: Take $K = 20.5, C_0 = 1.5$

which has the solution

$$z(t) = 2e^{-Ct/2} \cos(\sqrt{K - C^2/4} \cdot t)$$

Take K to be known and $Q = C$. We also assume that $\varepsilon_i \sim N(0, \sigma_0^2)$

where $\sigma_0 = 0.1$.



Parameter Estimation: Example

Ordinary Least Squares: Here

$$\mathcal{X}(q) = \left[\frac{\partial y}{\partial C}(t_1, q), \dots, \frac{\partial y}{\partial C}(t_n, q) \right]^T$$

where

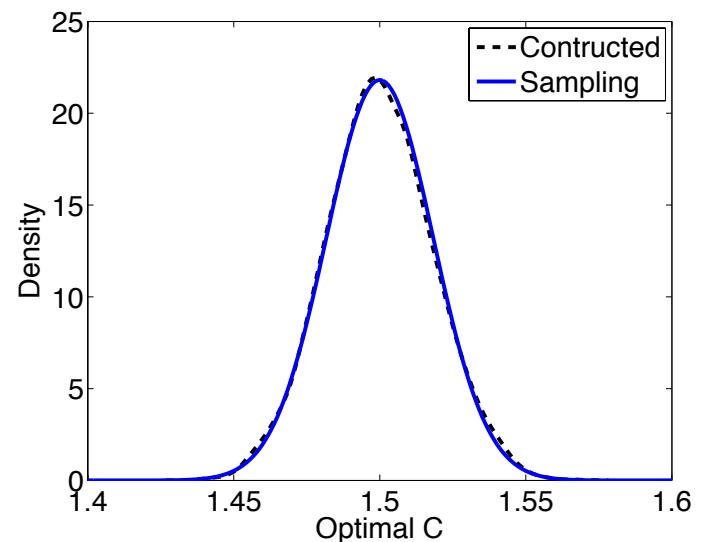
$$\frac{\partial y}{\partial C} = e^{-Ct/2} \left[\frac{Ct}{\sqrt{4K - C^2}} \sin \left(\sqrt{K - C^2/4} \cdot t \right) - t \cos \left(\sqrt{K - C^2/4} \cdot t \right) \right]$$

Then

$$V = \sigma_c^2 = \sigma_0^2 [\mathcal{X}^T(q) \mathcal{X}(q)]^{-1} = 3.35 \times 10^{-4}$$

so that

$$\hat{C} \sim N(C_0, \sigma_c^2), \sigma_c = 0.0183$$



Parameter Estimation: Example

Bayesian Inference: Employ the uniformed prior

$$\pi_0(q) = \chi_{[0,\infty)}(q)$$

Posterior Distribution:

$$\pi(q|v) = \frac{e^{-SS_q/2\sigma_0^2}}{\int_0^\infty e^{-SS_\zeta/2\sigma_0^2} d\zeta} = \frac{1}{\int_0^\infty e^{-(SS_\zeta - SS_q)/2\sigma_0^2} d\zeta}$$

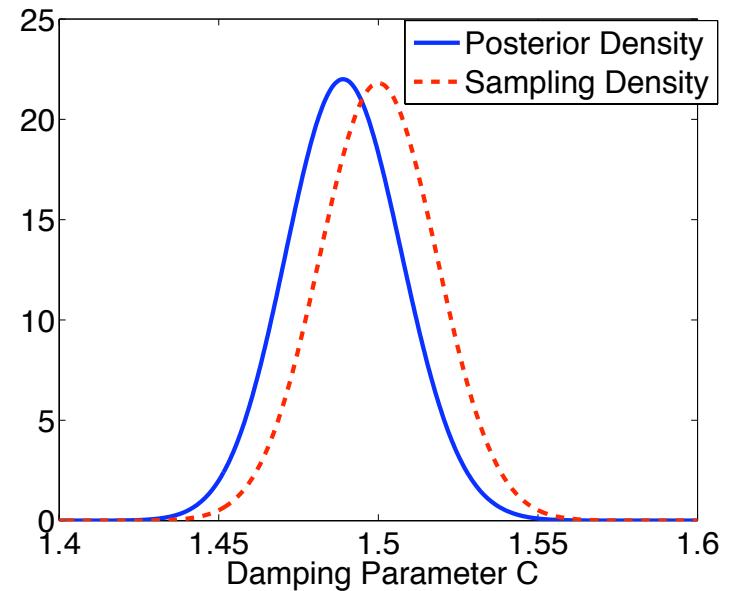
Issue: $e^{-SS_{q_{MAP}}} \approx 3 \times 10^{-113}$

Midpoint formula:

$$\pi(q|v) \approx \frac{1}{\sum_k e^{-(SS_{\zeta_i} - SS_q)w_i/2\sigma_0^2}}$$

Note:

- Slow even for one parameter.
- Strategy: create Markov chain using random sampling so that created chain has the posterior distribution as its limiting (stationary) distribution.



Bayesian Model Calibration

Bayesian Model Calibration:

- Parameters considered to be random variables with associated densities.

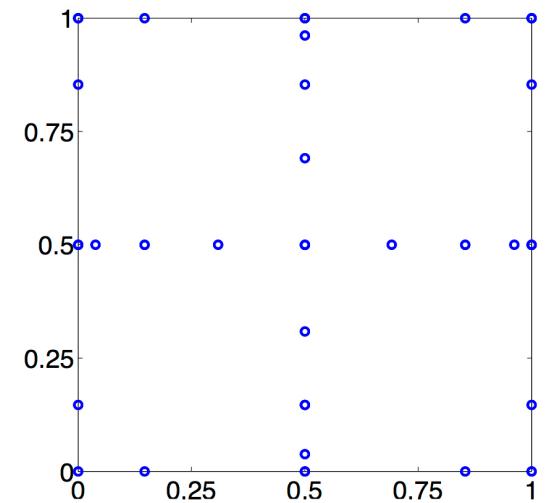
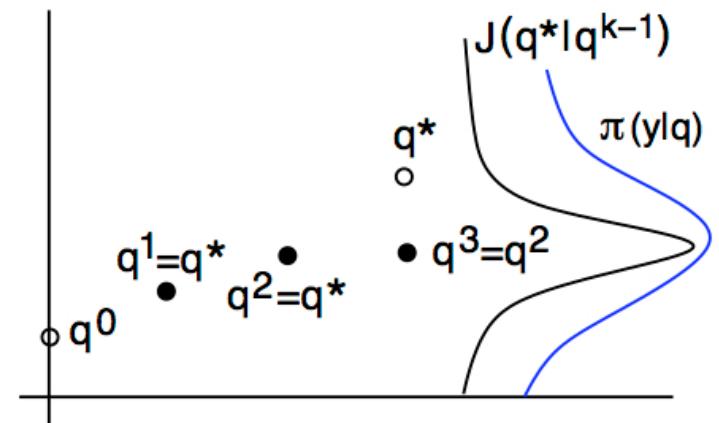
$$\pi(q|v) = \frac{\pi(v|q)\pi_0(q)}{\int_{\mathbb{R}^p} \pi(v|q)\pi_0(q)dq}$$

Problem:

- Often requires high dimensional integration;
 - e.g., $p = 18$ for MFC model
 - $p = \text{thousands to millions for some models}$

Strategies:

- Sampling methods
- Sparse grid quadrature techniques



Markov Chains

Definition: Sequence of random variables X_1, X_2, \dots that satisfy Markov property:
 X_{n+1} depends only on X_n ; that is

$$P(X_{n+1} = x_{n+1} | X_0 = x_0, X_1 = x_1, \dots, X_n = x_n) = P(X_{n+1} = x_{n+1} | X_n = x_n)$$

where x_i is the state of the chain at time i .

Note: A Markov chain is characterized by three components: a state space, an initial distribution, and a transition kernel.

State Space: Range of X_i : Set of all possible values

Initial Distribution: (Mass)

$$p^0 = [p_1^0, p_2^0, \dots, p_n^0] , \quad p_i^0 = P(X_0 = x_i)$$

Transition Probability: (Markov Kernel)

$$p_{ij} = P(X_{n+1} = x_j | X_n = x_i)$$

$$p_{ij}^{(n)} = P(X_{m+n} = x_j | X_m = x_i) \quad (\text{n-step transition probability})$$

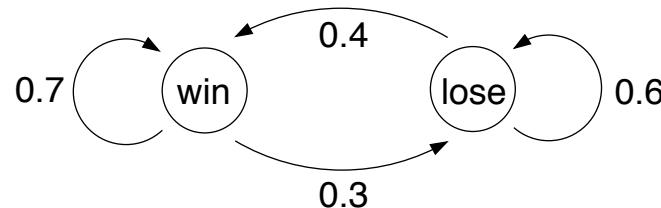
$$P = [p_{ij}] , \quad P_n = [p_{ij}^{(n)}]$$

Markov Chain Techniques

Markov Chain: Sequence of events where current state depends only on last value.

Baseball: States are $S = \{\text{win}, \text{lose}\}$. Initial state is $p^0 = [0.8, 0.2]$.

- Assume that team which won last game has 70% chance of winning next game and 30% chance of losing next game.
- Assume losing team wins 40% and loses 60% of next games.



