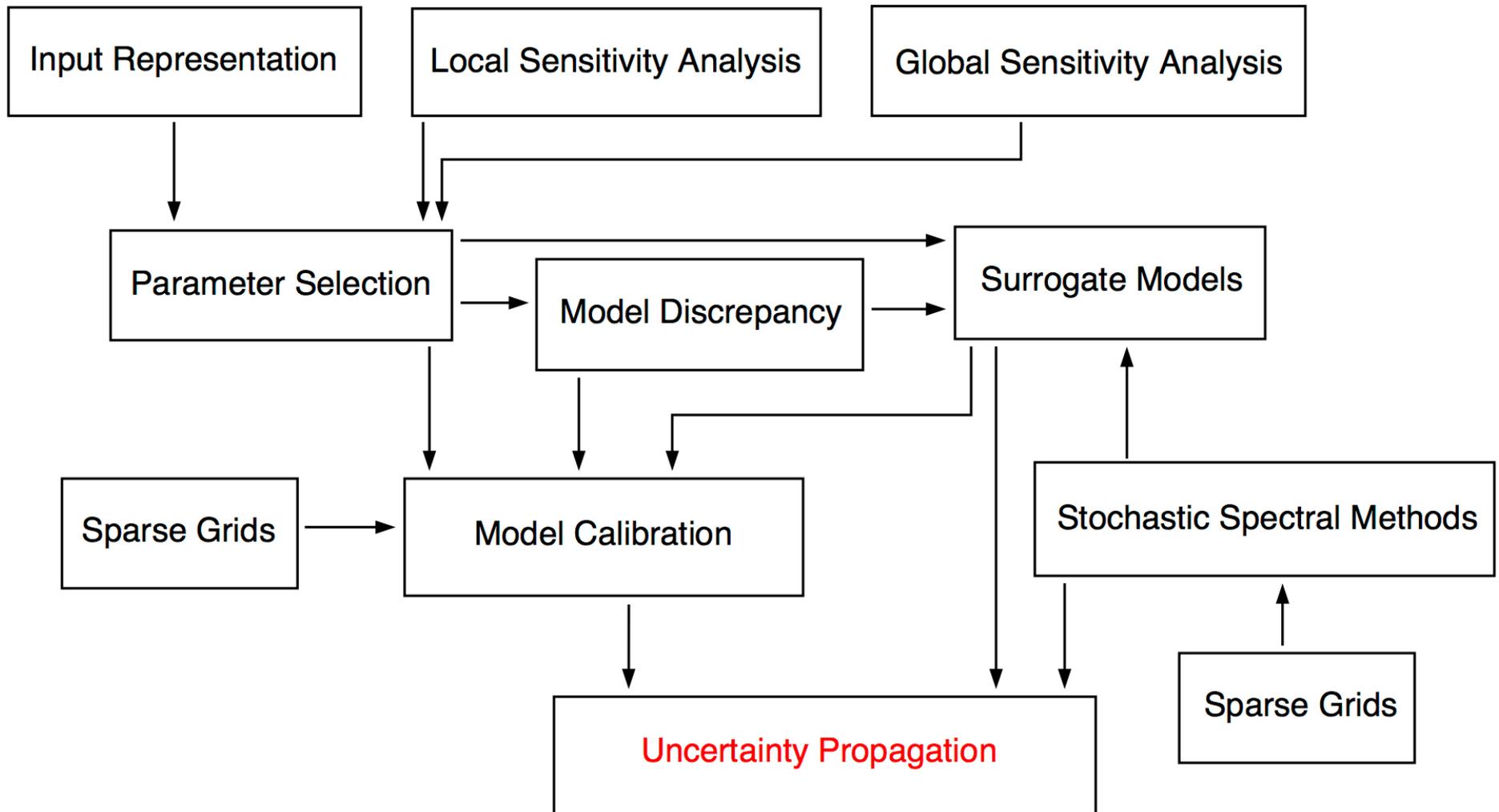


Steps in Uncertainty Quantification

Note: Uncertainty quantification requires synergy between statistics, mathematics and application area.



Uncertainty Propagation

Setting:

- We assume that we have determined distributions for parameters
 - e.g., Bayesian inference, prior experiments, expert opinion

