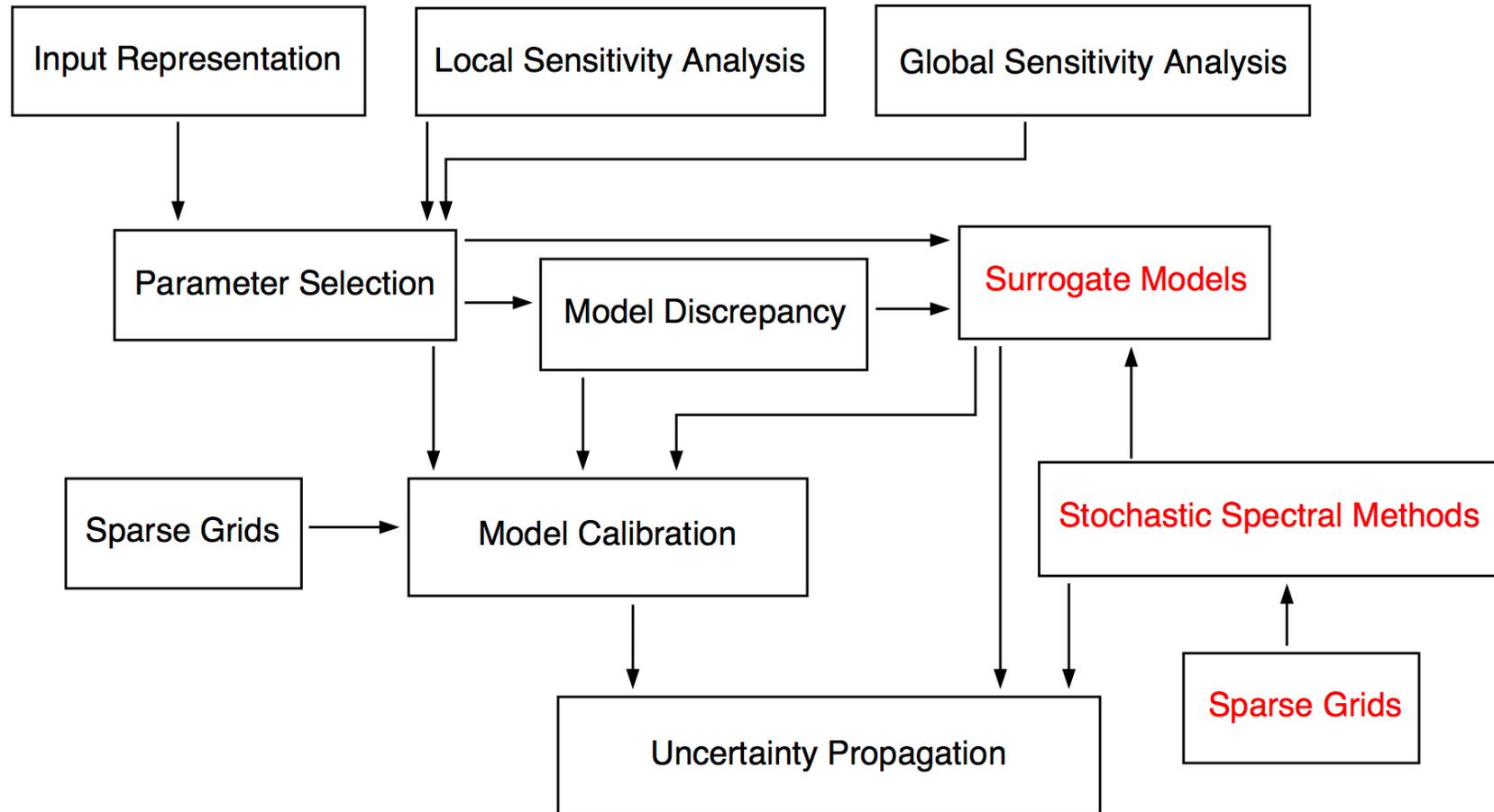


# Steps in Uncertainty Quantification



## Challenge:

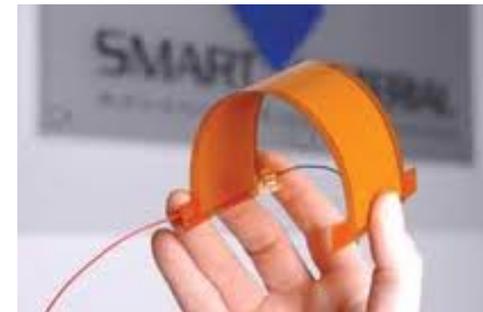
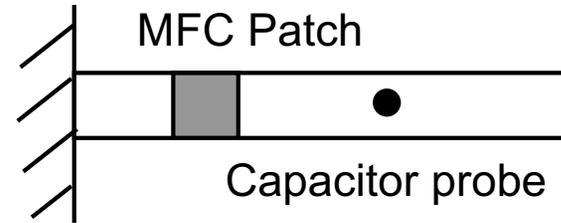
- How do we do uncertainty quantification for computationally expensive models?
- Example:
  - We have a computational budget of **5000** model evaluations.
  - Bayesian inference and uncertainty propagation require **120,000** evaluations.

# Uncertainty Quantification Challenges

**Example:** MFC model – **Fourth-order PDE**

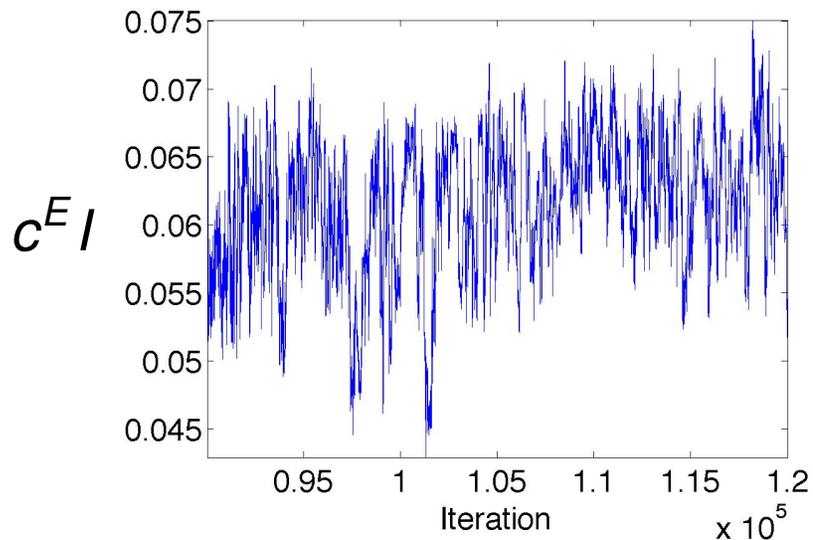
$$\rho \frac{\partial^2 w}{\partial t^2} - \frac{\partial^2 M}{\partial x^2} = f$$

$$M = -\underline{c^E I} \frac{\partial^2 w}{\partial x^2} - c_D I \frac{\partial^3 w}{\partial x^2 \partial t} - [k_1 e(E, \sigma_0) E + k_2 \varepsilon_{irr}(E, \sigma_0)] \chi_{MFC}(x)$$



Macro-Fiber Composite

**Bayesian Inference:** **Took 6 days!**



**Problem:**

$1.2 \times 10^5$  PDE solutions

**Solution:** Highly efficient surrogate models

# Surrogate Models: Motivation

**Example:** Consider the heat equation

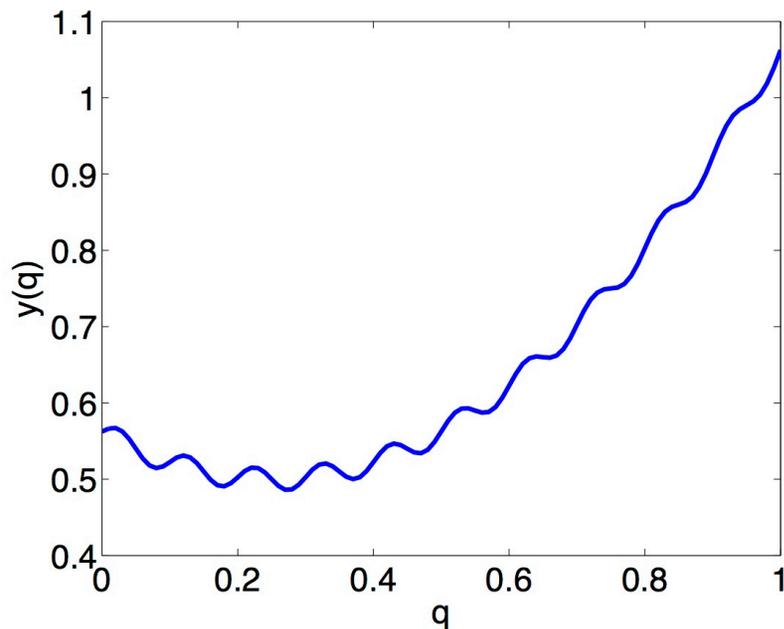
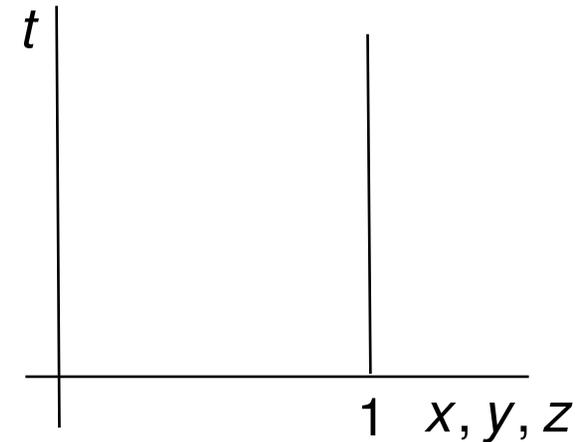
$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} + f(q)$$

Boundary Conditions

Initial Conditions

with the response

$$y(q) = \int_0^1 \int_0^1 \int_0^1 \int_0^1 u(t, x, y, z) dx dy dz dt$$



## Notes:

- Requires approximation of PDE in 3-D
- What would be a **simple surrogate**?

# Surrogate Models: Motivation

**Example:** Consider the heat equation

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} + f(q)$$

Boundary Conditions

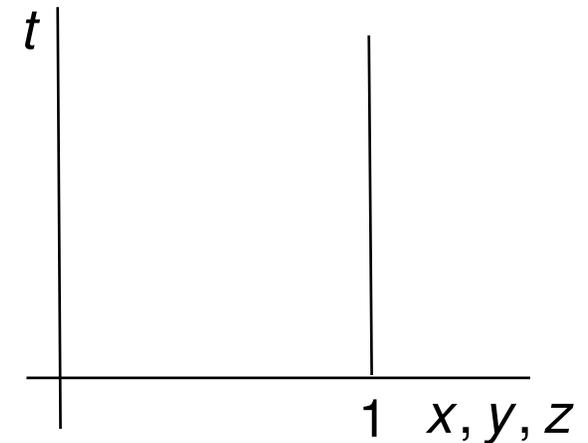
Initial Conditions

with the response

$$y(q) = \int_0^1 \int_0^1 \int_0^1 \int_0^1 u(t, x, y, z) dx dy dz dt$$

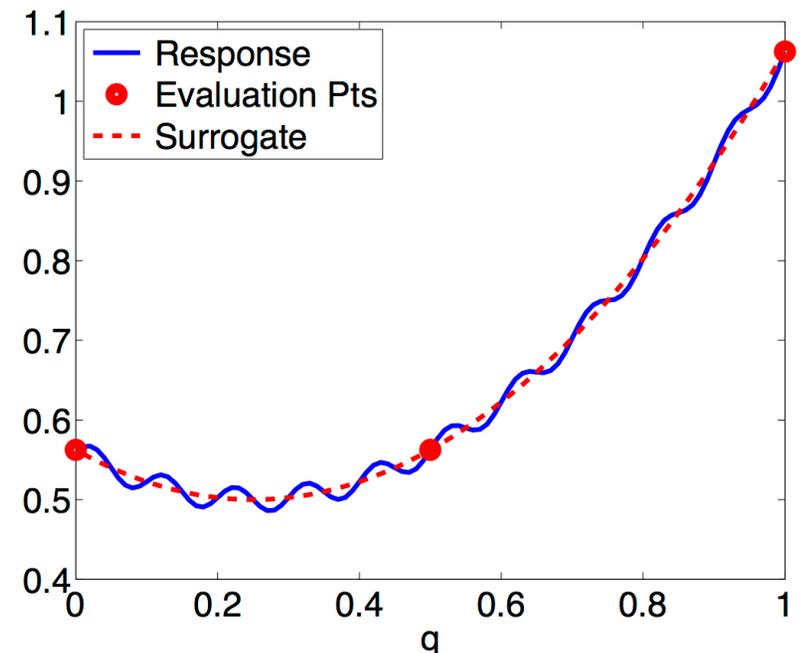
**Question:** How do you construct a polynomial surrogate?