- Percentage of teams who win/lose next game given by

$$p^1 = [0.8, 0.2] \begin{bmatrix} 0.7 & 0.3 \\ 0.4 & 0.6 \end{bmatrix} = [0.64, 0.36]$$

- Question: does the following limit exist?

$$p^n = [0.8, 0.2] \begin{bmatrix} 0.7 & 0.3 \\ 0.4 & 0.6 \end{bmatrix}^n$$

Markov Chain Techniques

Baseball Example: Solve constrained relation

$$\pi = \pi P , \quad \sum \pi_i = 1$$

$$\Rightarrow [\pi_{win} , \pi_{lose}] \begin{bmatrix} 0.7 & 0.3 \\ 0.4 & 0.6 \end{bmatrix} = [\pi_{win} , \pi_{lose}] , \quad \pi_{win} + \pi_{lose} = 1$$

to obtain

$$\pi = [0.5714 , 0.4286]$$

Markov Chain Techniques

Baseball Example: Solve constrained relation

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Alternative: Iterate to compute solution

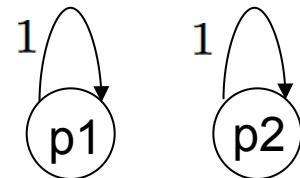
n	p^n	n	p^n	n	p^n
0	[0.8000 , 0.2000]	4	[0.5733 , 0.4267]	8	[0.5714 , 0.4286]
1	[0.6400 , 0.3600]	5	[0.5720 , 0.4280]	9	[0.5714 , 0.4286]
2	[0.5920 , 0.4080]	6	[0.5716 , 0.4284]	10	[0.5714 , 0.4286]
3	[0.5776 , 0.4224]	7	[0.5715 , 0.4285]		

Notes:

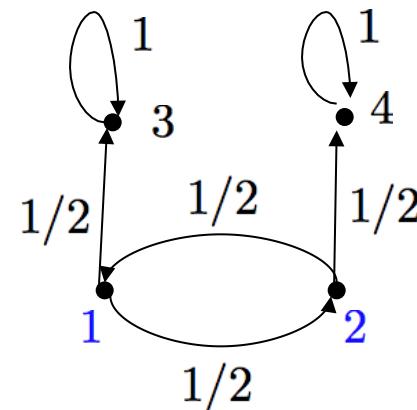
- Forms basis for Markov Chain Monte Carlo (MCMC) techniques
- Goal: construct chains whose stationary distribution is the posterior density

Irreducible Markov Chains

Reducible Markov Chain:



$$p^0 = [p_1, p_2] = \pi$$



$$P = \begin{bmatrix} 0 & 1/2 & 1/2 & 0 \\ 1/2 & 0 & 0 & 1/2 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

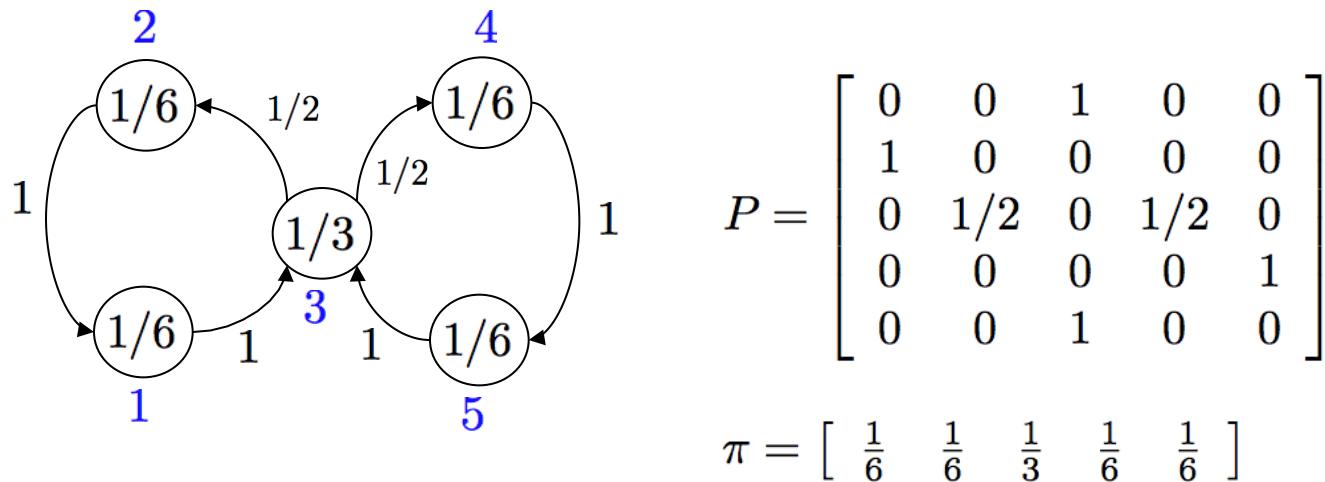
Note: Limiting distribution not unique if chain is reducible.

Irreducible: A Markov chain is *irreducible* if any state x_j can be reached from any state x_i in a finite number of steps; that is

$$p_{ij}^{(n)} > 0 \text{ for all states in finite } n$$

Periodic Markov Chains

Example:



Note: Chain returns to state 1 at steps 3, 6, 9, ... so Period = 3

Note: Probability mass “cycles” through chain so no convergence

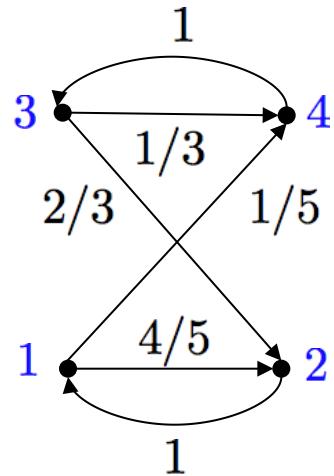
Periodicity: A Markov chain is *periodic* if parts of the state space are visited at regular intervals. The period k is defined as

$$\begin{aligned} k &= \gcd \left\{ n \mid p_{ii}^{(n)} > 0 \right\} \\ &= \gcd \{ n \mid P(X_{m+n} = x_i | X_m = x_i) > 0 \} \end{aligned}$$

- The chain is aperiodic if $k = 1$.

Periodic Markov Chains

Example:



$$P = \begin{bmatrix} 0 & 4/5 & 0 & 1/5 \\ 1 & 0 & 0 & 0 \\ 0 & 2/3 & 0 & 1/3 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$p^0 = \left[\frac{1}{4} \quad \frac{1}{4} \quad \frac{1}{4} \quad \frac{1}{4} \right]$$

$$p^0 = [1 \ 0 \ 0 \ 0]$$

Stationary Distribution

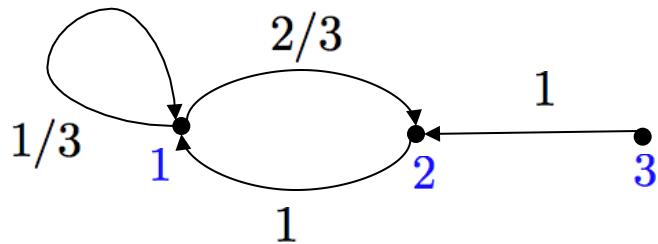
Theorem: A finite, homogeneous Markov chain that is irreducible and aperiodic has a unique stationary distribution π and the chain will converge in the sense of distributions from any initial distribution p^0 .

Recurrence (Persistence): A state x_i is recurrent (persistent) if the probability of returning to x_i is 1; that is,

$$P(X_{m+n} = x_i \text{ for some } n \geq 1 | X_m = x_i) = 1$$

- It is *transient* if probability strictly less than 1

Example: State 3 is transient



Ergodicity: A state is termed *ergodic* if it is aperiodic and recurrent. If all states of an irreducible Markov chain are ergodic, the chain is said to be *ergodic*.

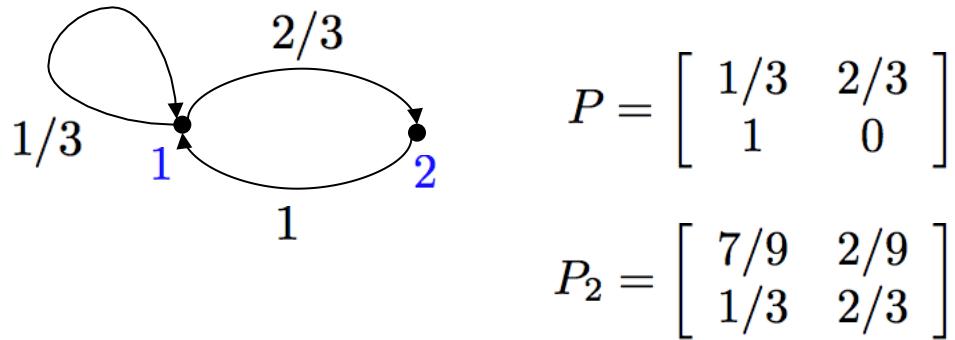
Matrix Theory

Definition: A matrix $A \in \mathbb{R}^{(n \times n)}$ is

- (i) Nonnegative, denoted $A \geq 0$, if $a_{ij} \geq 0$ for all i, j
- (ii) Strictly positive, denoted $A > 0$, if $a_{ij} > 0$ for all i, j

Lemma: Let P be the transition matrix of an ergodic finite Markov chain with state space S . Then for some $N_0 \geq 1$, $P_n > 0$ for all $n > N_0$.

Example:



Matrix Theory

Theorem (Perron-Frobenius): For any strictly positive matrix $A > 0$, there exist $\lambda_0 > 0$ and $x_0 > 0$ such that

- (i) $Ax_0 = \lambda_0 x_0$
- (ii) If $\lambda \neq \lambda_0$ is any other eigenvalue of A , then $|\lambda| < \lambda_0$
- (iii) λ_0 has geometric and algebraic multiplicity 1

Corollary 1: If $A \geq 0$ is a nonnegative matrix such that $A^n > 0$, then theorem also applies to A .

Proposition: Let $A > 0$ be a strictly positive $n \times n$ matrix with row and column sums

$$r_i = \sum_j a_{ij} \quad , \quad c_j = \sum_i a_{ij} \quad , \quad i, j = 1, \dots, n$$

Then

$$\min_i r_i \leq \lambda_0 \leq \max_i r_i \quad , \quad \min_j c_j \leq \lambda_0 \leq \max_j c_j$$

Stationary Distribution

Corollary: Let $P \geq 0$ be the transition matrix of an ergodic Markov chain. Then there exists a unique stationary distribution π such that $\pi P = \pi$.

Proof: By Lemma and Corollary 1, P has a largest eigenvalue $\lambda_0 = 1$.

Since multiplicity is 1, unique π such that $\pi P = \pi$ and $\sum_i \pi_i = 1$.