$$\dot{T}_1 = \lambda_1 - d_1 T_1 - (1 - \varepsilon)k_1 VT_1$$

$$\dot{T}_2 = \lambda_2 - d_2 T_2 - (1 - f\varepsilon)k_2 VT_2$$

$$\dot{T}_1^* = (1 - \varepsilon)k_1 VT_1 - \delta T_1^* - m_1 ET_1^*$$

$$\dot{T}_2^* = (1 - f\varepsilon)k_2 VT_2 - \delta T_2^* - m_2 ET_2^*$$

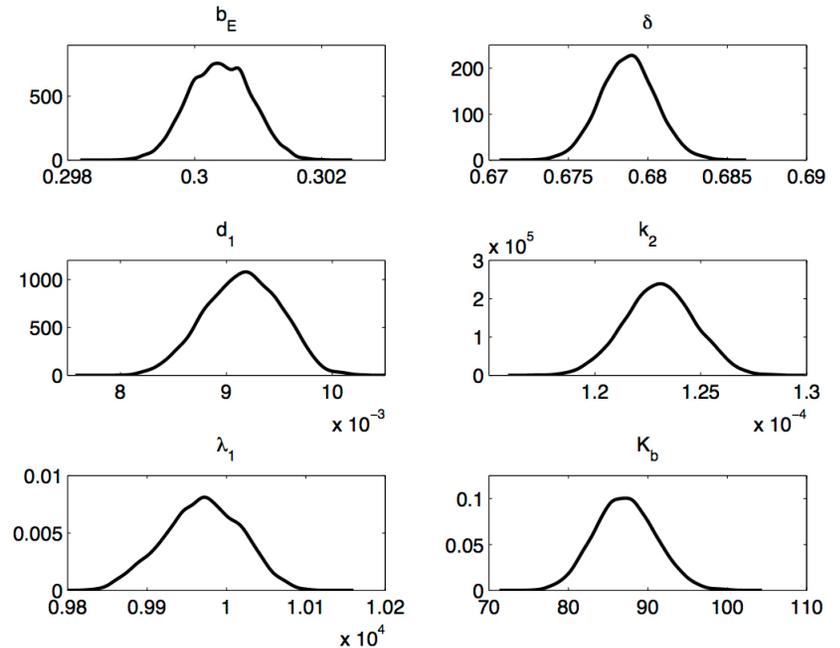
$$\dot{V} = N_T \delta (T_1^* + T_2^*) - cV - [(1 - \varepsilon)\rho_1 k_1 T_1 + (1 - f\varepsilon)\rho_2 k_2 T_2] V$$

$$\dot{E} = \lambda_E + \frac{b_E (T_1^* + T_2^*)}{T_1^* + T_2^* + K_b} E - \frac{d_E (T_1^* + T_2^*)}{T_1^* + T_2^* + K_d} E - \delta_E E$$

Goal: Construct statistics for quantities of interest

- e.g., Expected viral load in HIV patient with appropriate uncertainty intervals
- Note: Often involves moderate to high-dimensional integration

$$\mathbb{E}[V(t)] = \int_{\mathbb{R}^6} V(t, q) \rho(q) dq$$



Forward Uncertainty Propagation: Linear Models

Linear Models: Analytic mean and variance relations

Example: Linear stress-strain relation

$$\Upsilon_i = Ee_i + E_2e_i^3 + \varepsilon_i, \quad i = 1, \dots, n$$

Model Statistics:

Let \bar{E} , \bar{E}_2 and $\text{var}(E)$, $\text{var}(E_2)$ denote parameter means and variance. Then

$$\mathbb{E}[Ee_i + E_2e_i^3] = \bar{E}e_i + \bar{E}_2e_i^3$$

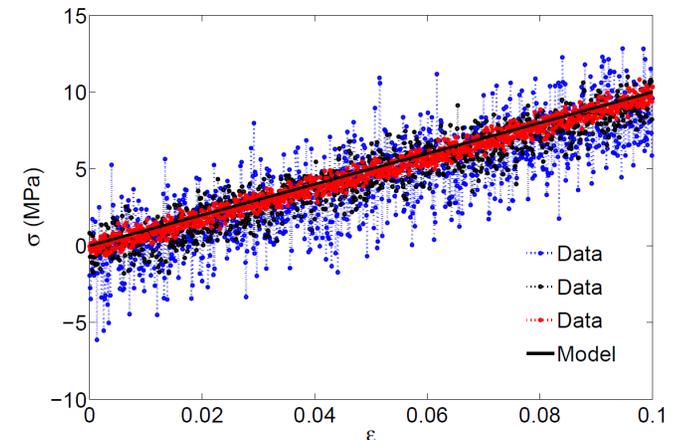
$$\text{var}[Ee_i + E_2e_i^3] = e_i^2 \text{var}(E) + e_i^6 \text{var}(E_2) + 2e_i^4 \text{cov}(E, E_2)$$

Response Statistics: Assume measurement errors uncorrelated from model response.

$$\mathbb{E}[\Upsilon_i] = \bar{E}e_i + \bar{E}_2e_i^3$$

$$\text{var}[\Upsilon_i] = e_i^2 \text{var}(E) + e_i^6 \text{var}(E_2) + 2e_i^4 \text{cov}(E, E_2) + \text{var}(\varepsilon_i)$$

Problem: Models are almost always nonlinearly parameterized



Forward Uncertainty Propagation: Sampling Methods

Strategy 1: Randomly sample from parameter and measurement error distributions and propagate through model to quantify response uncertainty.

Advantages:

- Applicable to nonlinear models.
- Parameters can be correlated and non-Gaussian.
- Straight-forward to apply and convergence rate is independent of number of parameters.
- Can directly incorporate both parameter and measurement uncertainties.

Disadvantages:

- Very slow convergence rate: $\mathcal{O}(1/\sqrt{M})$ where M is the number of samples.
- 100-fold more evaluations required to gain additional place of accuracy.
- This motivates numerical analysis techniques.