- Regression
- **Interpolation**



**Surrogate:** Quadratic

$$y_s(q) = (q - 0.25)^2 + 0.5$$



# Surrogate Models

**Recall:** Consider the model

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} + f(q)$$

Boundary Conditions

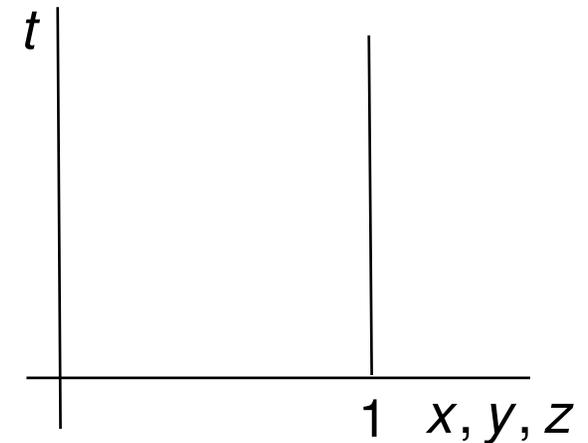
Initial Conditions

with the response

$$y(q) = \int_0^1 \int_0^1 \int_0^1 \int_0^1 u(t, x, y, z) dx dy dz dt$$

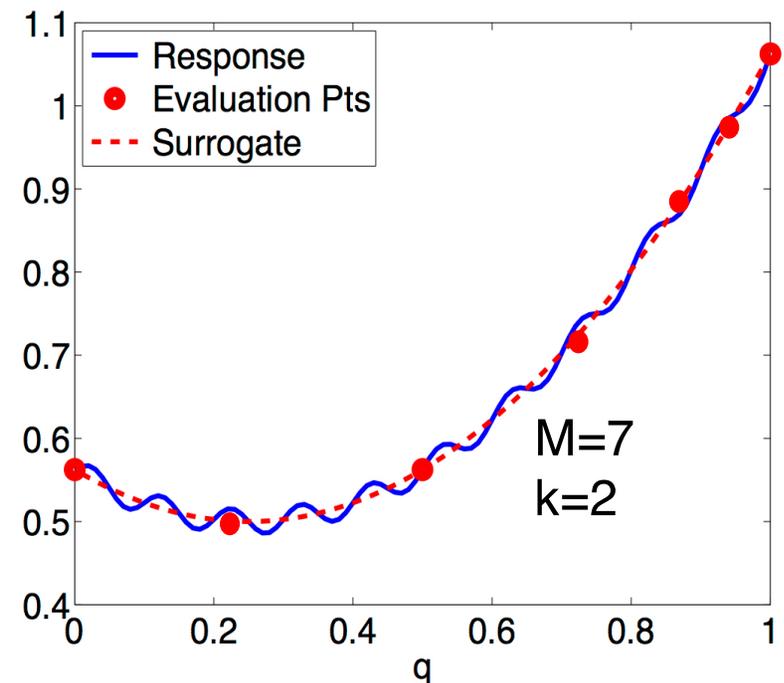
**Question:** How do you construct a polynomial surrogate?

- Interpolation
- Regression



**Surrogate:** Quadratic

$$y_s(q) = (q - 0.25)^2 + 0.5$$



# Surrogate Models

**Question:** How do we keep from fitting noise?

- Akaike Information Criterion (AIC)

$$AIC = 2k - 2 \log[\pi(y|q)]$$

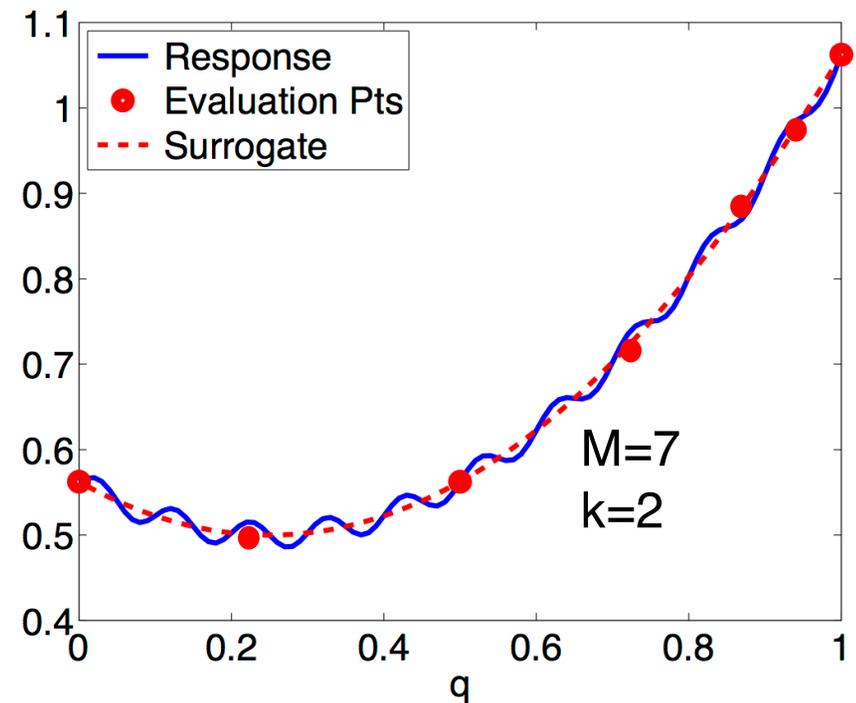
- Bayesian Information Criterion (AIC)

$$BIC = k \log(M) - 2 \log[\pi(y|q)]$$

Likelihood:

$$\pi(y|q) = \frac{1}{(2\pi\sigma^2)^{M/2}} e^{-SS_q/2\sigma^2} \quad \text{Maximize}$$

$$SS_q = \sum_{m=1}^M [y_m - y_s(q^m)]^2 \quad \text{Minimize}$$



# Surrogate Models

**Question:** How do we keep from fitting noise?

- Akaike Information Criterion (AIC)

$$AIC = 2k - 2 \log[\pi(y|q)]$$

- Bayesian Information Criterion (AIC)

$$BIC = k \log(M) - 2 \log[\pi(y|q)]$$

Likelihood:

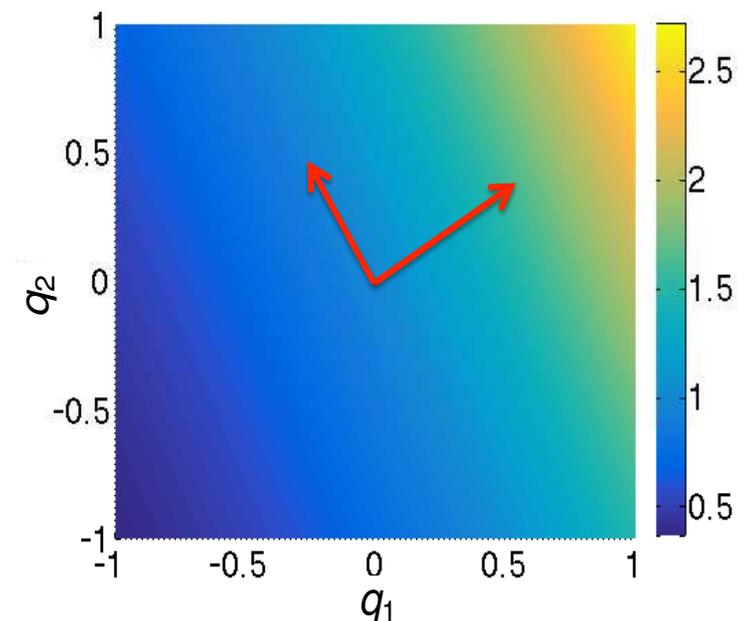
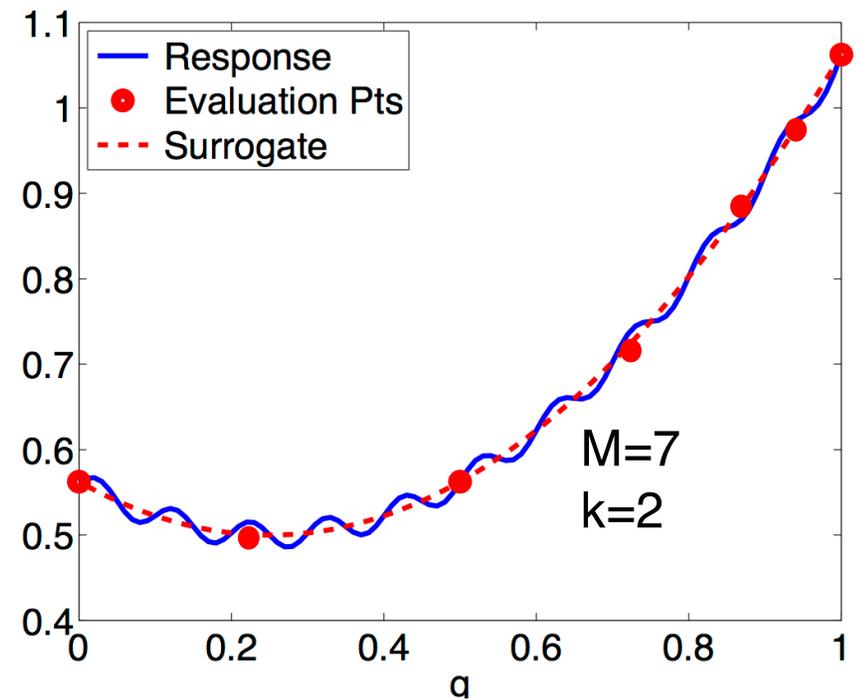
$$\pi(y|q) = \frac{1}{(2\pi\sigma^2)^{M/2}} e^{-SS_q/2\sigma^2} \quad \text{Maximize}$$

$$SS_q = \sum_{m=1}^M [y_m - y_s(q^m)]^2 \quad \text{Minimize}$$

**Example:**  $y = \exp(0.7q_1 + 0.3q_2)$

**Exercise:**

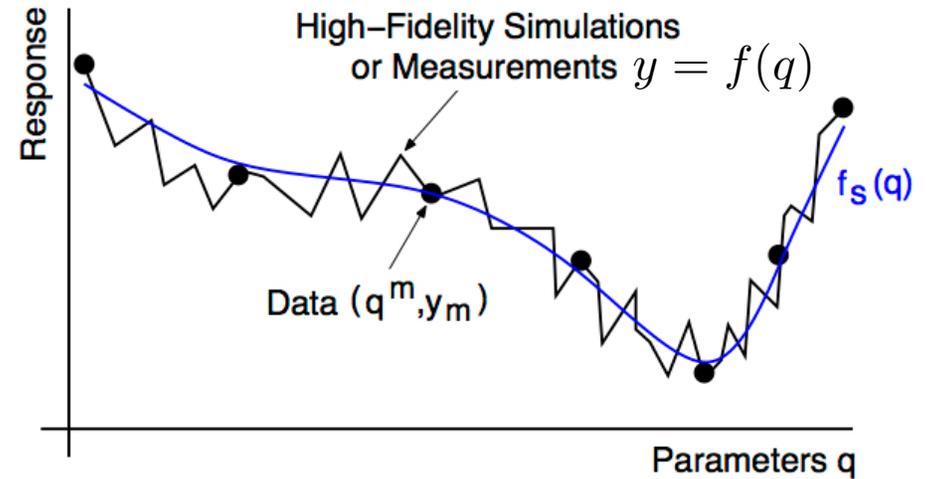
- Construct a polynomial surrogate using the code `response_surface.m`.
- What order seems appropriate?



# Data-Fit Models

## Notes:

- Often termed response surface models, emulators, meta-models.
- Constructed via interpolation or regression.
- Data can consist of high-fidelity simulations or experiments.