Convergence: Express

$$UPV = \Lambda = \begin{bmatrix} 1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_n \end{bmatrix}$$

where $1 > |\lambda_2| \geq \dots \geq |\lambda_n|$, $V = U^{-1}$

Note:

$$P^n = V \begin{bmatrix} 1 & & & \\ & \lambda_2^n & & \\ & & \ddots & \\ & & & \lambda_n^n \end{bmatrix} U \rightarrow V \begin{bmatrix} 1 & & & \\ & 0 & & \\ & & \ddots & \\ & & & 0 \end{bmatrix} U$$

Stationary Distribution

Note:

$$UP = \Lambda U \Rightarrow \begin{bmatrix} \pi_1 & \cdots & \pi_n \\ \vdots & & \vdots \end{bmatrix} \begin{bmatrix} P \end{bmatrix} = \begin{bmatrix} 1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_n \end{bmatrix} \begin{bmatrix} \pi_1 & \cdots & \pi_n \\ \vdots & & \vdots \end{bmatrix}$$

and

$$V = U^{-1} = \begin{bmatrix} \pi_1 & \cdots & \pi_n \\ \vdots & & \vdots \end{bmatrix} \begin{bmatrix} 1 & \cdots \\ \vdots & \\ 1 & \cdots \end{bmatrix} = \begin{bmatrix} 1 & \cdots & 0 \\ \vdots & & \vdots \\ 0 & \cdots & 1 \end{bmatrix}$$

Thus

$$\begin{aligned} \lim_{n \rightarrow \infty} p^n &= \lim_{n \rightarrow \infty} p^0 P^n \\ &= \lim_{n \rightarrow \infty} [p_1^0 \ \cdots \ p_n^0] \begin{bmatrix} 1 & \cdots \\ \vdots & \\ 1 & \cdots \end{bmatrix} \begin{bmatrix} 1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_n \end{bmatrix} \begin{bmatrix} \pi_1 & \cdots & \pi_n \\ \vdots & & \vdots \end{bmatrix} \\ &= [p_1^0 \ \cdots \ p_n^0] \begin{bmatrix} 1 & \cdots \\ \vdots & \\ 1 & \cdots \end{bmatrix} \begin{bmatrix} 1 & & & \\ & 0 & & \\ & & \ddots & \\ & & & 0 \end{bmatrix} \begin{bmatrix} \pi_1 & \cdots & \pi_n \\ \vdots & & \vdots \end{bmatrix} \\ &= [\pi_1 \cdots \pi_n] \\ &= \pi \end{aligned}$$

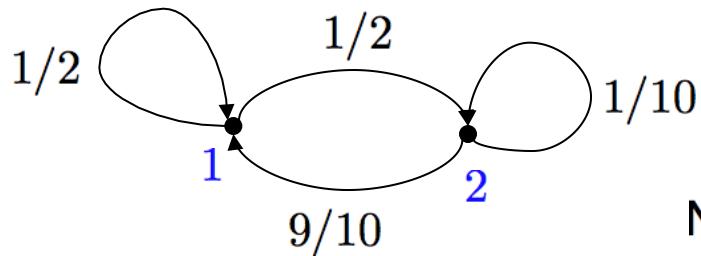
Detailed Balance Conditions

Reversible Chains: A Markov chain determined by the transition matrix $P = [p_{ij}]$ is reversible if there is a distribution π that satisfies the detailed balance conditions

$$\pi_i p_{ij} = \pi_j p_{ji}$$

Proof: We need to show that $\pi_j = \sum_i \pi_i p_{ij}$. Note that $\sum_i \pi_i p_{ij} = \sum_i \pi_j p_{ji} = \pi_j \sum_i p_{ji}$

Example:



$$P = \begin{bmatrix} 1/2 & 1/2 \\ 9/10 & 1/10 \end{bmatrix}$$

$$\pi = \begin{bmatrix} 9/14 & 5/14 \end{bmatrix}$$

Note: $\frac{1}{2} \cdot \frac{9}{14} = \frac{9}{10} \cdot \frac{5}{14}$ so detailed balance satisfied

Markov Chain Monte Carlo Methods

Strategy: Markov chain simulation used when it is impossible, or computationally prohibitive, to sample q directly from

$$\pi(q|v) = \frac{\pi(v|q)\pi_0(q)}{\int_{\mathbb{R}^p} \pi(v|q)\pi_0(q)dq}$$

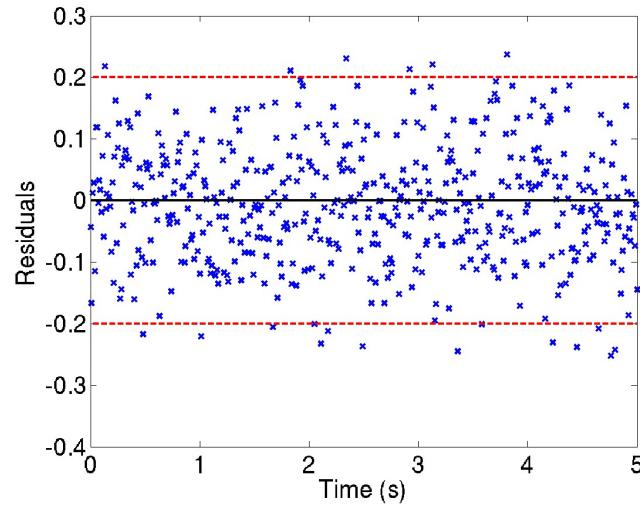
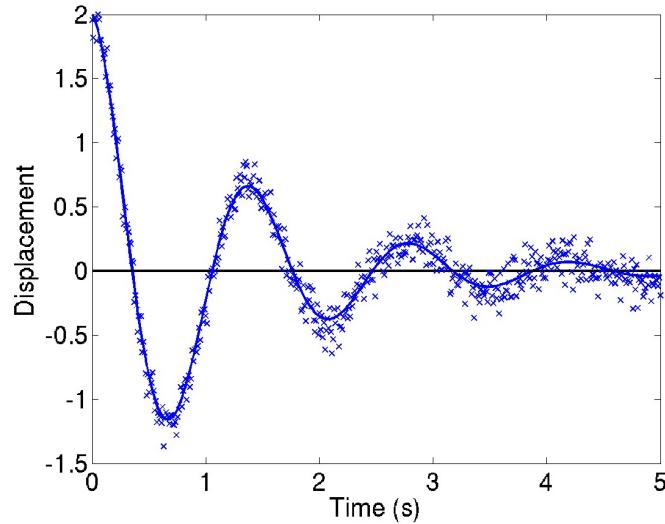
- Create a Markov process whose stationary distribution is $\pi(q|v)$.

Note:

- In Markov chain theory, we are given a Markov chain, P , and we construct its equilibrium distribution.
- In MCMC theory, we are “given” a distribution and we want to construct a Markov chain that is reversible with respect to it.

Model Calibration Problem

Assumption: Assume that measurement errors are iid and $\varepsilon_i \sim N(0, \sigma^2)$



Likelihood:

$$\pi(v|q) = L(q, \sigma|v) = \frac{1}{(2\pi\sigma^2)^{n/2}} e^{-SS_q/2\sigma^2}$$

where

$$SS_q = \sum_{i=1}^n [v_i - f_i(q)]^2$$

is the sum of squares error.

Markov Chain Monte Carlo Methods

General Strategy:

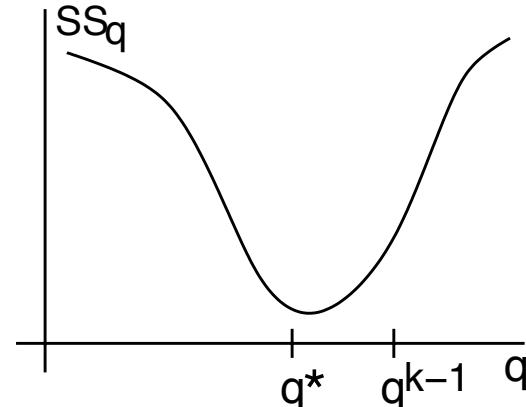
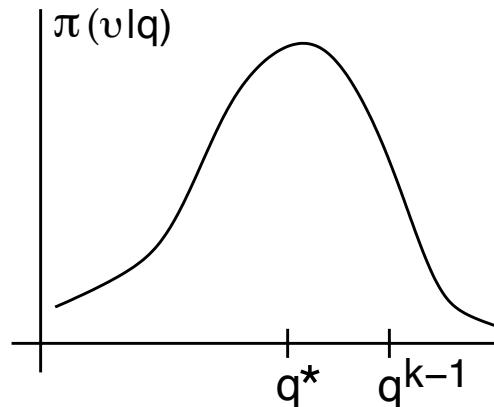
- Current value: $X_{k-1} = q^{k-1}$
- Propose candidate $q^* \sim J(q^*|q^{k-1})$ from proposal (jumping) distribution
- With probability $\alpha(q^*, q^{k-1})$, accept q^* ; i.e., $X_k = q^*$
- Otherwise, stay where you are: $X_k = q^{k-1}$

Intuition: Recall that

$$\pi(q|v) = \frac{\pi(v|q)\pi_0(q)}{\int_{\mathbb{R}^p} \pi(v|q)\pi_0(q)dq}$$

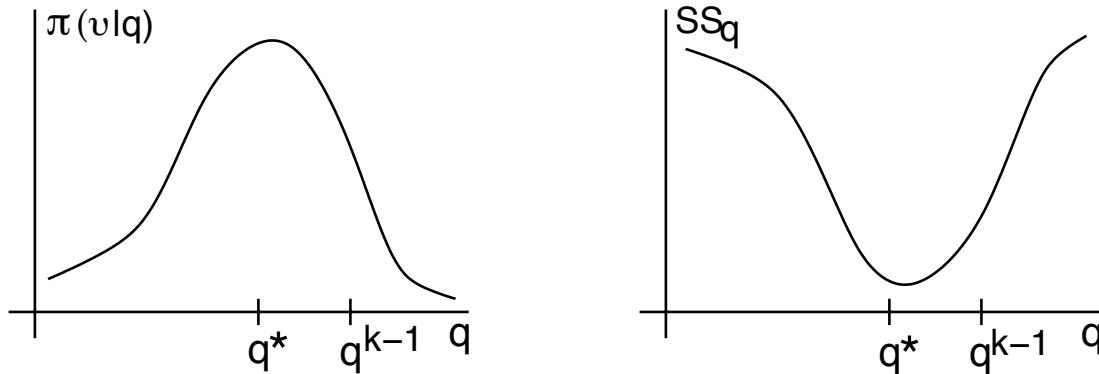
where

$$\pi(v|q) = \frac{1}{(2\pi\sigma^2)^{n/2}} e^{-\sum_{i=1}^n [v_i - f_i(q)]^2 / 2\sigma^2} = \frac{1}{(2\pi\sigma^2)^{n/2}} e^{-SS_q / 2\sigma^2}$$



Markov Chain Monte Carlo Methods

Intuition:

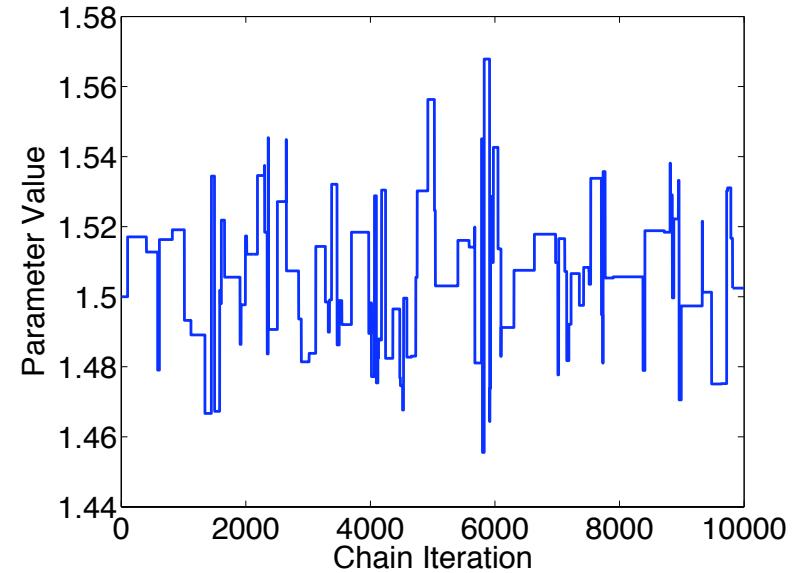
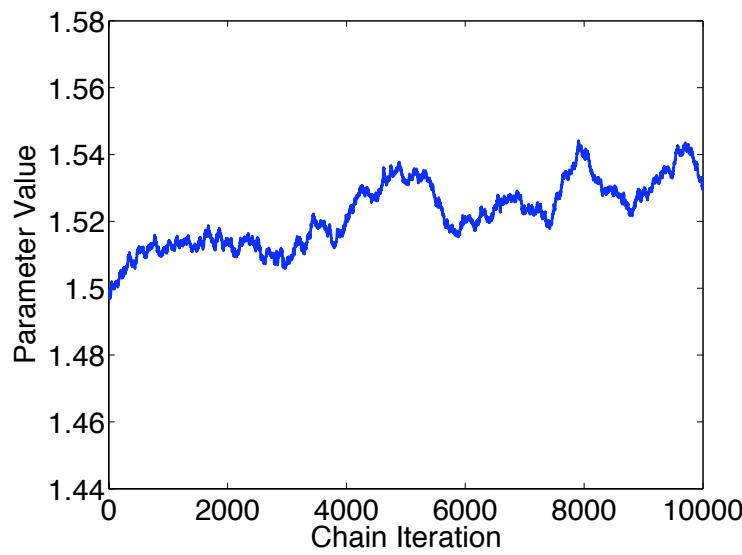
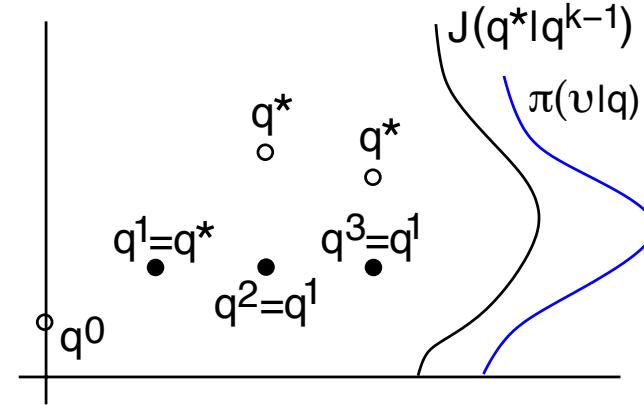
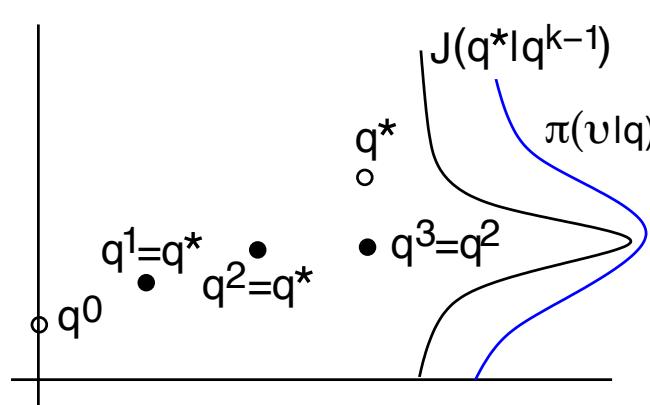


- Consider $r(q^*|q^{k-1}) = \frac{\pi(q^*|v)}{\pi(q^{k-1}|v)} = \frac{\pi(v|q^*)\pi_0(q^*)}{\pi(v|q^{k-1})\pi_0(q^{k-1})}$
 - If $r < 1 \Leftrightarrow \pi(v|q^*) < \pi(v|q^{k-1})$, accept with probability $\alpha = r$
 - If $r > 1$, accept with probability $\alpha = 1$

Note: Narrower proposal distribution yields higher probability of acceptance.

Markov Chain Monte Carlo Methods

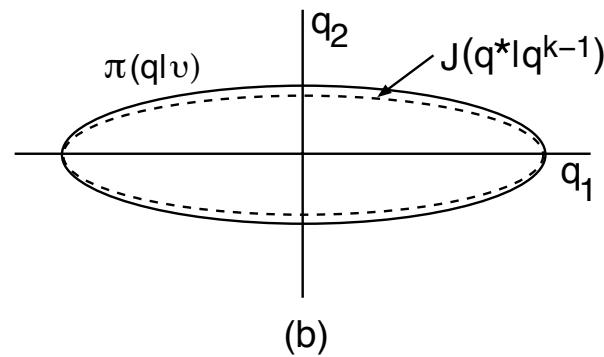
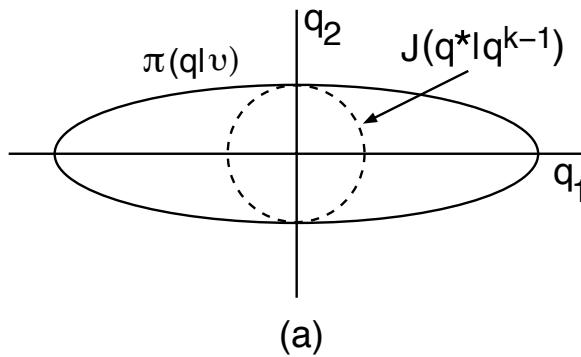
Note: Narrower proposal distribution yields higher probability of acceptance.



Proposal Distribution

Proposal Distribution: Significantly affects mixing

- Too wide: Too many points rejected and chain stays still for long periods;
- Too narrow: Acceptance ratio is high but algorithm is slow to explore parameter space
- Ideally, it should have similar “shape” to posterior distribution.



Problem:

- Anisotropic posterior, isotropic proposal;
- Efficiency nonuniform for different parameters

Result:

- Recovers efficiency of univariate case

Proposal Distribution

Proposal Distribution: Two basic approaches

- Choose a fixed proposal function

- Independent Metropolis

- Random walk (local Metropolis)

$$q^* = q^{k-1} + Rz$$

- Two (of several) choices: $z \sim N(0, 1)$

$$(i) R = cI \Rightarrow q^* \sim N(q^{k-1}, cI)$$

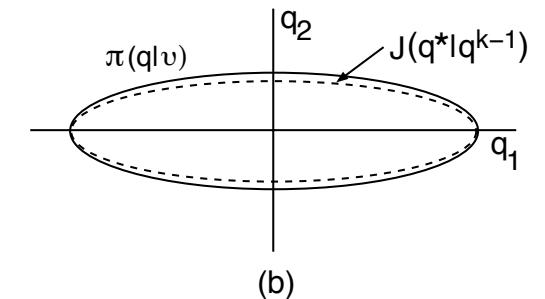
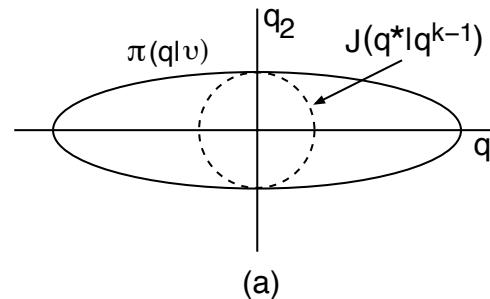
$$(ii) R = \text{chol}(V) \Rightarrow q^* \sim N(q^{k-1}, V)$$

where

Sensitivity Matrix

$$V = \sigma_{OLS}^2 [\mathcal{X}^T(q_{OLS}) \mathcal{X}(q_{OLS})]^{-1}$$

$$\sigma_{OLS}^2 = \frac{1}{n-p} \sum_{i=1}^n [v_i - f_i(q_{OLS})]^2$$



Metropolis Algorithm

Metropolis Algorithm: [Metropolis and Ulam, 1949]

1. Initialization: Choose an initial parameter value q^0 that satisfies $\pi(q^0|v) > 0$.
2. For $k = 1, \dots, M$

- (a) For $z \sim N(0, 1)$, construct the candidate

$$q^* = q^{k-1} + Rz$$

where R is the Cholesky decomposition of V or D . This ensures that

$$q^* \sim N(q^{k-1}, V) \text{ or } q^* \sim N(q^{k-1}, D).$$

- (b) Compute the ratio

$$r(q^*|q^{k-1}) = \frac{\pi(q^*|v)}{\pi(q^{k-1}|v)} = \frac{\pi(v|q^*)\pi_0(q^*)}{\pi(v|q^{k-1})\pi_0(q^{k-1})}. \quad (1)$$

- (c) Set

$$q^k = \begin{cases} q^* & , \text{ with probability } \alpha = \min(1, r) \\ q^{k-1} & , \text{ else.} \end{cases}$$

That is, we accept q^* with probability 1 if $r \geq 1$ and we accept it with probability r if $r < 1$.

Metropolis-Hastings Algorithm

Metropolis-Hastings Algorithm: $J(q^*|q^{k-1})$ does not have to be symmetric

$$\begin{aligned}\bullet \text{ Acceptance Ratio: } r(q^*|q^{k-1}) &= \frac{\pi(q^*|v)/J(q^*|q^{k-1})}{\pi(q^{k-1}|v)/J(q^{k-1}|q^*)} \\ &= \frac{\pi(v|q^*)\pi_0(q^*)J(q^{k-1}|q^*)}{\pi(v|q^{k-1})\pi_0(q^{k-1})J(q^*|q^{k-1})}.\end{aligned}$$

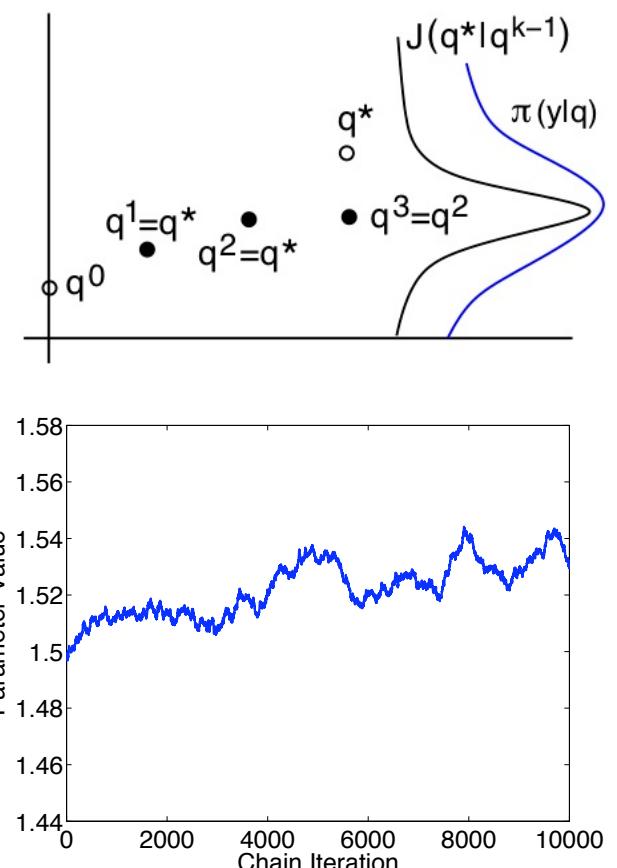
Examples:

- Cauchy distribution: $J(q^*|q^{k-1}) = \frac{1}{\pi[1+(q^*)^2]}$
- $\chi^2(k)$ distribution: $J(q^*|q^{k-1}) = \kappa(q^*)^{k/2-1} e^{q^*/2}$

Note: Considered one of top 10 algorithms of 20th century

Random Walk Metropolis Algorithm for Parameter Estimation

1. Set number of chain elements M and design parameters n_s, σ_s
2. Determine $q^0 = \arg \min_q \sum_{i=1}^N [v_i - f_i(q)]^2$
3. Set $SS_{q^0} = \sum_{i=1}^N [v_i - f_i(q^0)]^2$
4. Compute initial variance estimate: $s_0^2 = \frac{SS_{q^0}}{n-p}$
5. Construct covariance estimate $V = s_0^2 [\mathcal{X}^T(q^0) \mathcal{X}(q^0)]^{-1}$ and $R = \text{chol}(V)$
6. For $k = 1, \dots, M$
 - (a) Sample $z_k \sim N(0, 1)$
 - (b) Construct candidate $q^* = q^{k-1} + R z_k$
 - (c) Sample $u_\alpha \sim U(0, 1)$
 - (d) Compute $SS_{q^*} = \sum_{i=1}^N [v_i - f_i(q^*)]^2$
 - (e) Compute
$$\alpha(q^* | q^{k-1}) = \min \left(1, e^{-[SS_{q^*} - SS_{q^{k-1}}]/2s_{k-1}^2} \right)$$
 - (f) If $u_\alpha < \alpha$,
 - Set $q^k = q^*$, $SS_{q^k} = SS_{q^*}$
 - else
 - Set $q^k = q^{k-1}$, $SS_{q^k} = SS_{q^{k-1}}$
 - endif
 - (g) Update $s_k \sim \text{Inv-gamma}(a_{val}, b_{val})$ where
$$a_{val} = 0.5(n_s + n), b_{val} = 0.5(n_s \sigma_s^2 + SS_{q^k})$$



Sampling Error Variance

Strategy: Treat error variance σ^2 as parameter to be sampled.

Definition: The property that the prior and posterior distributions have the same parametric form is termed *conjugacy*.

Note: The likelihood

$$\pi(v, q | \sigma^2) = \frac{1}{(2\pi\sigma^2)^{n/2}} e^{-SS_q/2\sigma^2}$$

has the conjugate prior

$$\pi_0(\sigma^2) \propto (\sigma^2)^{-(\alpha+1)} e^{\beta/\sigma^2}$$

The posterior is

$$\pi(\sigma^2 | q, v) \propto (\sigma^2)^{-(\alpha+1+n/2)} e^{-(\beta+SS_q/2)/\sigma^2}$$

so that

$$\sigma^2 | (v, q) \sim \text{Inv-gamma} \left(\alpha + \frac{n}{2}, \beta + \frac{SS_q}{2} \right)$$

or

$$\sigma^2 | (v, q) \sim \text{Inv-gamma} \left(\frac{n_s + n}{2}, \frac{n_s \sigma_s^2 + SS_q}{2} \right)$$

Note:

- n_0 taken small;
e.g., $n_0 = 1$ or $n_0 = .01$
- Take $\sigma_s^2 = s_{k-1}^2 = \frac{R_{k-1}^T R_{k-1}}{n-p}$

Random Walk Metropolis

Example: We revisit the spring model

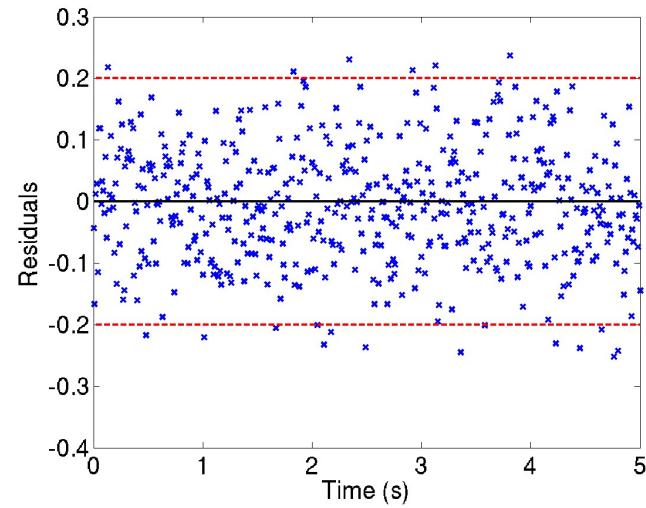
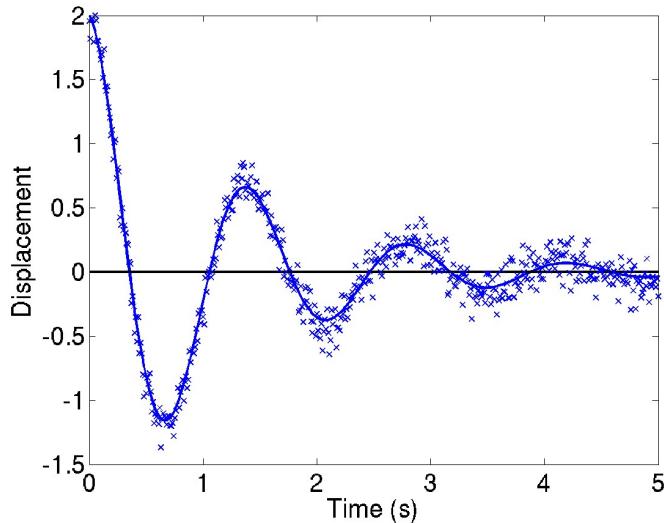
$$\ddot{z} + C\dot{z} + Kz = 0$$

$$z(0) = 2, \dot{z}(0) = -C$$

which has the solution

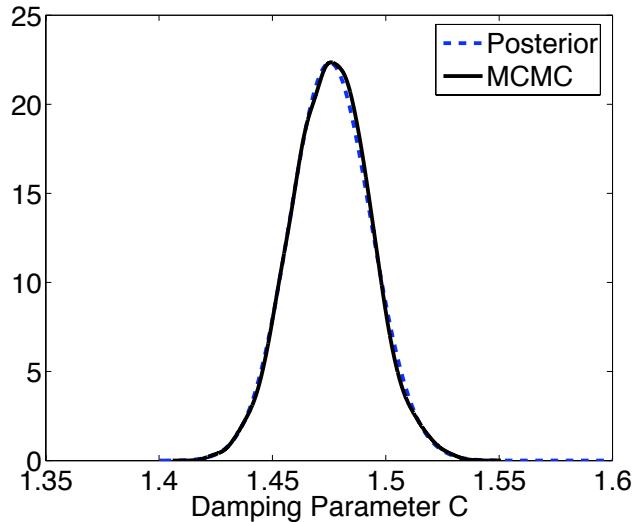
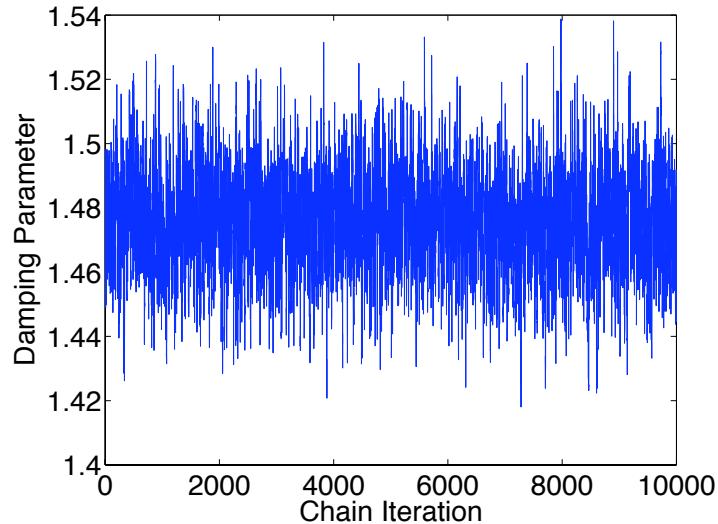
$$z(t) = 2e^{-Ct/2} \cos(\sqrt{K - C^2/4} \cdot t)$$

We assume that $\varepsilon_i \sim N(0, \sigma_0^2)$ where $\sigma_0 = 0.1$.



Random Walk Metropolis

Case i: Take $K = 20.5$ and $Q = [C, \sigma^2]$

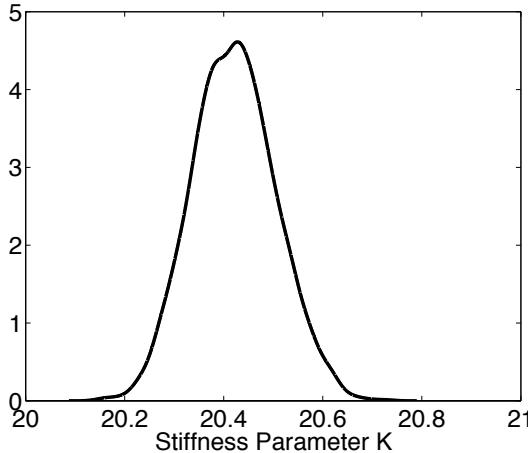
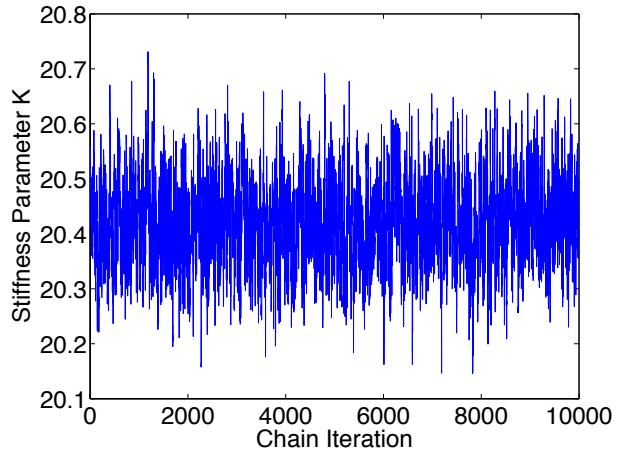
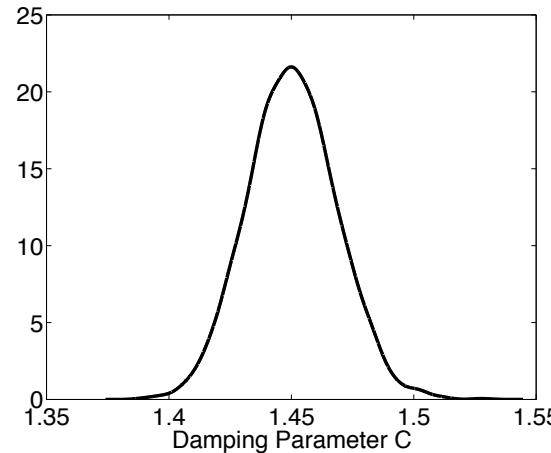
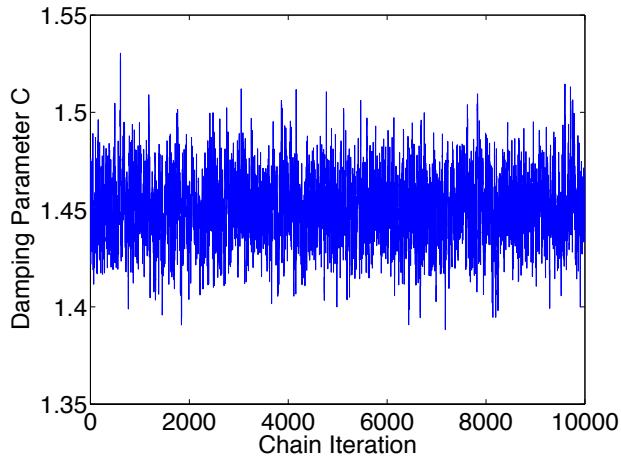