Numerical Quadrature

Motivation: Computation of expected values requires approximation of integrals

$$\mathbb{E}[u(t, x)] = \int_{\mathbb{R}^p} u(t, x, q) \rho(q) dq$$

Example: HIV model

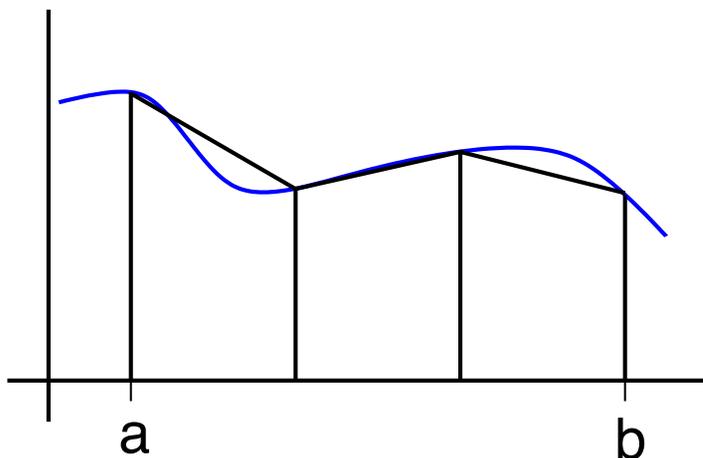
$$\mathbb{E}[V(t)] = \int_{\mathbb{R}^6} V(t, q) \rho(q) dq$$

Numerical Quadrature:

$$\int_{\mathbb{R}^p} f(q) \rho(q) dq \approx \sum_{r=1}^R f(q^r) w^r$$

Questions:

- How do we choose the quadrature points and weights?
 - E.g., Newton-Cotes; e.g., trapezoid rule



$$\int_a^b f(q) dq \approx \frac{h}{2} \left[f(a) + f(b) + 2 \sum_{r=1}^{R-2} f(q^r) \right]$$

$$q^r = a + hr, \quad h = \frac{b-a}{R-1}$$

Numerical Quadrature

Motivation: Computation of expected values requires approximation of integrals

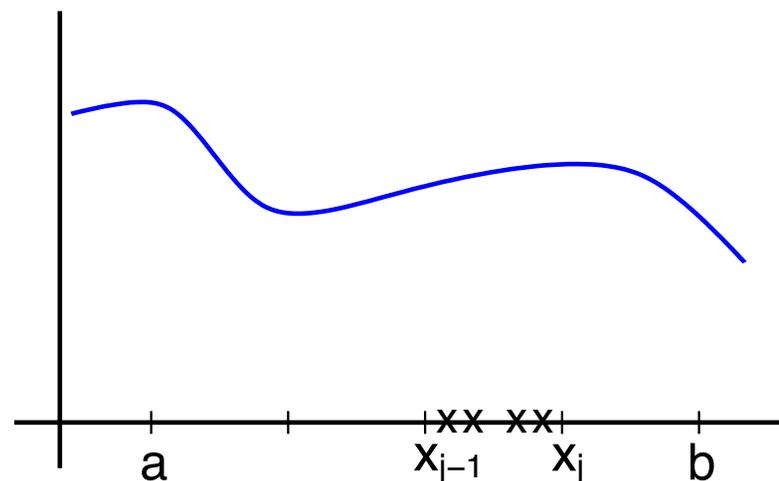
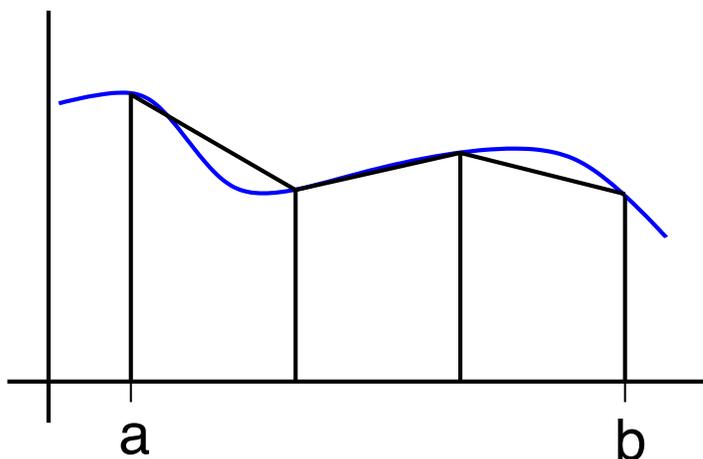
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Numerical Quadrature:

$$\int_{\mathbb{R}^p} f(q) \rho(q) dq \approx \sum_{r=1}^R f(q^r) w^r$$

Questions:

- How do we choose the quadrature points and weights?
 - E.g., Newton-Cotes, Gaussian algorithms