**Example:** Steady-state Euler-Bernoulli beam model with PZT patch

$$\underline{YI} \frac{d^4 w}{dx^4}(x) = k_p V \chi_{pzt}(x)$$

Data: Displacement observations

Parameter:  $YI$



# Data-Fit Models

**Example:** Steady-state Euler-Bernoulli beam model with PZT patch

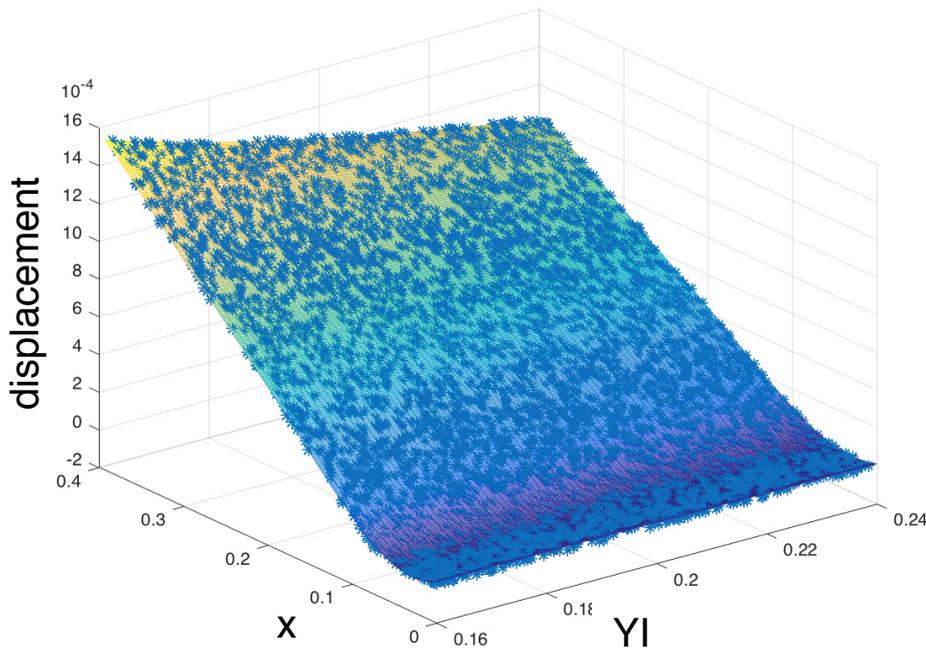
$$YI \frac{d^4 w}{dx^4}(x) = k_p V \chi_{pzt}(x)$$

Data: Displacement observations

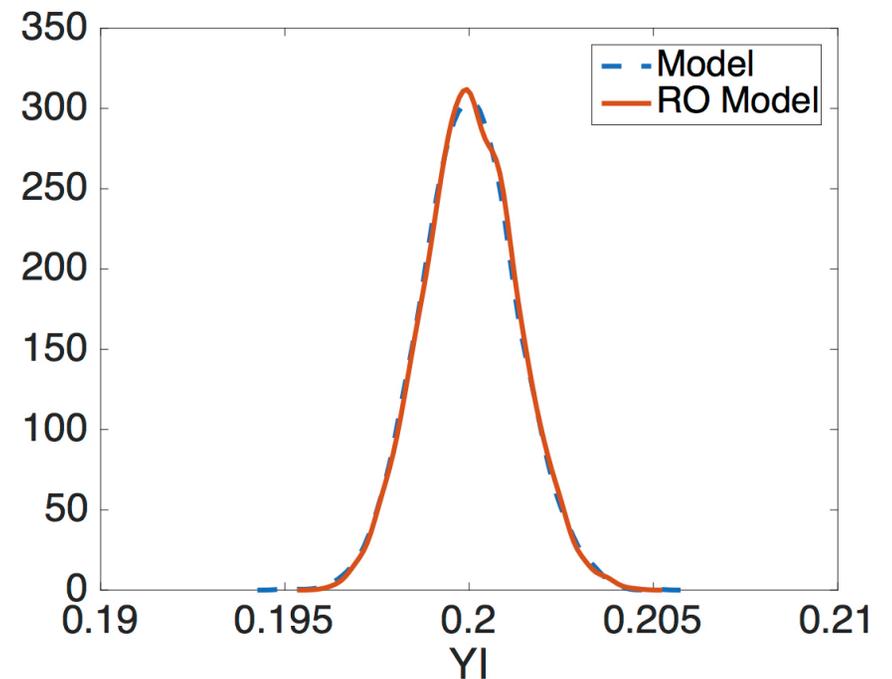
Parameter:  $YI$

Training points: 5000

Polynomial surrogate: 6<sup>th</sup> order



## Bayesian Inference



# Data-Fit Models

## Notes:

- Often termed response surface models, surrogates, emulators, meta-models.
- Rely on interpolation or regression.
- Data can consist of high-fidelity simulations or experiments.
- Common techniques: polynomial models, **kriging (Gaussian process regression)**, **orthogonal polynomials**.

**Strategy:** Consider high fidelity model

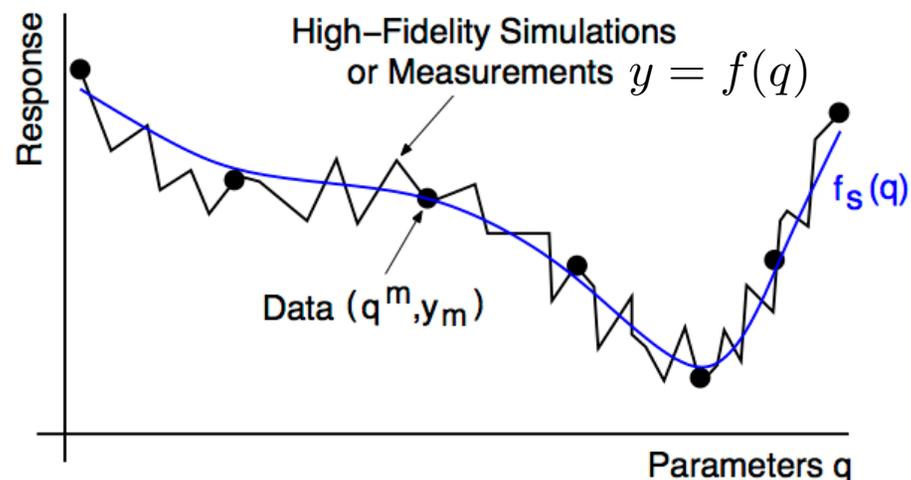
$$y = f(q)$$

with  $M$  model evaluations

$$y_m = f(q^m), \quad m = 1, \dots, M$$

**Statistical Model:**  $f_s(q)$ : Surrogate for  $f(q)$

$$y_m = f_s(q^m) + \varepsilon_m, \quad m = 1, \dots, M$$



**Surrogate:**

$$y^k(Q) = f_s(Q) = \sum_{k=0}^K \alpha_k \Psi_k(Q)$$

**Note:**  $\Psi_k(Q)$  orthogonal with respect to inner product associated with pdf

e.g.,  $Q \sim N(0, 1)$ : Hermite polynomials

$Q \sim U(-1, 1)$ : Legendre polynomials

# Orthogonal Polynomial Representations

## Representation:

$$y^K(Q) = \sum_{k=0}^K \alpha_k \Psi_k(Q)$$

**Note:**  $\Psi_0(Q) = 1$  implies that

$$\mathbb{E}[\Psi_0(Q)] = 1$$

$$\begin{aligned} \mathbb{E}[\Psi_i(Q)\Psi_j(Q)] &= \int_{\Gamma} \Psi_i(q)\Psi_j(q)\rho(q)dq \\ &= \delta_{ij}\gamma_i \end{aligned}$$

where  $\gamma_i = \mathbb{E}[\Psi_i^2(Q)]$

## Properties:

$$(i) \quad \mathbb{E}[y^K(Q)] = \alpha_0$$

$$(ii) \quad \text{var}[y^K(Q)] = \sum_{k=1}^K \alpha_k^2 \gamma_k$$

**Note: Can be used for:**

- Uncertainty propagation
- Sobol-based global sensitivity analysis

**Issue:** How does one compute  $\alpha_k$ ,  $k = 0, \dots, K$ ?

- Stochastic Galerkin techniques (Polynomial Chaos Expansion – PCE)
- Nonintrusive PCE (Discrete projection)
- Stochastic collocation
- Regression-based methods with sparsity control (Lasso)

**Note:** Methods nonintrusive and treat code as blackbox. 147

# Orthogonal Polynomial Representations: **Add Fourier**

**Nonintrusive PCE:** Take weighted inner product of  $y(q) = \sum_{k=0}^{\infty} \alpha_k \Psi_k(q)$  to obtain

$$\alpha_k = \frac{1}{\gamma_k} \int_{\Gamma} y(q) \Psi_k(q) \rho(q) dq$$

Quadrature:

$$\alpha_k \approx \frac{1}{\gamma_k} \sum_{r=1}^R y(q^r) \Psi_k(q^r) w^r$$

**Note:**

(i) Low-dimensional: Tensor 1-D quadrature rules – e.g., Gaussian

(ii) Moderate-dimensional: Sparse grid (Smolyak) techniques

(iii) High-dimensional: Monte Carlo or quasi-Monte Carlo (QMC) techniques

**Regression-Based Methods with Sparsity Control (Lasso):** Solve

$$\min_{\alpha \in \mathbb{R}^{K+1}} \|\Lambda \alpha - d\|^2 \quad \text{subject to} \quad \sum_{k=0}^K |\alpha_k| \leq \tau$$

**Note:** Sample points  $\{q^m\}_{m=1}^M$

$$\Lambda \in \mathbb{R}^{M \times (K+1)} \quad \text{where} \quad \Lambda_{jk} = \Psi_k(q^j)$$

$$d = [y(q^1), \dots, y(q^m)]$$

e.g., SPGL1

• MATLAB Solver for large-scale sparse reconstruction

# Stochastic Collocation

**Strategy:** Consider high fidelity model

$$y = f(q)$$

with  $M$  model evaluations

$$y_m = f(q^m), \quad m = 1, \dots, M$$

**Collocation Surrogate:**

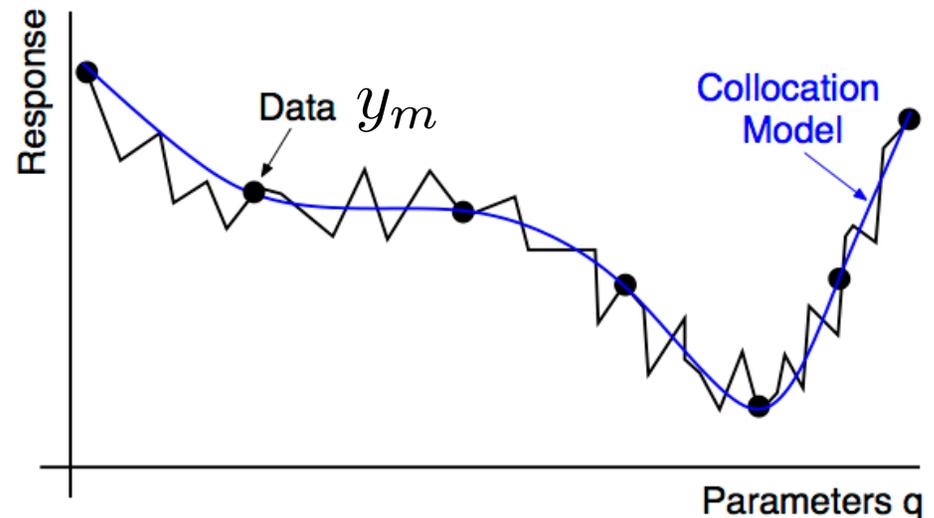
$$Y^M(q) = \sum_{m=1}^M y_m L_m(q)$$

where  $L_m(q)$  is a Lagrange polynomial, which in 1-D, is represented by

$$L_m(q) = \prod_{\substack{j=0 \\ j \neq m}}^M \frac{q - q^j}{q^m - q^j} = \frac{(q - q^1) \dots (q - q^{m-1})(q - q^{m+1}) \dots (q - q^M)}{(q^m - q^1) \dots (q^m - q^{m-1})(q^m - q^{m+1}) \dots (q^m - q^M)}$$

**Note:**

$$L_m(q^j) = \delta_{jm} = \begin{cases} 0 & , \quad j \neq m \\ 1 & , \quad j = m \end{cases}$$



**Result:**  $Y^M(q^m) = y_m$

# Orthogonal Polynomial Methods for PDE

**Evolution Model: e.g.,** thermal-hydraulic equations

$$\frac{\partial u}{\partial t} = \mathcal{N}(u, Q) + F(Q) \quad , \quad x \in \mathcal{D}, \quad t \in [0, \infty)$$

$$B(u, Q) = G(Q) \quad , \quad x \in \partial\mathcal{D}, \quad t \in [0, \infty)$$

$$u(0, x, Q) = I(Q) \quad , \quad x \in \mathcal{D}$$

**Weak Formulation:** For all  $v \in V$

$$\int_{\mathcal{D}} \frac{\partial u}{\partial t} v dx + \int_{\mathcal{D}} \mathcal{N}(u, Q) S(v) dx = \int_{\mathcal{D}} F(Q) v dx$$