Note: Kernel density estimator (KDE) used to construct density.

Random Walk Metropolis

Case ii: Take $Q = [C, K, \sigma^2]$ with $J(q^*|q^{k-1}) = N(q^{k-1}, V)$ and

$$V = \begin{bmatrix} 0.000345 & 0.000268 \\ 0.000268 & 0.007071 \end{bmatrix}$$



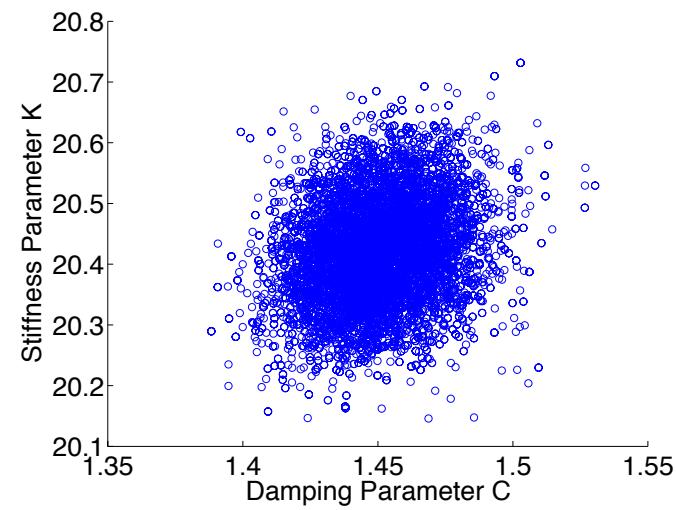
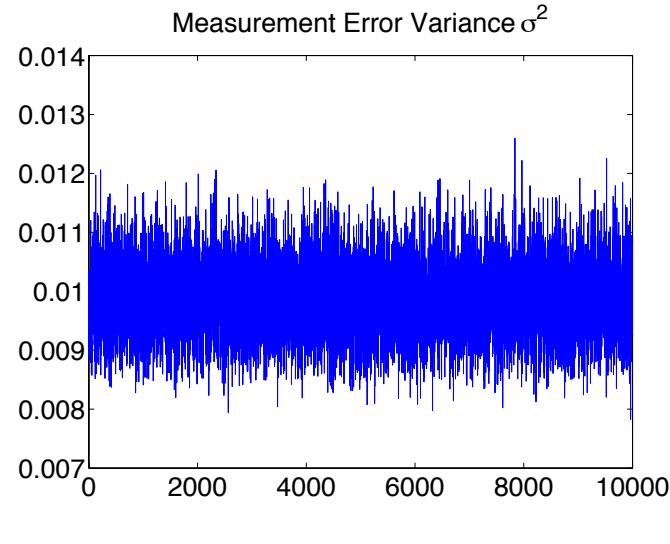
Note:

$$\begin{aligned} 2\sigma_C &\approx 0.04 \\ \Rightarrow \sigma_C^2 &\approx 0.4 \times 10^{-3} \end{aligned}$$

$$\begin{aligned} 2\sigma_K &\approx 0.18 \\ \Rightarrow \sigma_K^2 &\approx 0.0081 \end{aligned}$$

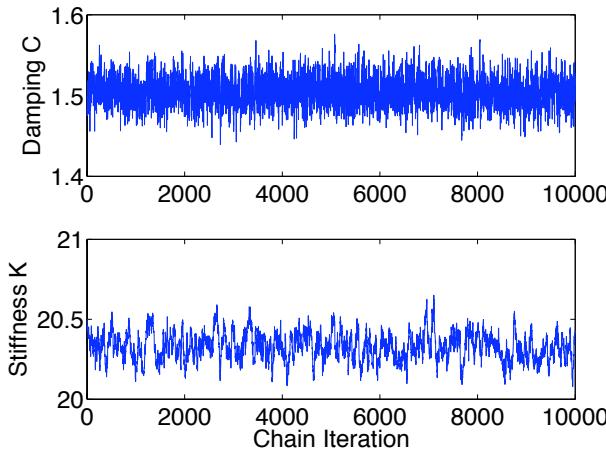
Random Walk Metropolis

Case ii: Measurement error variance and joint samples

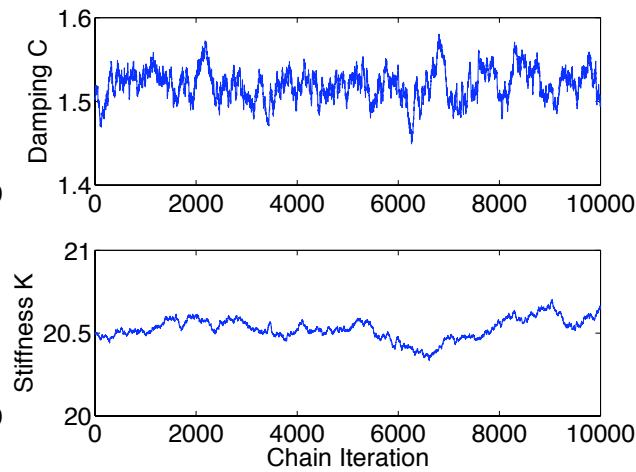


Random Walk Metropolis

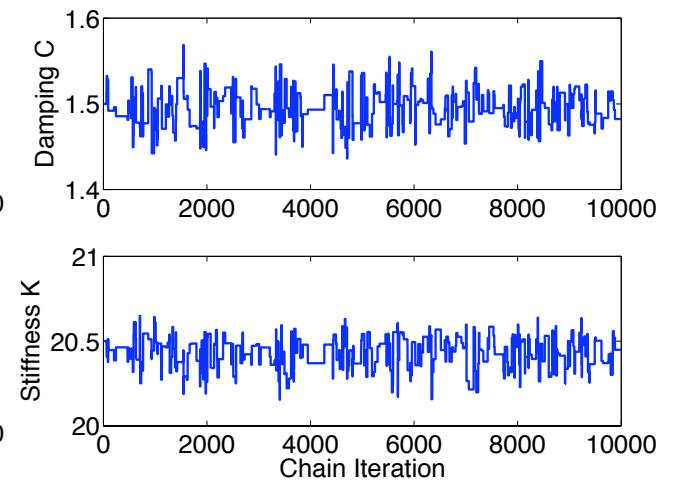
Case iii: Isotropic proposal function $J(q^*|q^{k-1}) = N(q^{k-1}, sI)$



$$s = 9 \times 10^{-4}$$



$$s = 9 \times 10^{-6}$$



$$s = 9 \times 10^{-2}$$

Stationary Distribution and Convergence Criteria

Here

$$\begin{aligned} p_{k-1,k} &= P(X_k = q^k | X_{k-1} = q^{k-1}) \\ &= P(\text{proposing } q^k)P(\text{accepting } q^k) \\ &= J(q^k | q^{k-1})\alpha(q^k | q^{k-1}) \\ &= J(q^k | q^{k-1}) \min \left(1, \frac{\pi(q^k | v)J(q^{k-1} | q^k)}{\pi(q^{k-1} | v)J(q^k | q^{k-1})} \right) \end{aligned}$$

Detailed Balance Condition:

$$\begin{aligned} \pi_{k-1} p_{k-1,k} &= \pi_k p_{k,k-1} \\ \Rightarrow \pi(q^{k-1} | v) p_{k-1,k} &= \pi(q^k | v) p_{k,k-1} \end{aligned}$$

From relation

$$v \min(1, x/v) = \min(x, v) = x \min(1, v/x)$$

it follows that

$$\begin{aligned} \pi(q^{k-1} | v) p_{k-1,k} &= \pi(q^{k-1} | v) J(q^k | q^{k-1}) \min \left(1, \frac{\pi(q^k | v)J(q^{k-1} | q^k)}{\pi(q^{k-1} | v)J(q^k | q^{k-1})} \right) \\ &= \pi(q^k | v) J(q^{k-1} | q^k) \min \left(1, \frac{\pi(q^{k-1} | v)J(q^k | q^{k-1})}{\pi(q^k | v)J(q^{k-1} | q^k)} \right) \\ &= \pi(q^k | v) p_{k,k-1} \end{aligned}$$

Delayed Rejection Adaptive Metropolis (DRAM)

Adaptive Metropolis:

- Update chain covariance matrix as chain values are accepted.