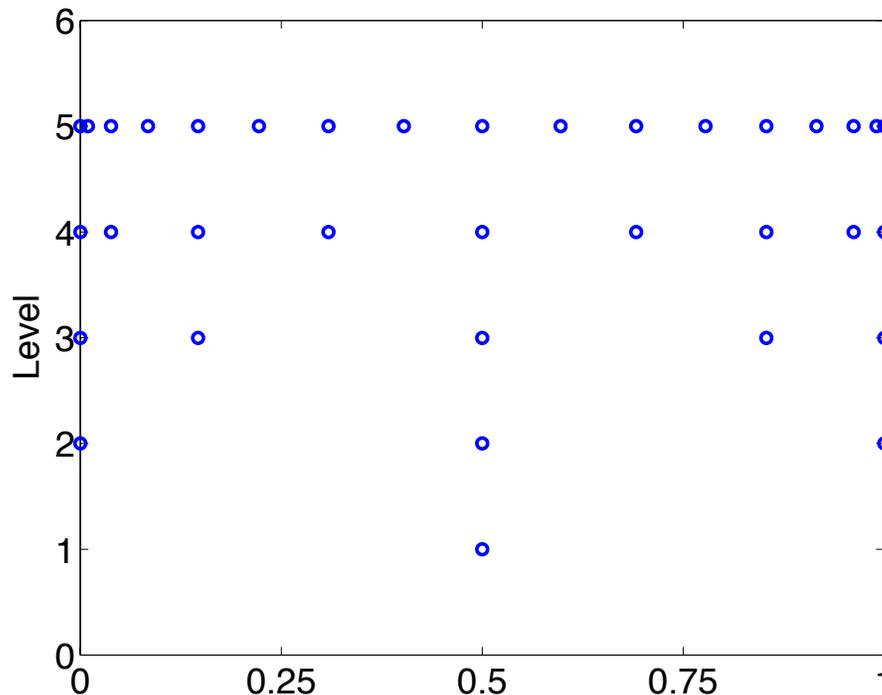
Numerical Quadrature

Numerical Quadrature:

$$\int_{\mathbb{R}^p} f(q) \rho(q) dq \approx \sum_{r=1}^R f(q^r) w^r$$

Questions:

- Can we construct nested algorithms to improve efficiency?
 - E.g., employ Clenshaw-Curtis points

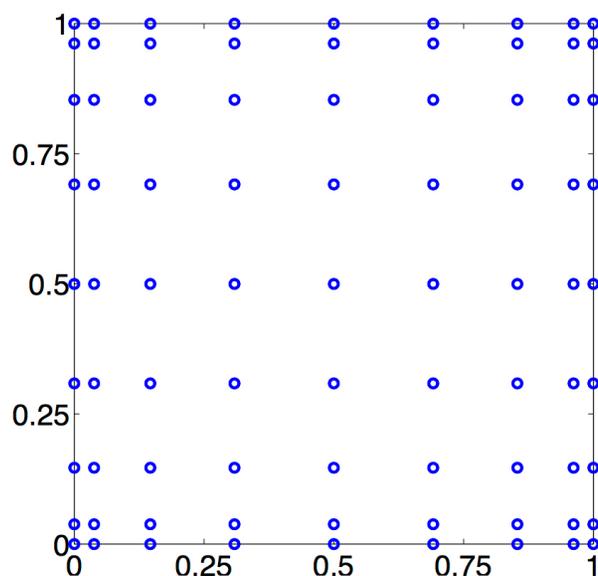


Numerical Quadrature

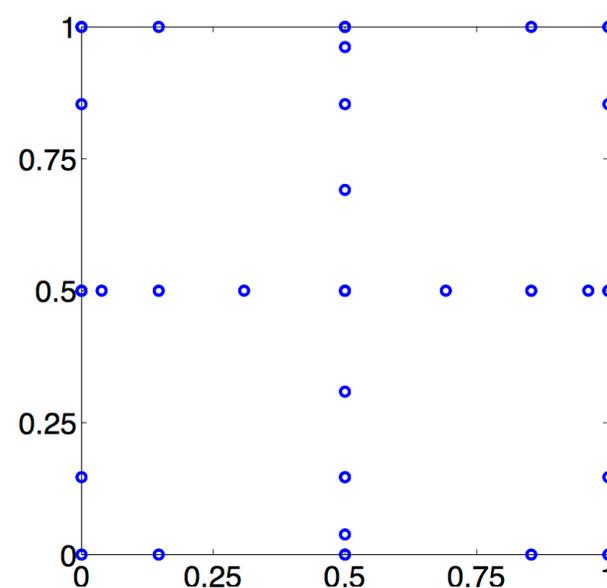
Questions:

- How do we reduce required number of points while maintaining accuracy?