**Response:**  $y(t, x) = \int_{\Gamma} u(t, x, q) \rho(q) dq$

**Representation:**

$$\begin{aligned} u^K(t, x, Q) &= \sum_{k=0}^K u_k(t, x) \Psi_k(Q) \\ &= \sum_{k=0}^K \sum_{j=1}^J u_{jk}(t) \phi_j(x) \Psi_k(Q) \end{aligned}$$

 e.g., Finite elements

**Example:**  $q = \alpha$

$$\frac{\partial u}{\partial t} = \alpha \frac{\partial^2 u}{\partial x^2}$$

$$y(t, 0) = u(t, L) = 0$$

$$u(0, x) = u_0(x)$$

For all  $v \in H_0^1(0, L)$

$$\int_0^L \frac{\partial u}{\partial t} v dx + \alpha \int_0^L \frac{\partial u}{\partial x} \frac{dv}{dx} = 0$$

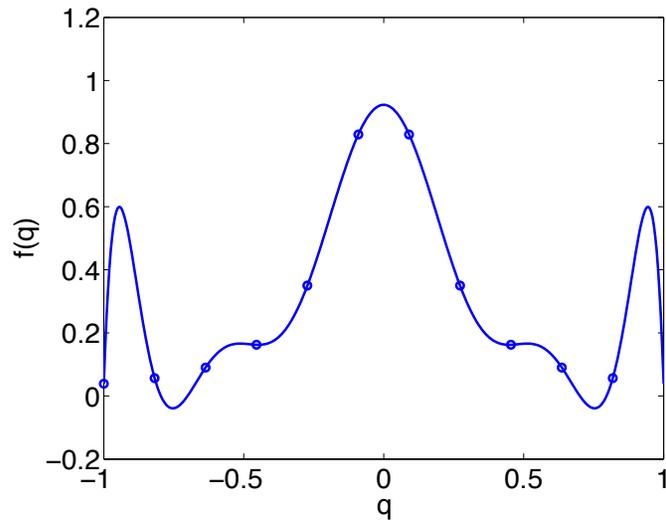
**Discrete Projection:**

$$u_k(t, x) \approx \frac{1}{\gamma_k} \sum_{r=1}^R u(t, x, q^r) \Psi_k(q^r) w^r$$

# Surrogate Models – Grid Choice

**Example:** Consider the Runge function  $f(q) = \frac{1}{1+25q^2}$  with points

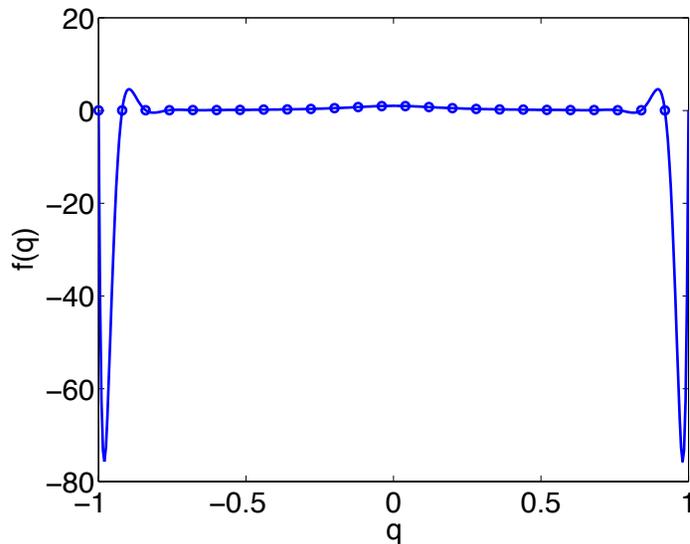
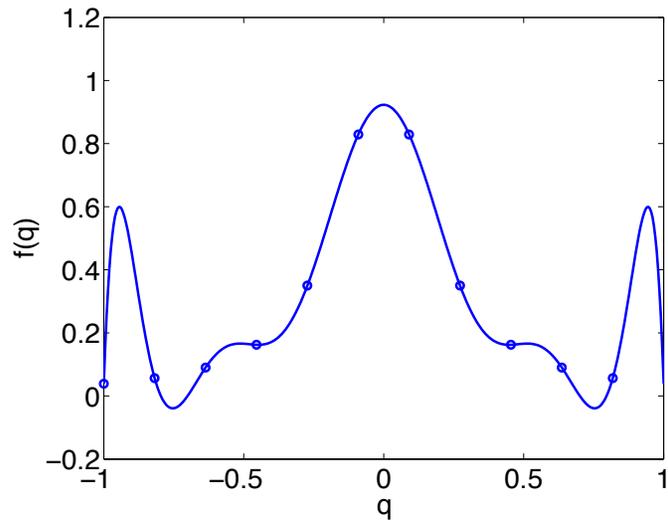
$$q^j = -1 + (j-1) \frac{2}{M}, \quad j = 1, \dots, M$$



# Surrogate Models – Grid Choice

**Example:** Consider the Runge function  $f(q) = \frac{1}{1+25q^2}$  with points

$$q^j = -1 + (j-1) \frac{2}{M}, \quad j = 1, \dots, M$$

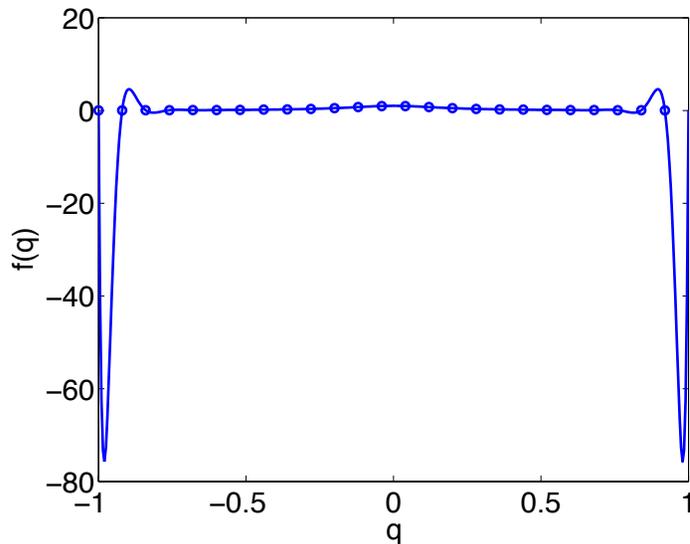
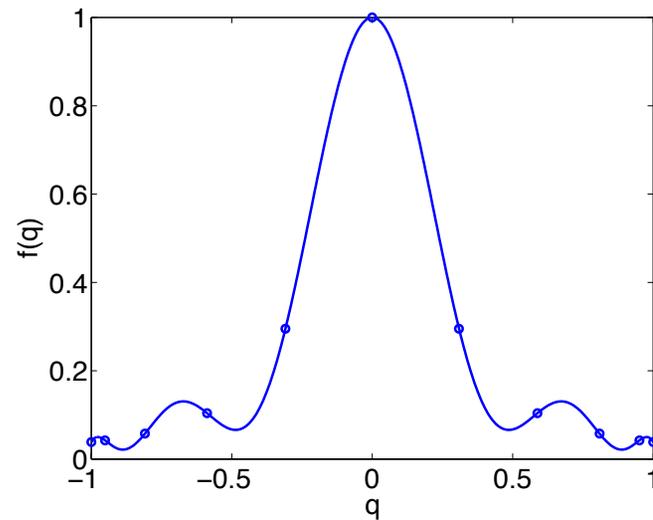
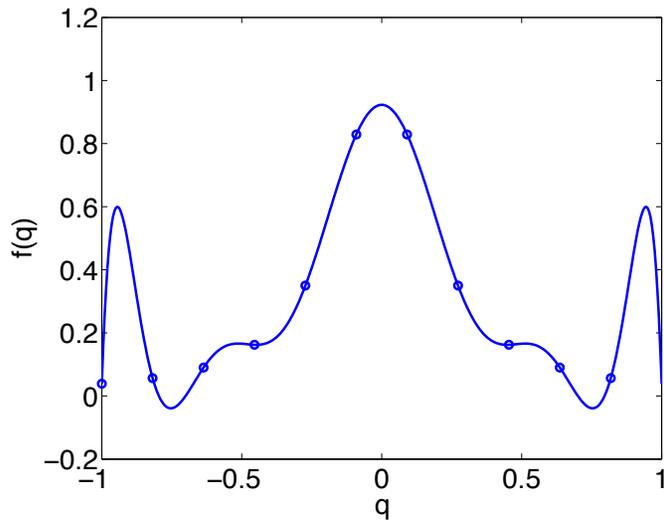


# Surrogate Models – Grid Choice

**Example:** Consider the Runge function  $f(q) = \frac{1}{1+25q^2}$  with points

$$q^j = -1 + (j-1) \frac{2}{M}, \quad j = 1, \dots, M$$

$$q^j = -\cos \frac{\pi(j-1)}{M-1}, \quad j = 1, \dots, M$$

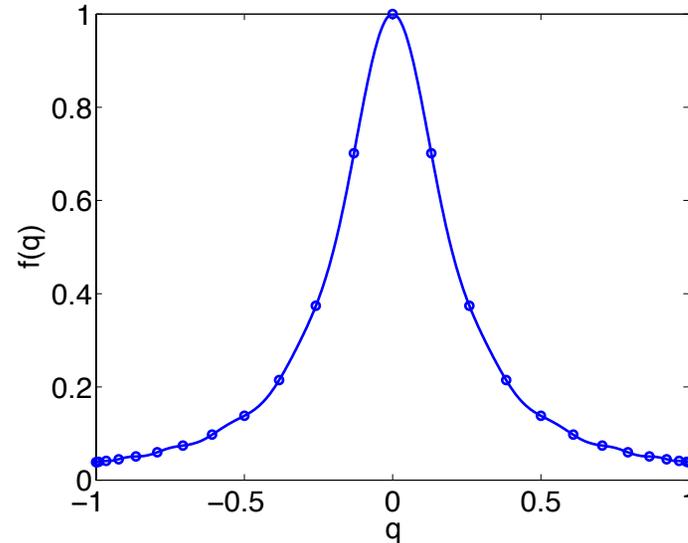
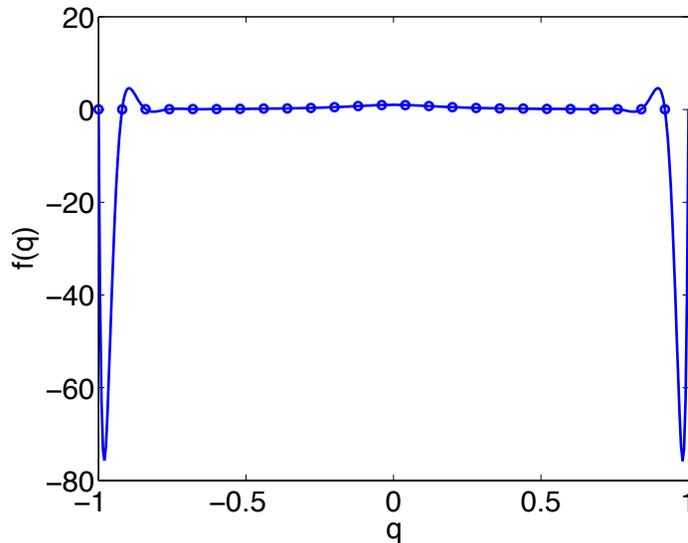
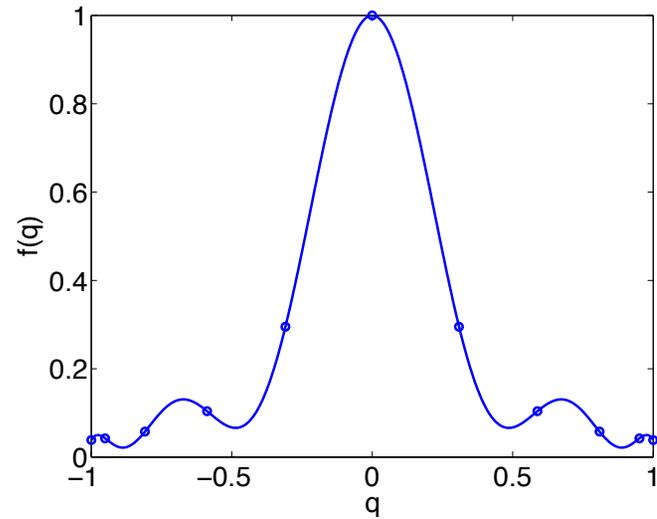
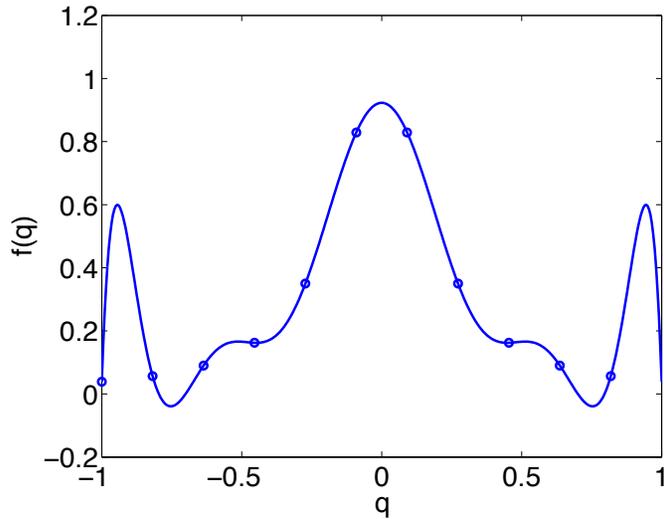