$$V_k = s_p \text{cov}(q^0, q^1, \dots, q^{k-1}) + \varepsilon I_p$$

- *Diminishing adaptation and bounded convergence* required since no longer Markov chain.
- Employ recursive relations

$$\bar{q}^k = \frac{1}{k+1} \sum_{i=0}^k q^i$$

$$= \frac{k}{k+1} \cdot \frac{1}{k} \sum_{i=0}^{k-1} q^i + \frac{1}{k+1} q^k$$

$$= \frac{k}{k+1} \bar{q}^{k-1} + \frac{1}{k+1} q^k$$

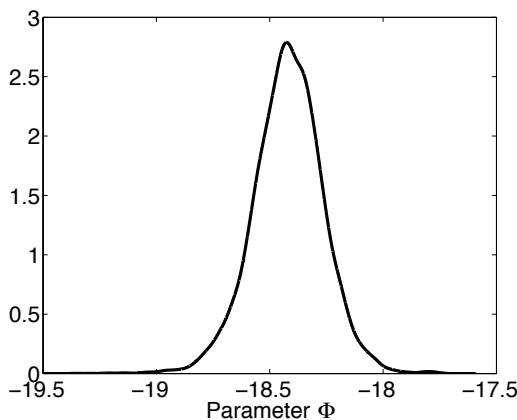
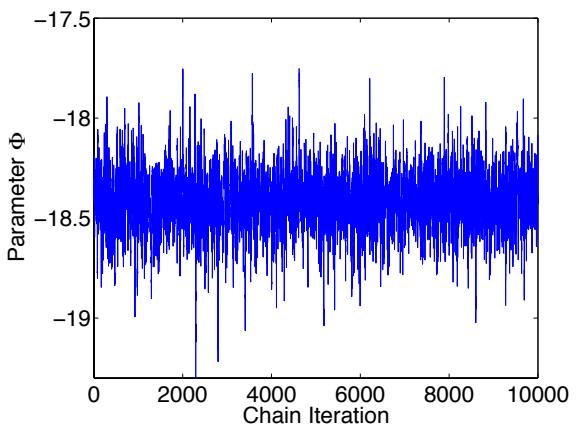
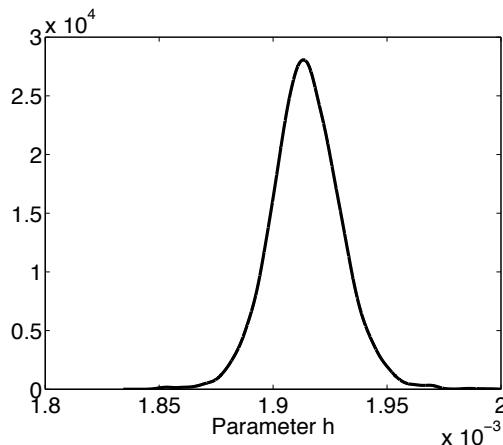
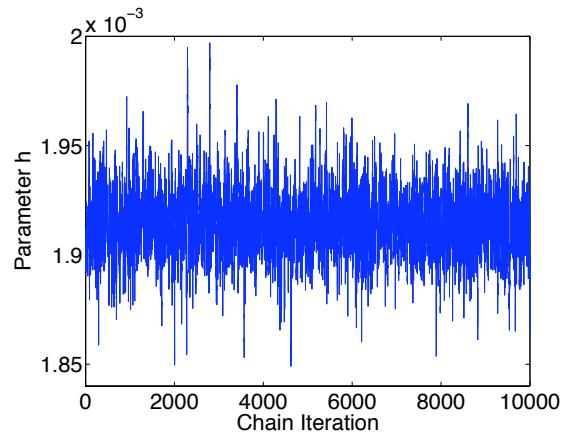
$$V_{k+1} = \frac{k-1}{k} V_k + \frac{s_p}{k} [k \bar{q}^{k-1} (\bar{q}^{k-1})^T - (k+1) \bar{q}^k (\bar{q}^k)^T + q^k (q^k)^T + \varepsilon I_p]$$

Delayed Rejection Adaptive Metropolis (DRAM)

Example: Heat model

$$\frac{d^2T_s}{dx^2} = \frac{2(a+b)}{ab} \frac{h}{k} [T_s(x) - T_{amb}]$$

$$\frac{dT_s}{dx}(0) = \frac{\Phi}{k} \quad , \quad \frac{dT_s}{dx}(L) = \frac{h}{k} [T_{amb} - T_s(L)]$$



Bayesian Analysis

$$\sigma = 0.2604$$

$$\sigma_\Phi = 0.1552$$

$$\sigma_h = 1.5450 \times 10^{-5}$$

Frequentist Analysis

$$\sigma = 0.2504$$

$$\sigma_\Phi = 0.1450$$

$$\sigma_h = 1.4482 \times 10^{-5}$$

Delayed Rejection Adaptive Metropolis (DRAM)

Example: HIV model

$$\dot{T}_1 = \lambda_1 - d_1 T_1 - (1 - \varepsilon) k_1 V T_1$$

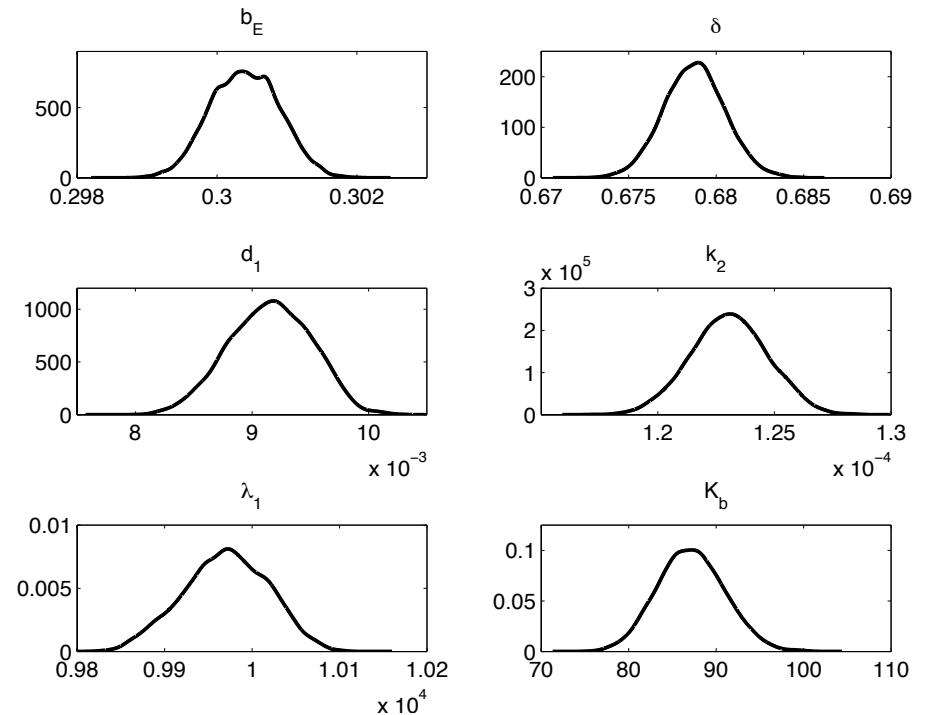
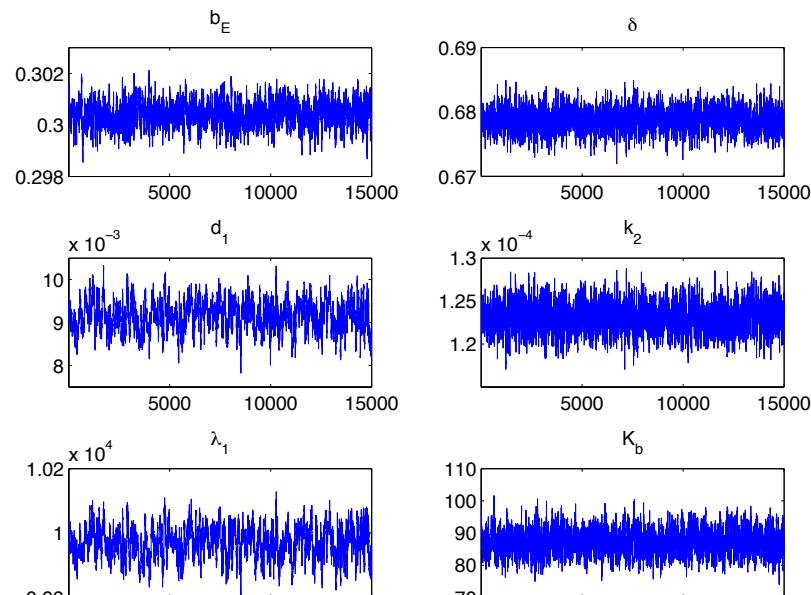
$$\dot{T}_2 = \lambda_2 - d_2 T_2 - (1 - f\varepsilon) k_2 V T_2$$

$$\dot{T}_1^* = (1 - \varepsilon) k_1 V T_1 - \delta T_1^* - m_1 E T_1^*$$

$$\dot{T}_2^* = (1 - f\varepsilon) k_2 V T_2 - \delta T_2^* - m_2 E T_2^*$$

$$\dot{V} = N_T \delta(T_1^* + T_2^*) - cV - [(1 - \varepsilon)\rho_1 k_1 T_1 + (1 - f\varepsilon)\rho_2 k_2 T_2]V$$

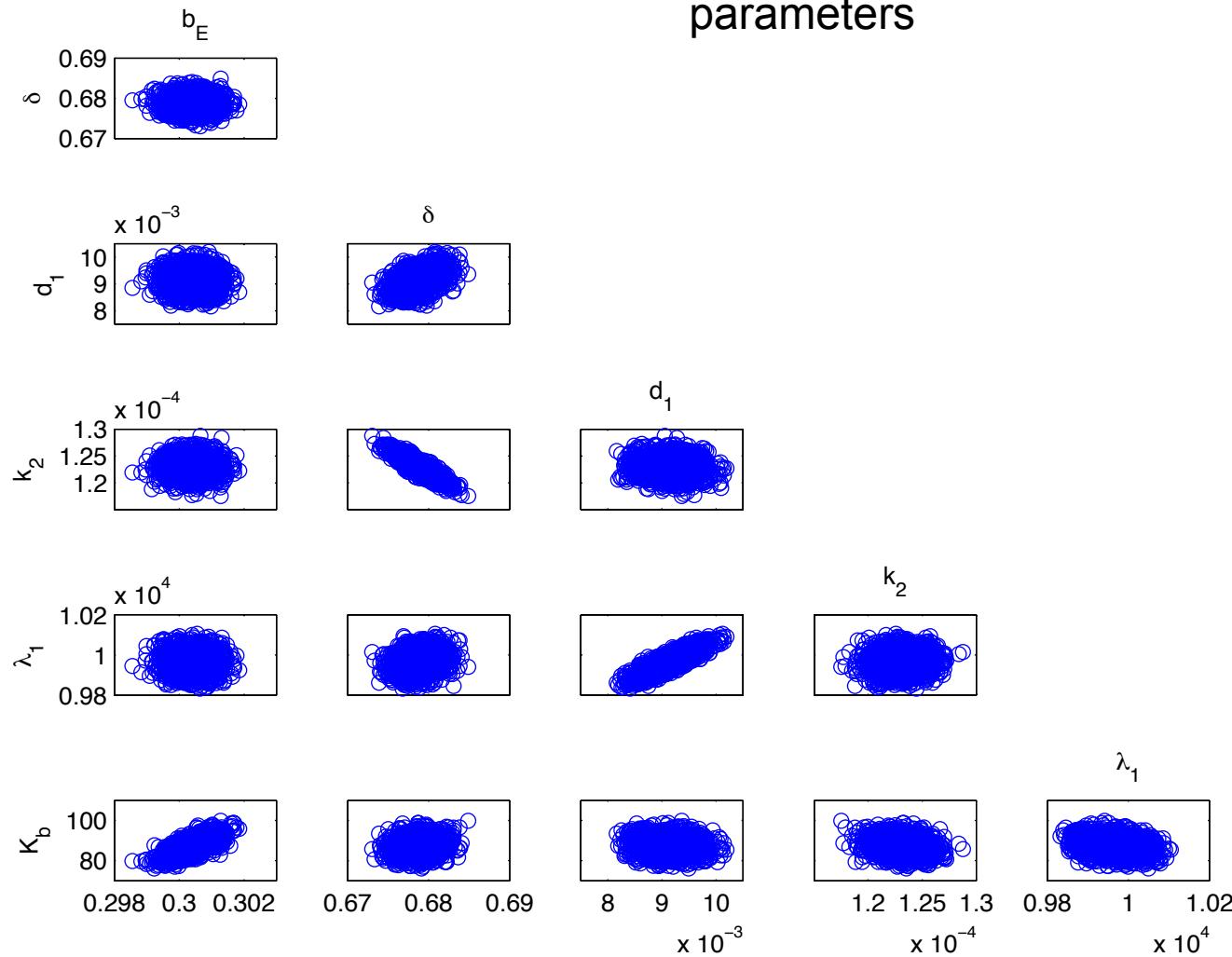
$$\dot{E} = \lambda_E + \frac{b_E(T_1^* + T_2^*)}{T_1^* + T_2^* + K_b} E - \frac{d_E(T_1^* + T_2^*)}{T_1^* + T_2^* + K_d} E - \delta_E E.$$