Tensored Grids: Exponential growth



Sparse Grids: Same accuracy



p	R_ℓ	Sparse Grid \mathcal{R}	Tensored Grid $R = (R_\ell)^p$
2	9	29	81
5	9	241	59,049
10	9	1581	$> 3 \times 10^9$
50	9	171,901	$> 5 \times 10^{47}$
100	9	1,353,801	$> 2 \times 10^{95}$

Numerical Quadrature

Problem:

- Accuracy of methods diminishes as parameter dimension p increases
- Suppose $f \in C^\alpha([0, 1]^p)$
- Tensor products: Take R_ℓ points in each dimension so $R = (R_\ell)^p$ total points
- Quadrature errors:

$$\text{Newton-Cotes: } E \sim \mathcal{O}(R_\ell^{-\alpha}) = \mathcal{O}(R^{-\alpha/p})$$

$$\text{Gaussian: } E \sim \mathcal{O}(e^{-\beta R_\ell}) = \mathcal{O}(e^{-\beta \sqrt[p]{R}})$$

$$\text{Sparse Grid: } E \sim \mathcal{O}\left(\mathcal{R}^{-\alpha} \log(\mathcal{R})^{\frac{(p-1)(\alpha+1)}{p}}\right)$$

Numerical Quadrature

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$$\text{Sparse Grid: } E \sim \mathcal{O}\left(\mathcal{R}^{-\alpha} \log(\mathcal{R})^{\frac{(p-1)(\alpha+1)}{p}}\right)$$

- Alternative: Monte Carlo quadrature

$$\int_{\mathbb{R}^p} f(q) \rho(q) dq \approx \frac{1}{R} \sum_{r=1}^R f(q^r) \quad , \quad E \sim \left(\frac{1}{\sqrt{R}}\right)$$

- Advantage: Errors independent of dimension p
- Disadvantage: Convergence is very slow!

Numerical Quadrature

Problem:

- Accuracy of methods diminishes as parameter dimension p increases
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- Advantage: Errors independent of dimension p
- Disadvantage: Convergence is very slow!

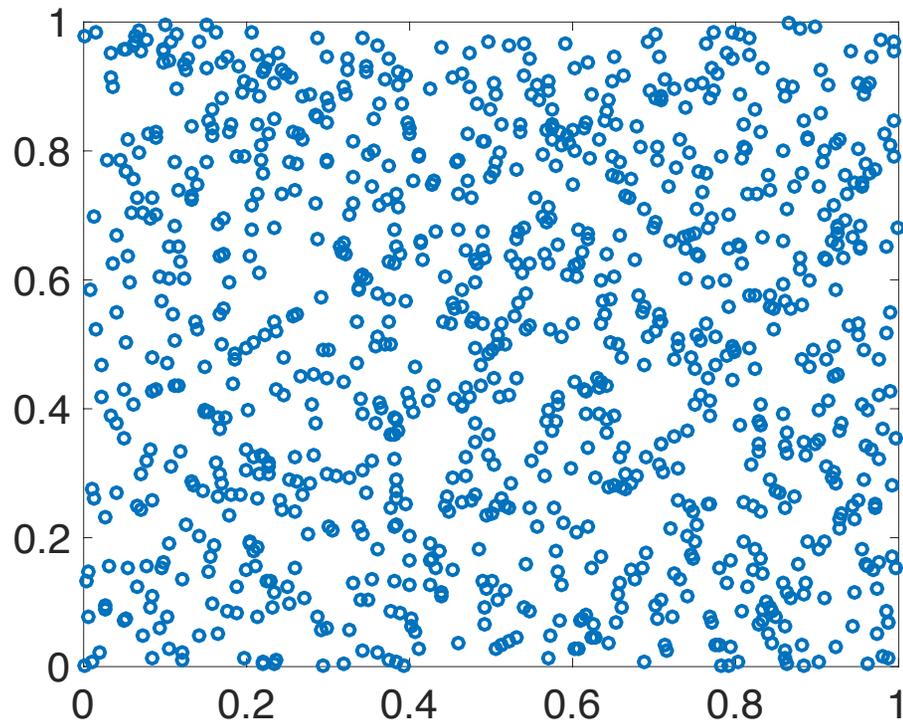
Conclusion: For high enough dimension p , monkeys throwing darts will beat Gaussian and sparse grid techniques!

Monte Carlo Sampling Techniques

Issues:

- Very low accuracy and slow convergence
- Random sampling may not “randomly” cover space ...