# Surrogate Models – Grid Choice

**Example:** Consider the Runge function  $f(q) = \frac{1}{1+25q^2}$  with points

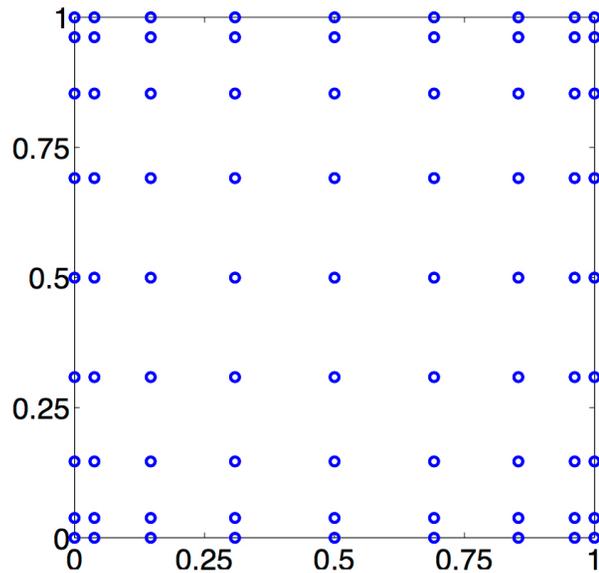
$$q^j = -1 + (j-1) \frac{2}{M}, \quad j = 1, \dots, M$$

$$q^j = -\cos \frac{\pi(j-1)}{M-1}, \quad j = 1, \dots, M$$

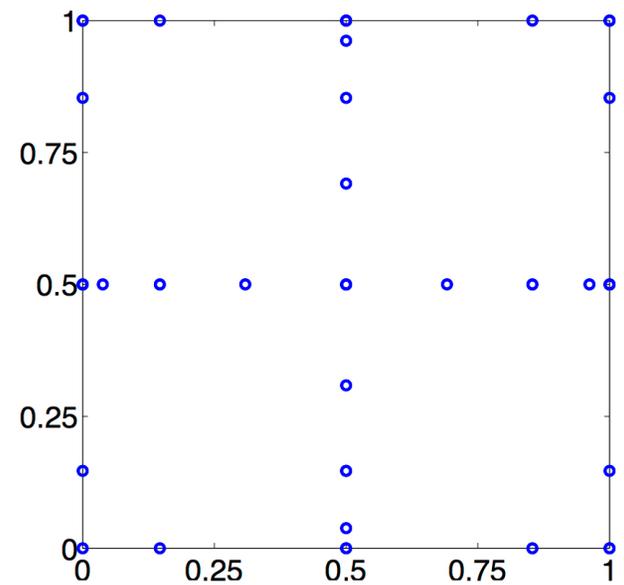


# Sparse Grid Techniques

**Tensor Grids:** Exponential growth



**Sparse Grids:** Same accuracy



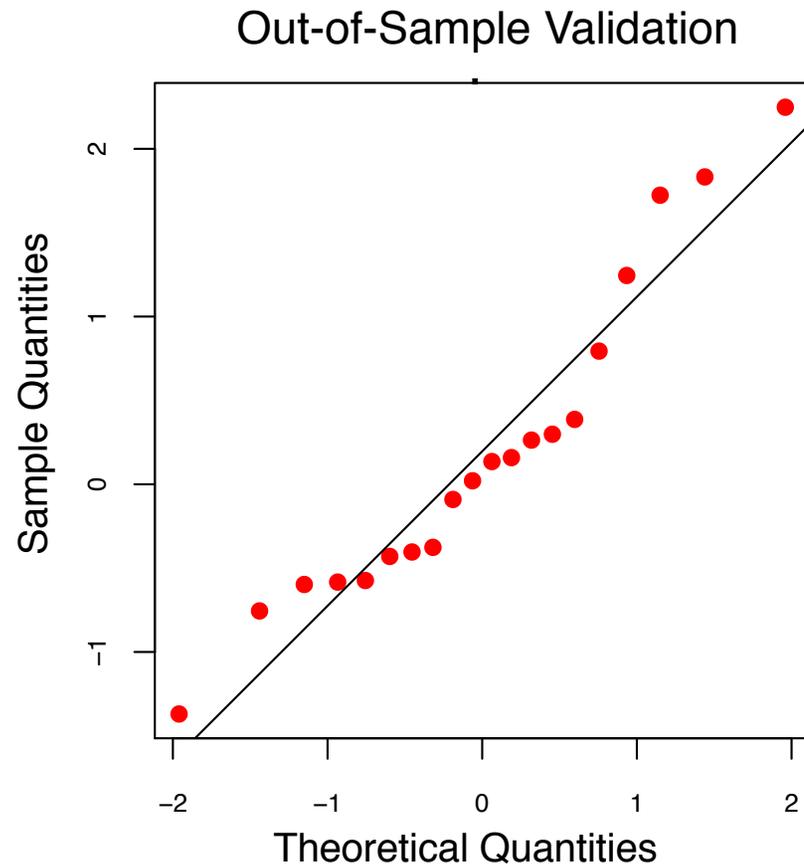
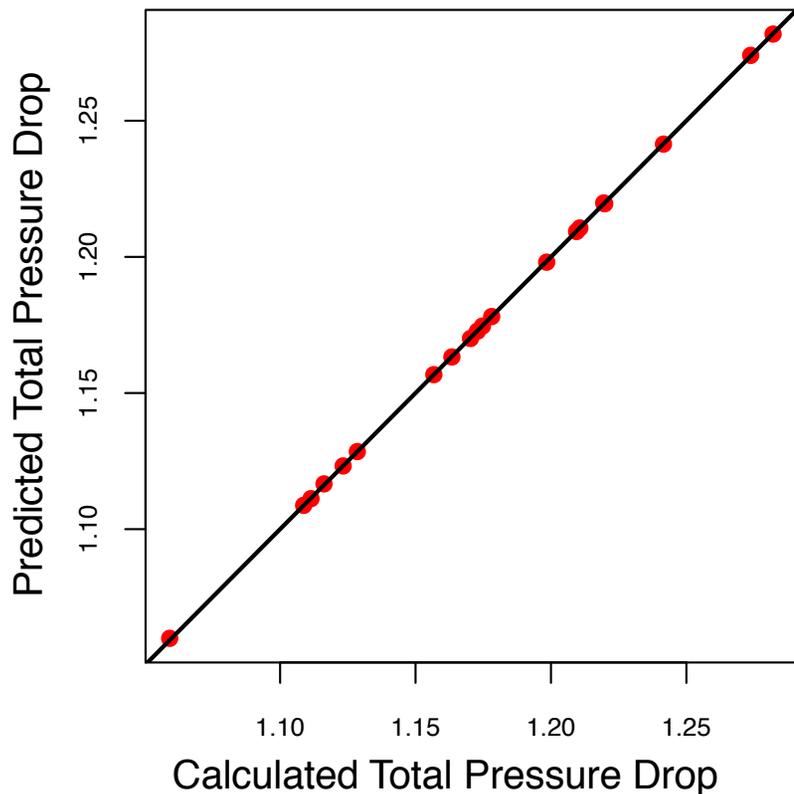
$p$	$R_\ell$	Sparse Grid $\mathcal{R}$	Tensor Grid $R = (R_\ell)^p$
2	9	29	81
5	9	241	59,049
10	9	1581	$> 3 \times 10^9$
50	9	171,901	$> 5 \times 10^{47}$
100	9	1,353,801	$> 2 \times 10^{95}$

# Surrogate Construction: Nuclear Power Plant Design

**Subchannel Code (COBRA-TF):** 33 VUQ parameters reduced to 5 using SA

**Surrogate:** Total pressure drop

- Kriging (GP) emulator constructed using 50 COBRA-TF runs perturbing 5 active inputs.
- Use remaining computational budget to evaluate quality of surrogate using post-processed Dakota outputs.



# Example: SIR Cholera Model

## Model:

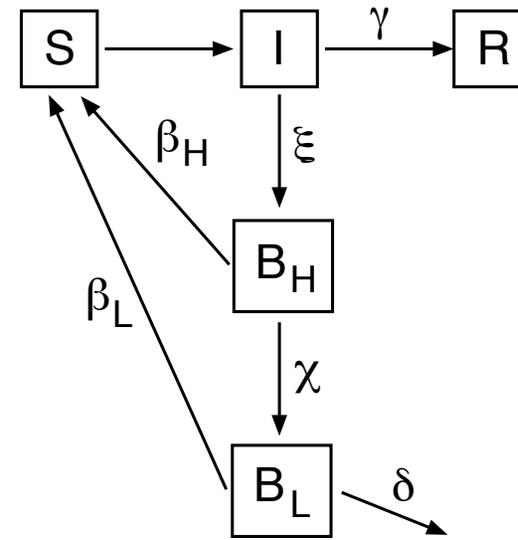
$$\frac{dS}{dt} = bN - \beta_L S \frac{B_L}{\kappa_L + B_L} - \beta_H S \frac{B_H}{\kappa_H + B_H} - bS$$

$$\frac{dI}{dt} = \beta_L S \frac{B_L}{\kappa_L + B_L} + \beta_H S \frac{B_H}{\kappa_H + B_H} - (\gamma + b)I$$

$$\frac{dR}{dt} = \gamma I - bR$$

$$\frac{dB_H}{dt} = \xi I - \chi B_H$$

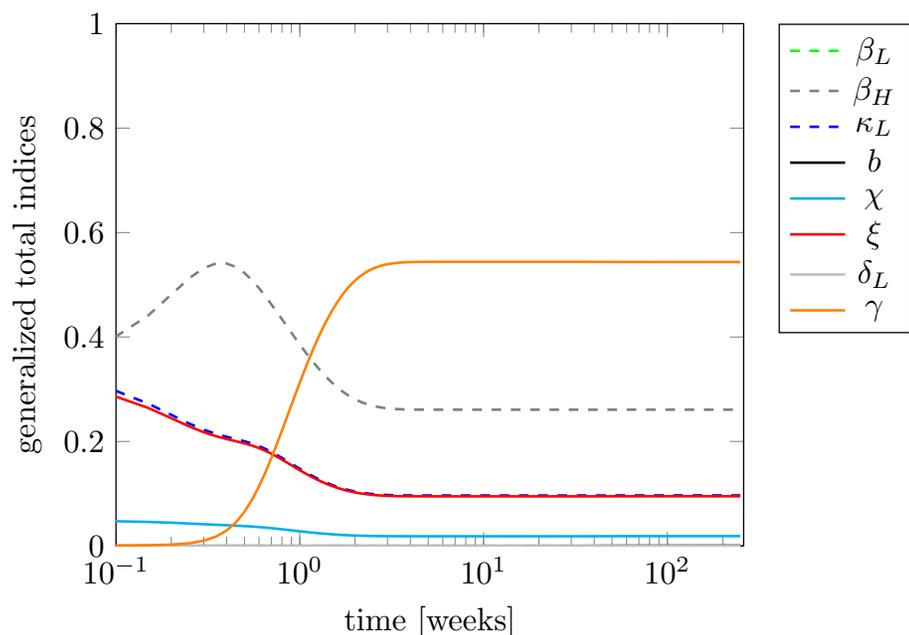
$$\frac{dB_L}{dt} = \chi B_H - \delta B_L$$



Model Parameter	Symbol	Units	Values
Rate of drinking $B_L$ cholera	$\beta_L$	$\frac{1}{\text{week}}$	1.5
Rate of drinking $B_H$ cholera	$\beta_H$	$\frac{1}{\text{week}}$	7.5 (*)
$B_L$ cholera carrying capacity	$\kappa_L$	$\frac{\# \text{ bacteria}}{\text{ml}}$	$10^6$
$B_H$ cholera carrying capacity	$\kappa_H$	$\frac{\# \text{ bacteria}}{\text{ml}}$	$\frac{\kappa_L}{700}$
Human birth and death rate	$b$	$\frac{1}{\text{week}}$	$\frac{1560}{1}$
Rate of decay from $B_H$ to $B_L$	$\chi$	$\frac{1}{\text{week}}$	$\frac{168}{5}$
Rate at which infectious individuals spread $B_H$ bacteria to water	$\xi$	$\frac{\# \text{ bacteria}}{\# \text{ individuals} \cdot \text{ml} \cdot \text{week}}$	70
Death rate of $B_L$ cholera	$\delta$	$\frac{1}{\text{week}}$	$\frac{7}{30}$
Rate of recovery from cholera	$\gamma$	$\frac{1}{\text{week}}$	$\frac{7}{5}$

# Example: SIR Cholera Model

**Strategy:** Employed collocation and discrete projection with sparse grids to compute time-dependent global sensitivity indices.