Delayed Rejection Adaptive Metropolis (DRAM)

Example: HIV model

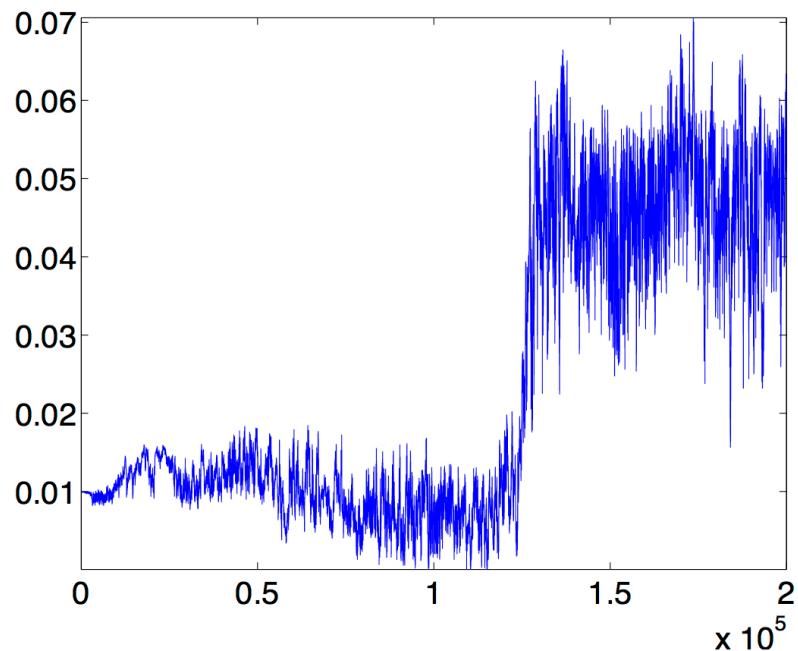
Note: Correlated versus nonidentifiable parameters



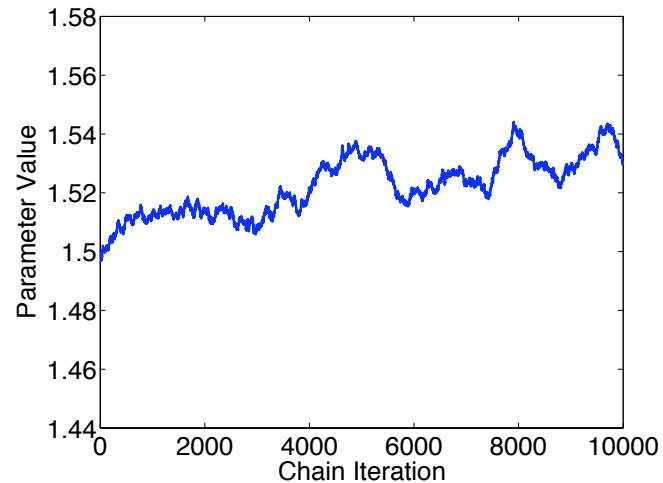
Chain Convergence (Burn-In)

Techniques:

- Visually check chains
- Statistical tests
- Often abused in the literature



Chain for nonidentifiable parameter



Chain not converged

Delayed Rejection Adaptive Metropolis (DRAM)

Websites

- http://www4.ncsu.edu/~rsmith/UQ_TIA/CHAPTER8/index_chapter8.html
- <http://helios.fmi.fi/~lainema/mcmc/>

Examples

- [Examples](#) on using the toolbox for some statistical problems.

Delayed Rejection Adaptive Metropolis (DRAM)

We fit the Monod model

$$y = \theta_1 \frac{1}{\theta_2 + x} + \epsilon \quad , \quad \epsilon \sim N(0, I\sigma^2)$$

to observations

x (mg / L COD): 28 55 83 110 138 225 375
y (1 / h): 0.053 0.060 0.112 0.105 0.099 0.122 0.125

First clear some variables from possible previous runs.

```
clear data model options
```

Next, create a data structure for the observations and control variables. Typically one could make a structure data that contains fields xdata and ydata.

```
data.xdata = [28 55 83 110 138 225 375]'; % x (mg / L COD)  
data.ydata = [0.053 0.060 0.112 0.105 0.099 0.122 0.125]'; % y (1 / h)
```

Construct model

```
modelfun = @(x,theta) theta(1)*x./(theta(2)+x);  
ssfun = @(theta,data) sum((data.ydata-modelfun(data.xdata,theta)).^2);  
model.ssfun = ssfun;  
model.sigma2 = 0.01^2;
```

Delayed Rejection Adaptive Metropolis (DRAM)

Input parameters

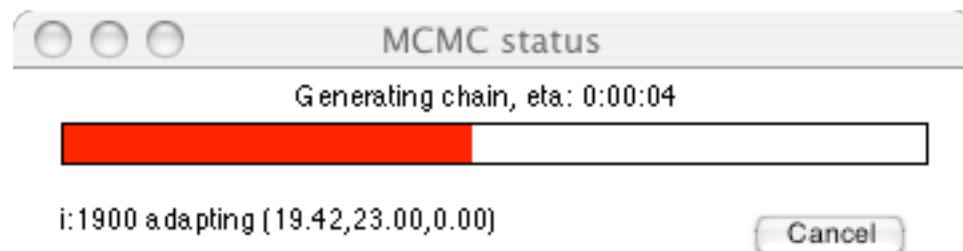
```
params = {  
    {'theta1', tmin(1), 0}  
    {'theta2', tmin(2), 0} };
```

and set options

```
options.nsimu = 4000;  
options.updatesigma = 1;  
options.qcov = tcov;
```

Run code

```
[res,chain,s2chain] = mcmcrun(model,data,params,options);
```



Delayed Rejection Adaptive Metropolis (DRAM)

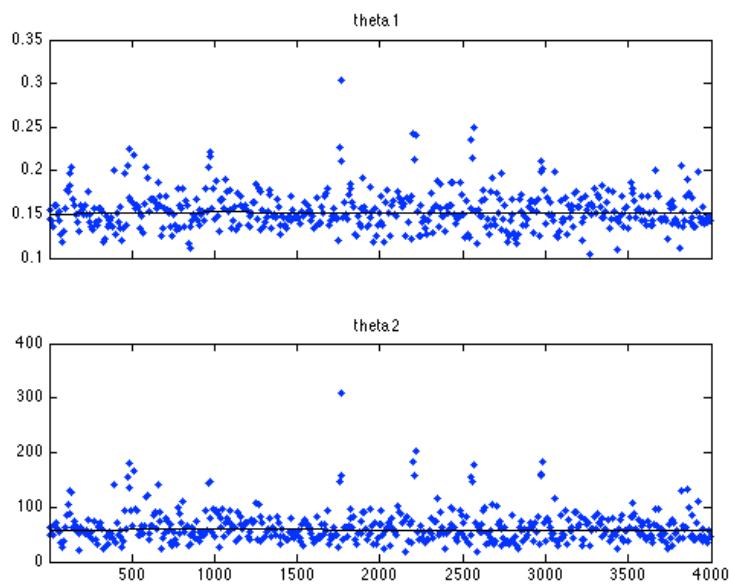
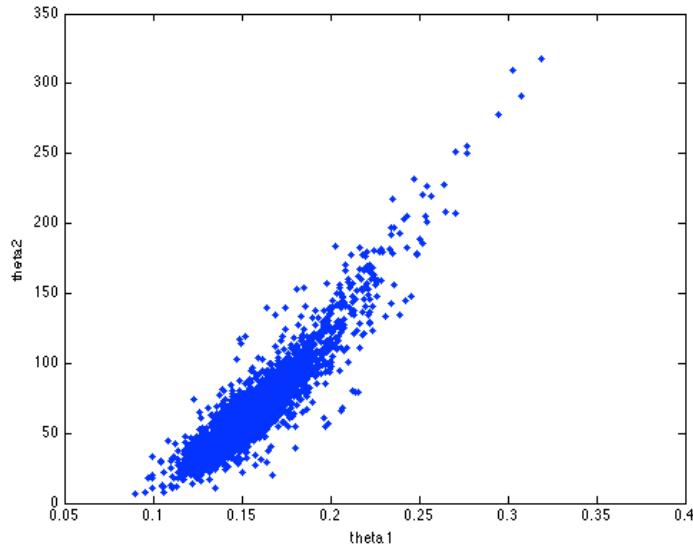
Plot results

```
figure(2); clf
```

```
mcmcplot(chain,[],res,'chainpanel');
```

```
figure(3); clf
```

```
mcmcplot(chain,[],res,'pairs');
```



Examples:

- Several available in MCMC_EXAMPLES
- ODE solver illustrated in algae example

Delayed Rejection Adaptive Metropolis (DRAM)

Construct credible and prediction intervals

```
figure(5); clf  
out = mcmcplot(res,chain,[],x,modelfun);  
mcmcplot(out);  
hold on  
plot(data.xdata,data.ydata,'s'); % add data points to the plot  
xlabel('x [mg/L COD]');  
ylabel('y [1/h]');  
hold off  
title('Predictive envelopes of the model')
```