Samples from Uniform Distribution

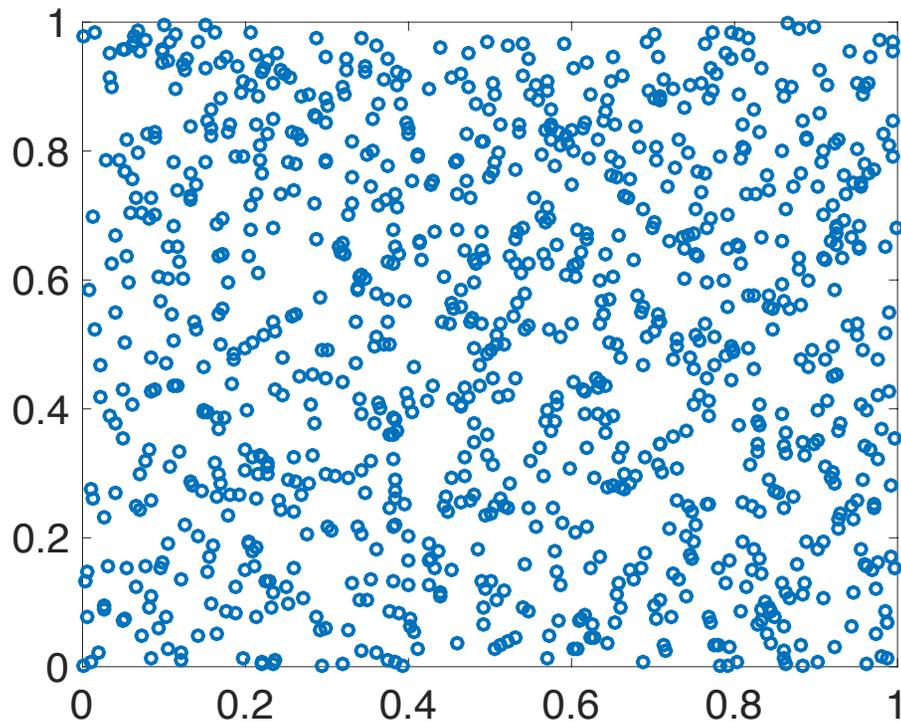


Monte Carlo Sampling Techniques

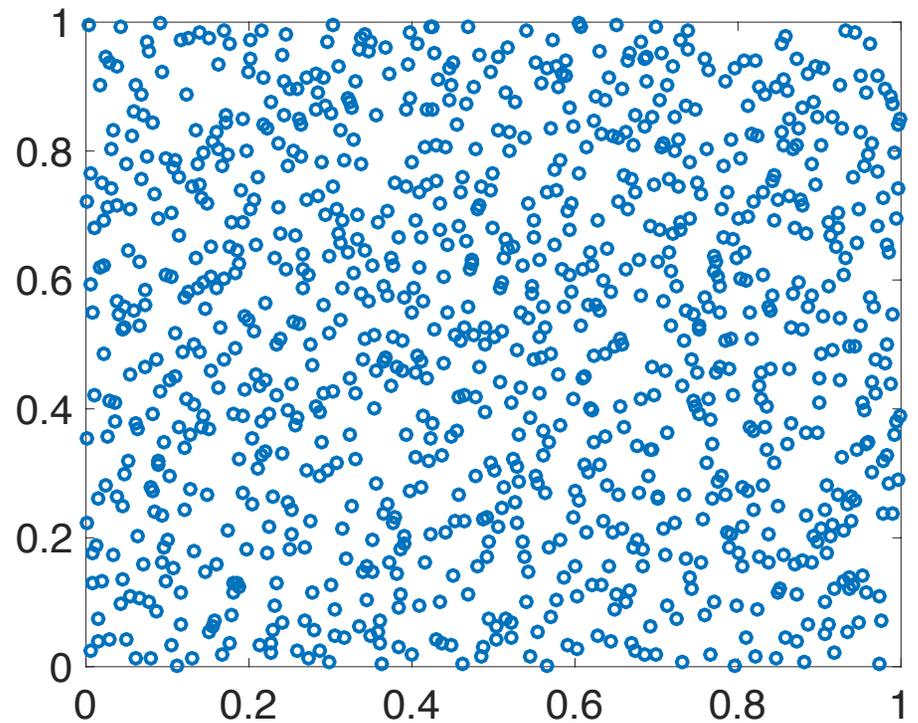
Issues:

- Very low accuracy and slow convergence
- Random sampling may not “randomly” cover space ...

Samples from Uniform Distribution



Sobol' Points



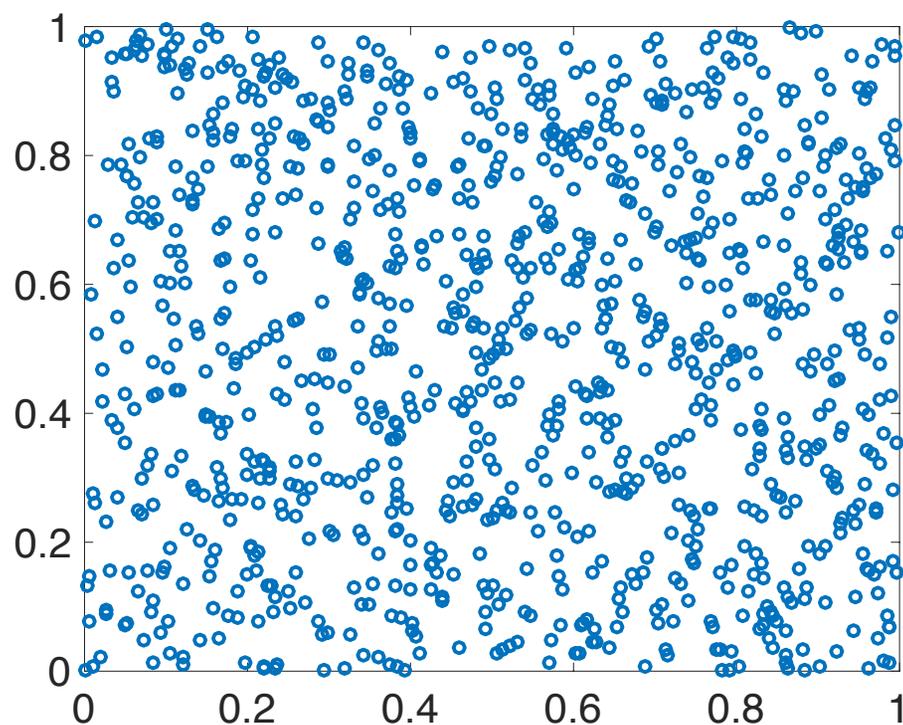
Sobol' Sequence: Use a base of two to form successively finer uniform partitions of unit interval and reorder coordinates in each dimension.