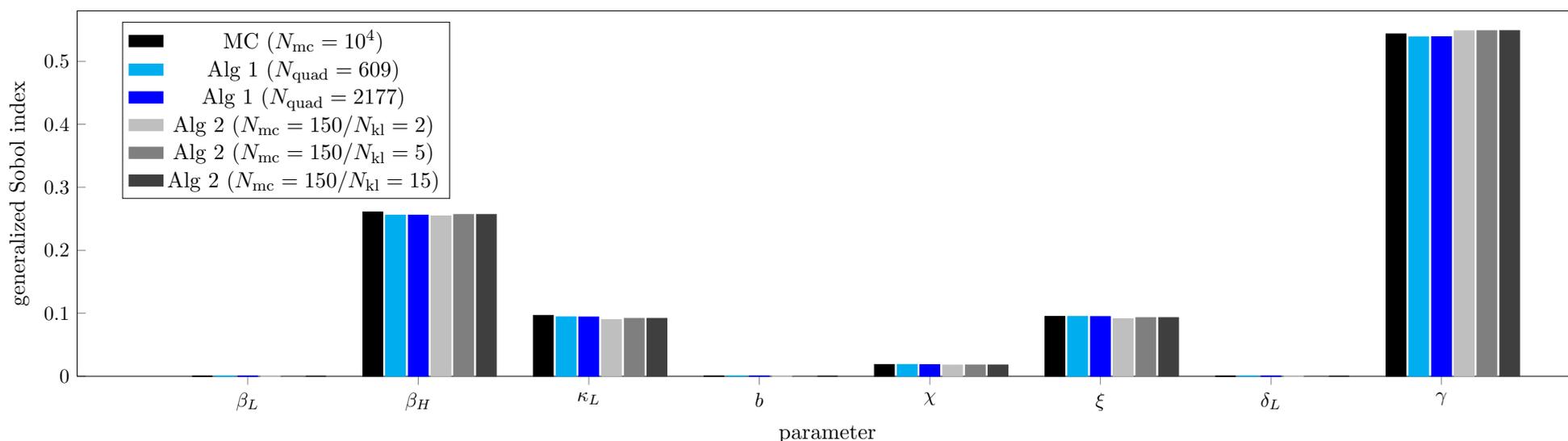
## Conclusion: Sensitive indices

$\gamma$ : Recovery rate

$\beta_H$ : Rate of drinking  $B_H$  cholera

$\kappa_L$ :  $B_L$  carrying capacity; Note  $\kappa_H = \kappa_L/700$

$\xi$ : Rate at which  $B_H$  bacteria spread



# Example: SIR Cholera Model

## Model:

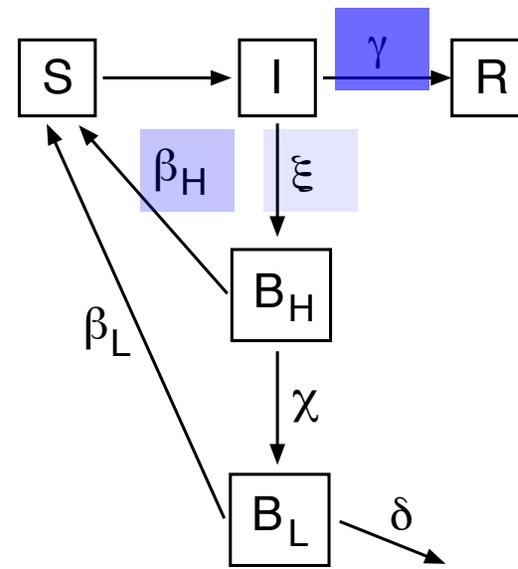
$$\frac{dS}{dt} = bN - \beta_L S \frac{B_L}{\kappa_L + B_L} - \beta_H S \frac{B_H}{\kappa_H + B_H} - bS$$

$$\frac{dI}{dt} = \beta_L S \frac{B_L}{\kappa_L + B_L} + \beta_H S \frac{B_H}{\kappa_H + B_H} - (\gamma + b)I$$

$$\frac{dR}{dt} = \gamma I - bR$$

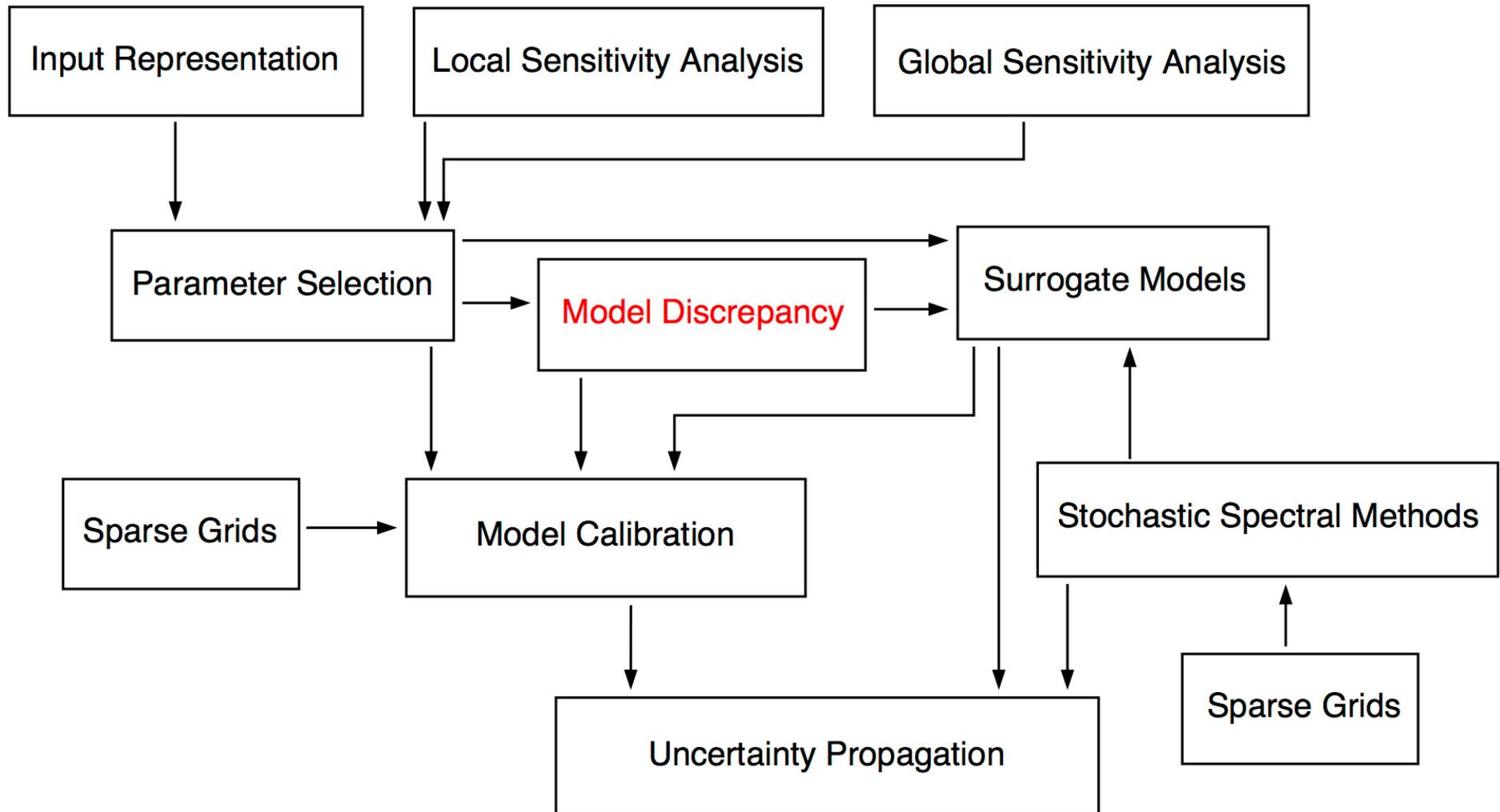
$$\frac{dB_H}{dt} = \xi I - \chi B_H$$

$$\frac{dB_L}{dt} = \chi B_H - \delta B_L$$



Model Parameter	Symbol	Units	Values
Rate of drinking $B_L$ cholera	$\beta_L$	$\frac{1}{\text{week}}$	1.5
Rate of drinking $B_H$ cholera	$\beta_H$	$\frac{1}{\text{week}}$	7.5 (*)
$B_L$ cholera carrying capacity	$\kappa_L$	$\frac{\# \text{ bacteria}}{\text{ml}}$	$10^6$
$B_H$ cholera carrying capacity	$\kappa_H$	$\frac{\# \text{ bacteria}}{\text{ml}}$	$\frac{\kappa_L}{700}$
Human birth and death rate	$b$	$\frac{1}{\text{week}}$	$\frac{1560}{1}$
Rate of decay from $B_H$ to $B_L$	$\chi$	$\frac{1}{\text{week}}$	$\frac{168}{5}$
Rate at which infectious individuals spread $B_H$ bacteria to water	$\xi$	$\frac{\# \text{ bacteria}}{\# \text{ individuals} \cdot \text{ml} \cdot \text{week}}$	70
Death rate of $B_L$ cholera	$\delta$	$\frac{1}{\text{week}}$	$\frac{7}{30}$
Rate of recovery from cholera	$\gamma$	$\frac{1}{\text{week}}$	$\frac{7}{5}$

# Steps in Uncertainty Quantification



## 6. Quantification of Model Discrepancy – Thin Beam

“Essentially all models are wrong, but some are useful” George E.P. Box

**Example:** Thin beam driven by PZT patches



**Euler-Bernoulli Model:** For all  $\phi \in V$

$$\int_0^L \left[ \rho(x) \frac{\partial^2 w}{\partial t^2} + \gamma \frac{\partial w}{\partial t} \right] \phi dx + \int_0^L \left[ YI(x) \frac{\partial^2 w}{\partial x^2} + cl(x) \frac{\partial^3 w}{\partial x^2 \partial t} \right] \phi'' dx$$

$$= k_p V(t) \int_{x_1}^{x_2} \phi'' dx$$

with

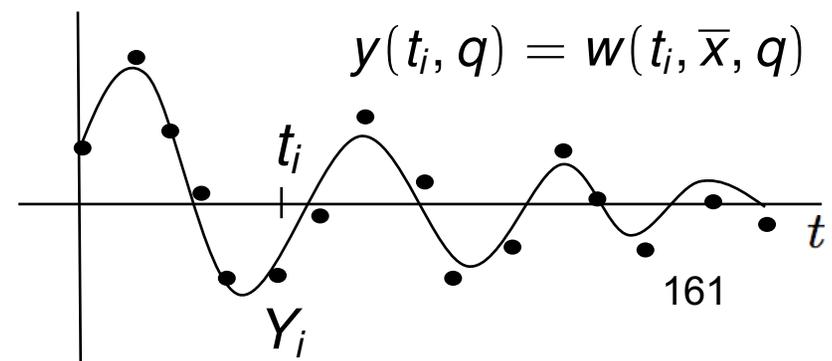
$$\rho(x) = \rho h b + \rho_p h_p b_p \chi_p(x), \quad YI(x) = YI + Y_p I_p \chi_p(x)$$

$$cl(x) = cl + c_p I_p \chi_p(x)$$

**Note:** 7 parameters, 32 states

**Statistical Model:**

$$Y_i = y(t_i, q) + \varepsilon_i$$

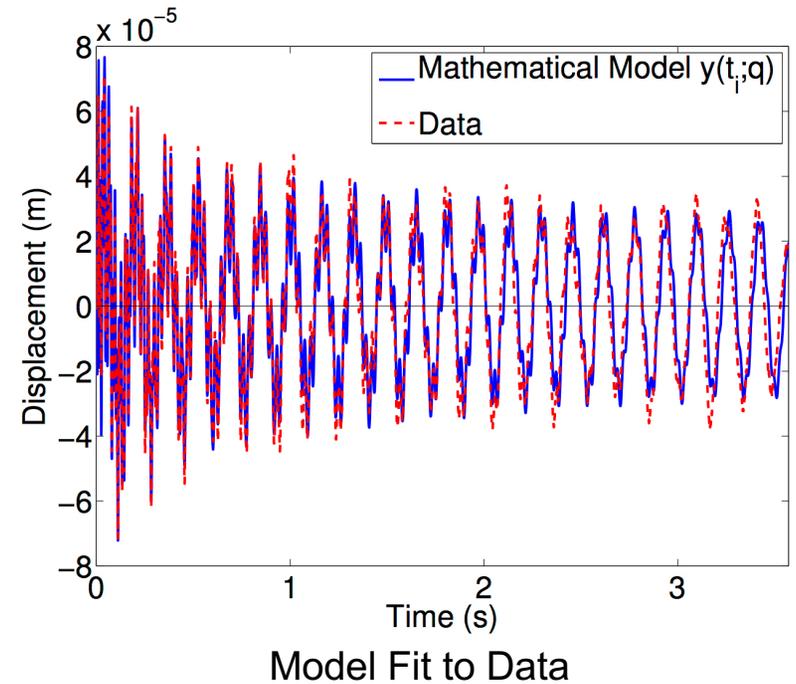
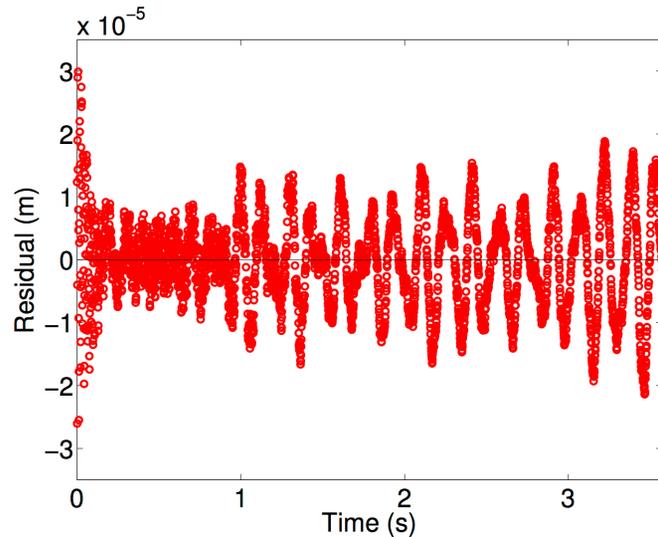


# Quantification of Model Discrepancy – Thin Beam

**Example:** Good model fit

$$Y_i = y(t_i, q) + \varepsilon_i$$

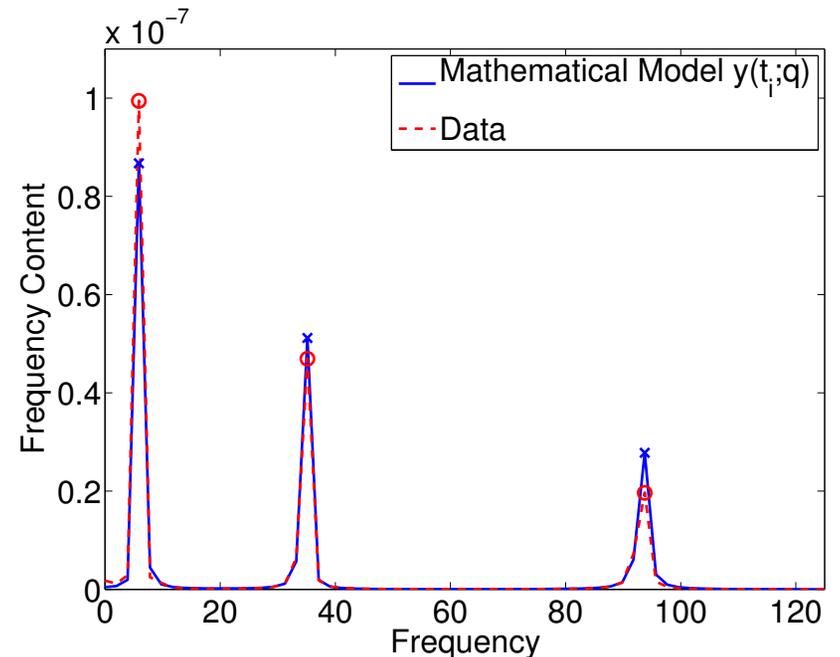
**Note:** Observation errors not iid



**Reference:** Additive observation errors

$$Y_i = y(t_i, q) + \delta(t_i, \tilde{q}) + \varepsilon_i$$

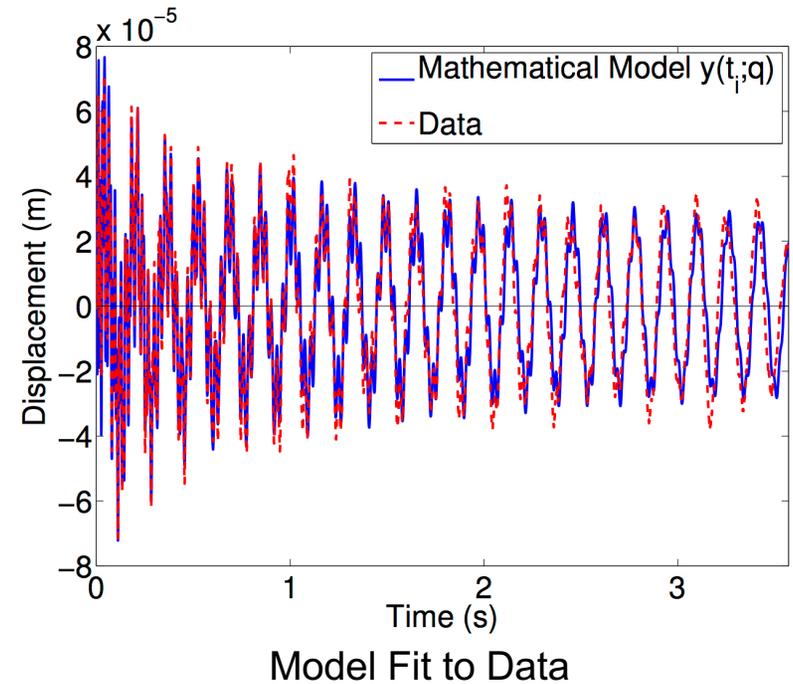
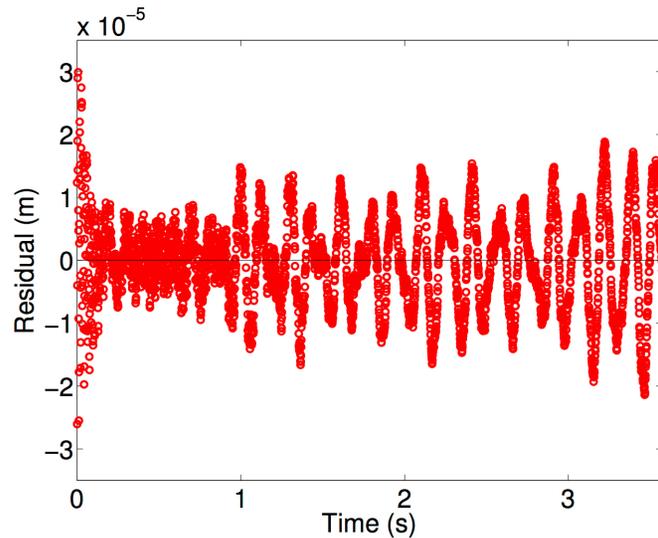
- M.C. Kennedy and A. O'Hagan, *Journal of the Royal Statistical Society, Series B*, 2001.



# Quantification of Model Discrepancy – Thin Beam

**Example:** Good model fit

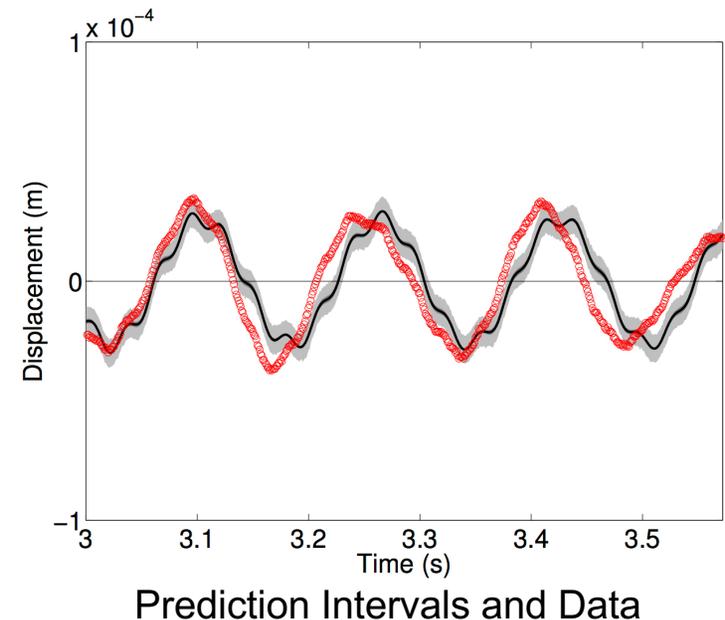
**Problem:** Observation errors not iid



**Result:** Prediction intervals wrong

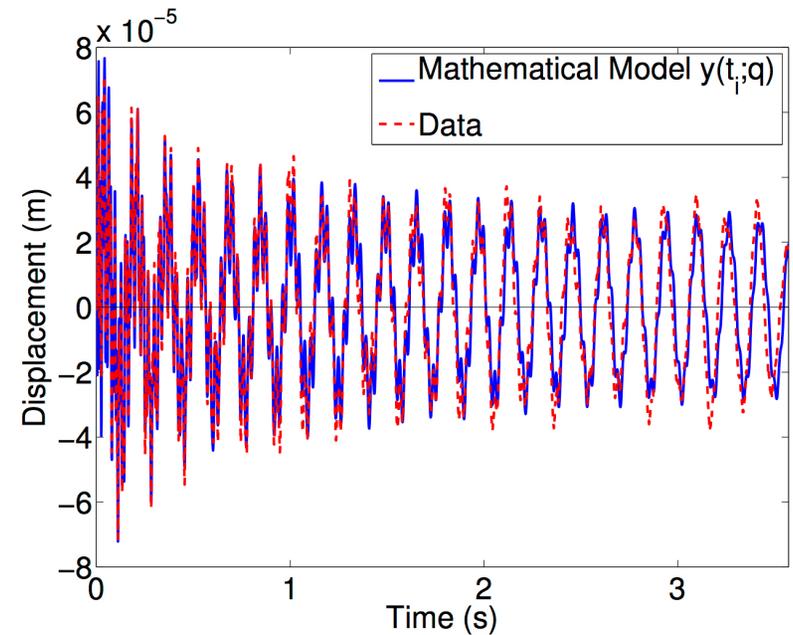
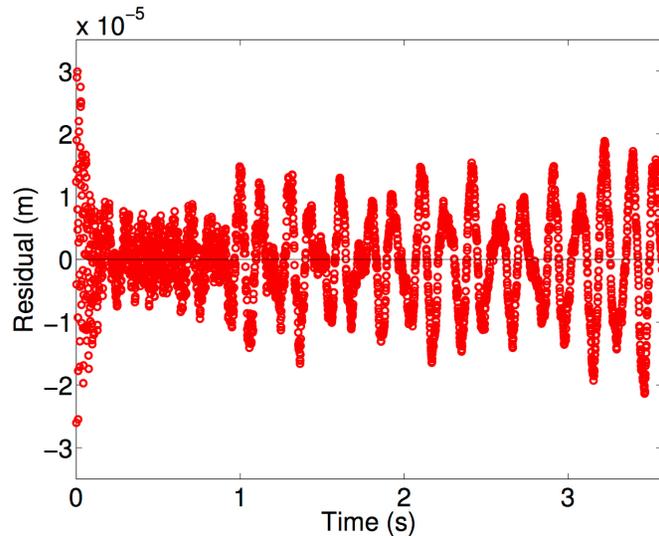
**Approaches:**

- GP Model: Inaccurate for extrapolation
- Control-based approaches: difficult to extrapolate.
- Problem: correct physics or biology required for extrapolation!