Quasi-Monte Carlo Sampling Techniques

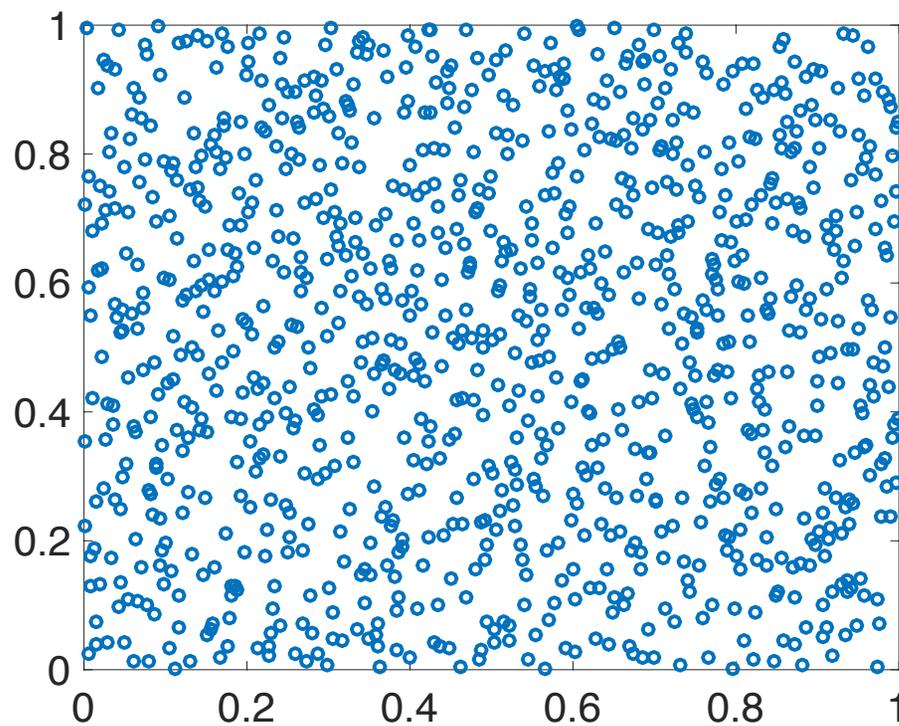
Issues:

- Very low accuracy and slow convergence
- Random sampling may not “randomly” cover space ...

Samples from Uniform Distribution



Sobol' Points



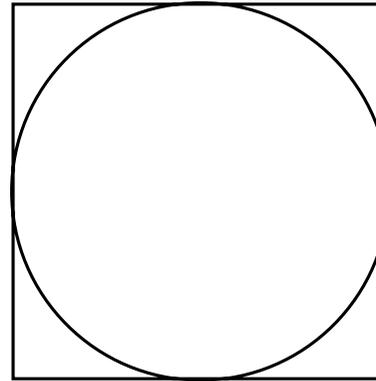
$$\int_{\mathbb{R}^p} f(\mathbf{q}) \rho(\mathbf{q}) d\mathbf{q} \approx \frac{1}{R} \sum_{r=1}^R f(\mathbf{q}^r) \quad , \quad E \sim \left(\frac{1}{\sqrt{R}} \right) \quad E \sim \mathcal{O} \left(\frac{(\log R)^\rho}{R} \right) \quad 83$$

Monte Carlo Sampling Techniques

Example: Use Monte Carlo sampling to approximate area of circle

$$\frac{A_c}{A_s} = \frac{\pi r^2}{4r^2} = \frac{\pi}{4}$$

$$\Rightarrow A_c = \frac{\pi}{4} A_s$$



Strategy:

- Randomly sample N points in square \Rightarrow approximately $N \frac{\pi}{4}$ in circle
- Count M points in circle

$$\Rightarrow \pi \approx \frac{4M}{N}$$

Quasi-Monte Carlo:

- SAMSI Program on *Quasi-Monte Carlo and High Dimensional Sampling Methods in Applied Math* in 2017-18

MATLAB Example

Monte Carlo Quadrature:

- Run `rand_points.m` to observe uniformly sampled and Sobol' points.
- Run `pi_approx.m` with different values of N to see if you observe convergence rate of $1/\sqrt{N}$