# Quantification of Model Discrepancy – Thin Beam

**Problem:** Measurement errors not iid



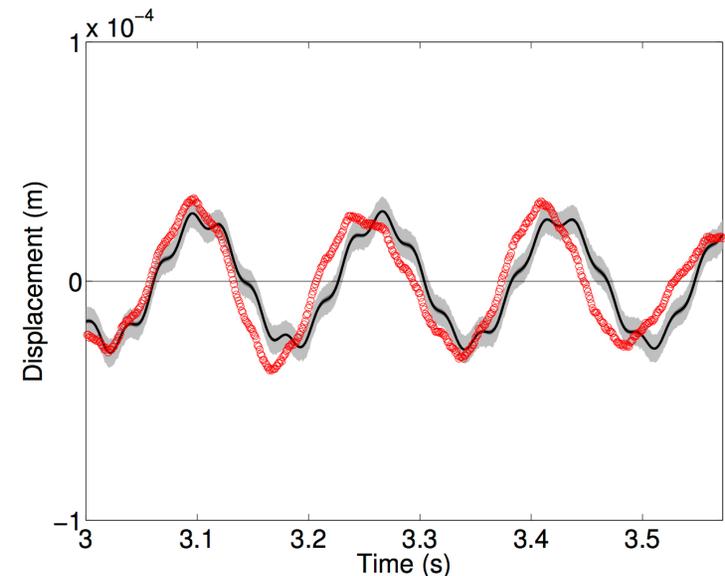
Model Fit to Data

**Result:** Prediction intervals wrong

**One Approach:**

- Determine components of model you trust (e.g., conservation laws) and don't trust (e.g., closure relations). Embed uncertainty into latter.
- T. Oliver, G. Terejanu, C.S. Simmons, R.D. Moser, *Comput Meth Appl Mech Eng*, 2015.

**2018-19 SAMSI Program: Model Uncertainty: Mathematical and Statistical (MUMS)**

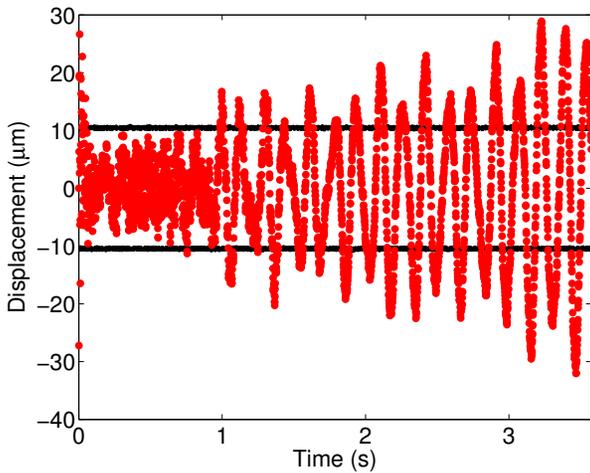


Prediction Intervals and Data

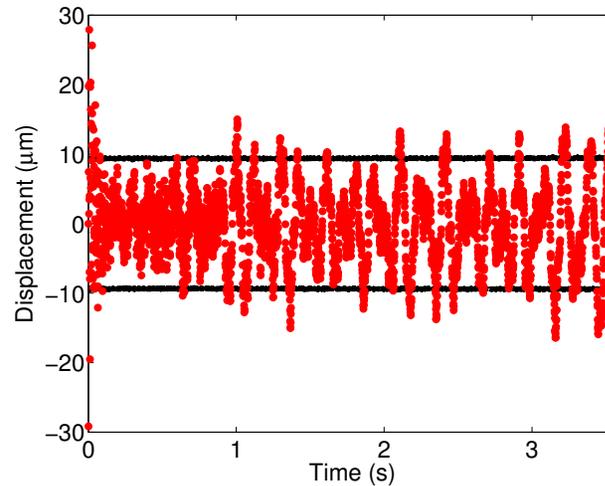
# Quantification of Model Discrepancy – Thin Beam

**Our Solution:** “Optimize” calibration interval

- Use damping/frequency domain results to guide.

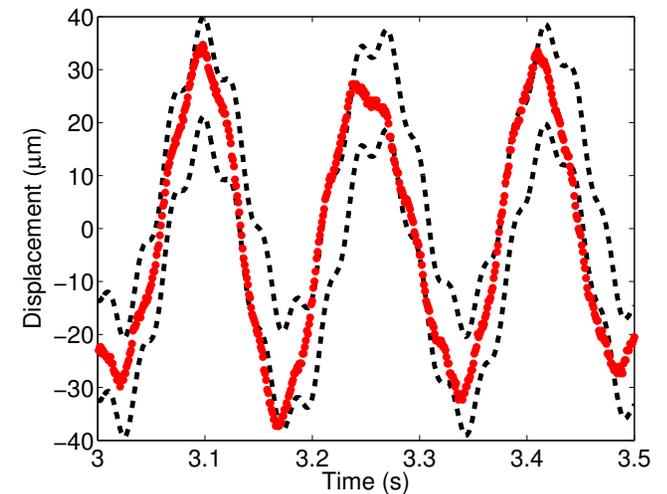
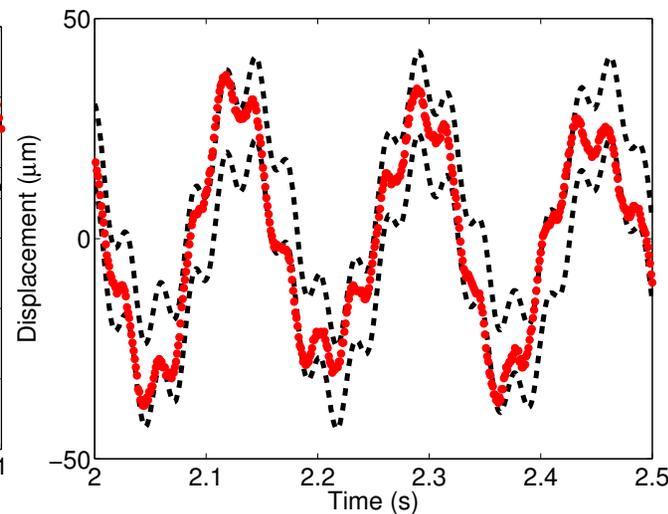
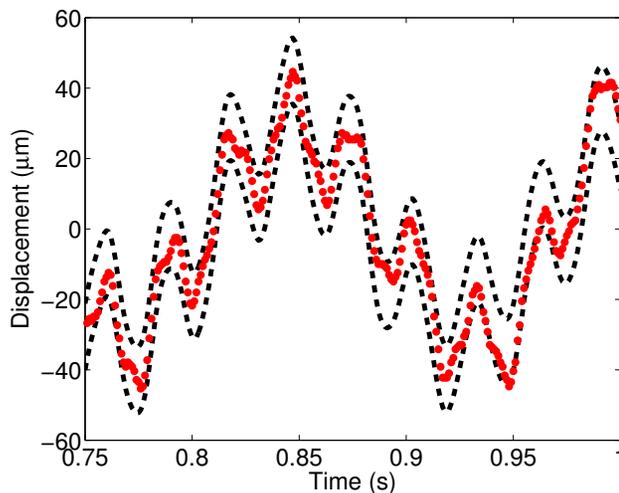


Calibrate on [0, 1]



Calibrate on [0.25, 1.25]

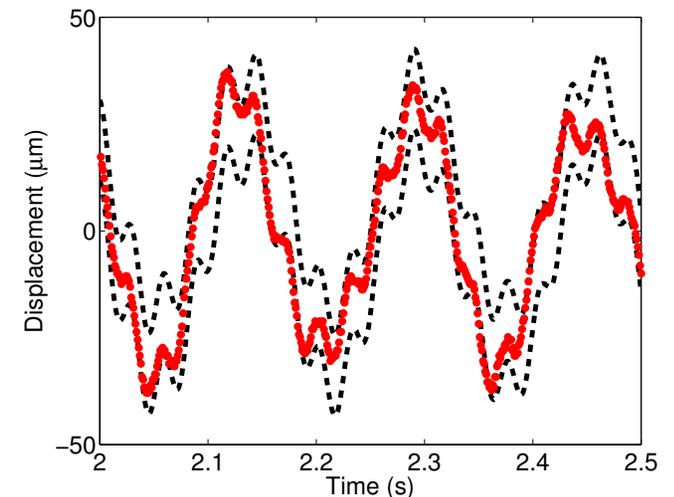
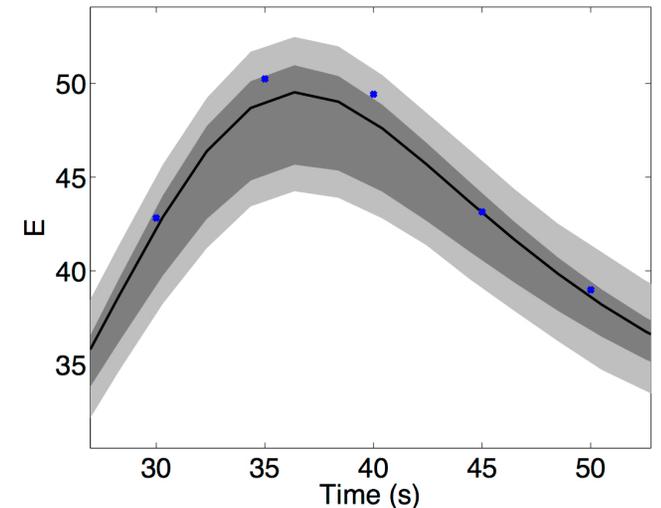
**Note:** We have substantially extended calibration regime.



# Concluding Remarks

## Notes:

- UQ requires a synergy between engineering, statistics, and applied mathematics.
- Model calibration, model selection, uncertainty propagation and experimental design are natural in a Bayesian framework.
- Goal is to predict model responses with quantified and reduced uncertainties.
- Parameter selection is critical to isolate identifiable and influential parameters.
- Surrogate models critical for computationally intensive simulation codes.
- Codes and packages: Sandia Dakota, R, MATLAB, Python, nanoHUB.
- *Prediction is very difficult, especially if it's about the future, Niels Bohr.*



# References

## Books:

- R.C. Smith, *Uncertainty Quantification: Theory, Implementation, and Applications*, SIAM, Philadelphia, 2014.

## Incomplete References:

### ***Orthogonal Polynomial Methods and High-Dimensional Approximation Theory:***

- M. Babuška, F. Nobile and R. Tempone, *Numer. Math.*, 2005
- A. Cohen, R. De Vore and C. Schwab, *Analysis and Applications*, 2011
- M. Gunzburger, C.G. Webster and G. Zhang, *Acta Numerica*, 2014.
- O.P. Le Maître and O.M. Knio, *Spectral Methods for Uncertainty Quantification*, 2010
- S., *Uncertainty Quantification: Theory, Implementation, and Applications*, 2014.
- A.L. Teckentrup, P. Jantsch, M. Gunzburger and C.G. Webster, *SIAM/ASA J. Uncert. Quant.*, 2015
- D. Xiu, *Numerical Methods for Stochastic Computations: A Spectral Method Approach*, 2010.

# References

## Incomplete References:

### ***Sparse Grids:***

- H-J. Bungartz and M. Griebel, *Acta Numerica*, 2004
- M. Gunzburger et al., *Water Resources Research*, 2013.
- F. Nobile, R. Tempone and C.G. Webster, *SIAM J. Num. Anal.*, 2008

### ***Compressed Sensing:***

- A. Chkifra, N. Dexter, H. Tran and C.G. Webster, *Mathematics of Computation*, *Submitted*

## Infinite-Dimensional Bayesian Inference:

- A.M. Stuart, *Acta Numerica* 2010
- T. Bui-Thanh et al., *SIAM J. Sci. Comput.*, 2013
- S.J. Vollmer, *SIAM/ASA J. Uncertainty Quantification*, 2015.
- T. Bui-Thanh and Q. Nguyen, *Inverse Problems and Imaging*, 2016,