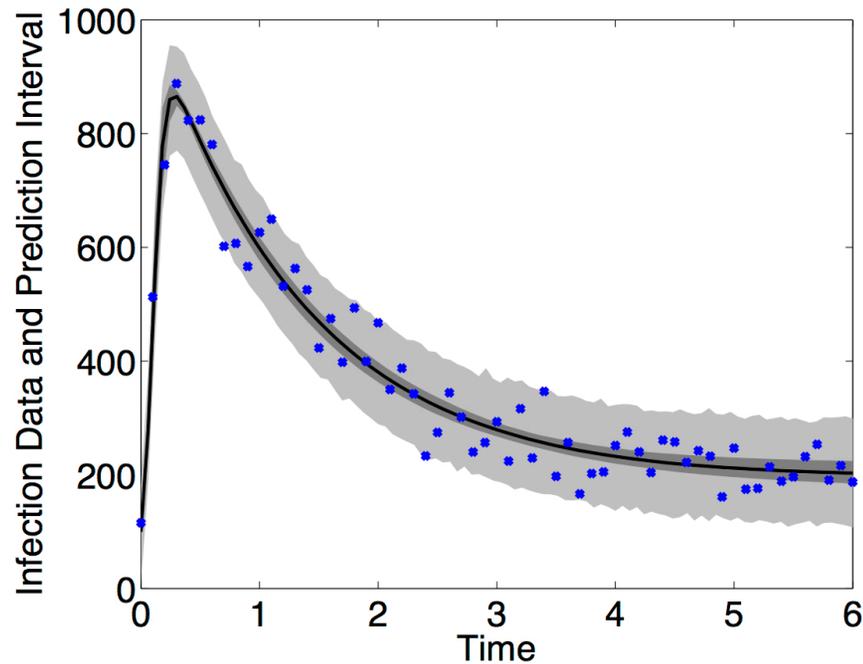
Website:

- <https://rsmith.math.ncsu.edu/DATAWORKS19/>

Confidence, Credible and Prediction Intervals

Note:

- We now know how to compute the mean response for the QoI.
- How do we compute appropriate intervals?



SIR Model:

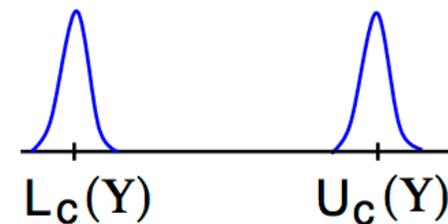
$$\frac{dS}{dt} = \delta N - \delta S - \gamma IS \quad , \quad S(0) = S_0 \quad \text{Susceptible}$$

$$\frac{dI}{dt} = \gamma IS - (r + \delta)I \quad , \quad I(0) = I_0 \quad \text{Infectious}$$

$$\frac{dR}{dt} = rI - \delta R \quad , \quad R(0) = R_0 \quad \text{Recovered}$$

Confidence, Credible and Prediction Intervals

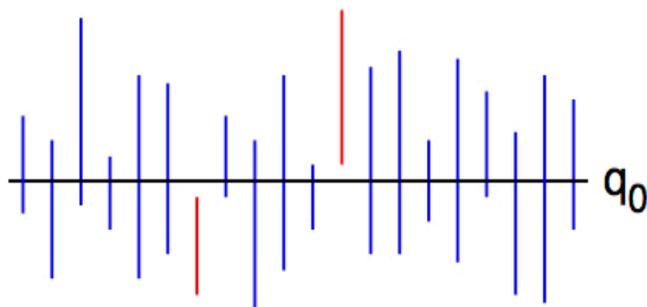
Data: $\Upsilon = [\Upsilon_1, \dots, \Upsilon_n]$ of iid random observations



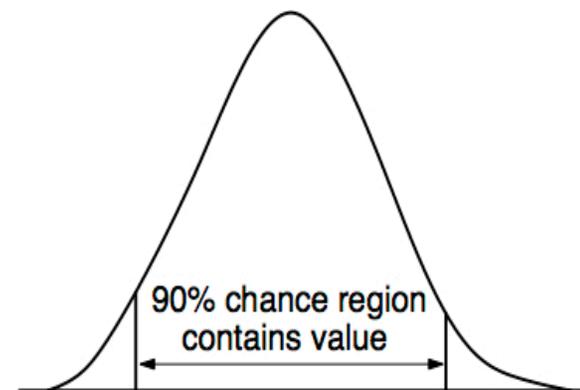
Confidence Interval (Frequentist): A $100 \times (1 - \alpha)\%$ confidence interval for a fixed, unknown parameter q_0 is a random interval $[L_c(\Upsilon), U_c(\Upsilon)]$, having probability at least $1 - \alpha$ of covering q_0 under the joint distribution of Υ .

Credible Interval (Bayesian): A $100 \times (1 - \alpha)\%$ credible interval is that having probability at least $1 - \alpha$ of containing q .

Strategy: Sample out of parameter density $\rho_Q(q)$



90% Confidence Intervals



90% Credible Interval

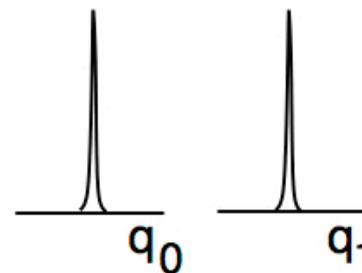
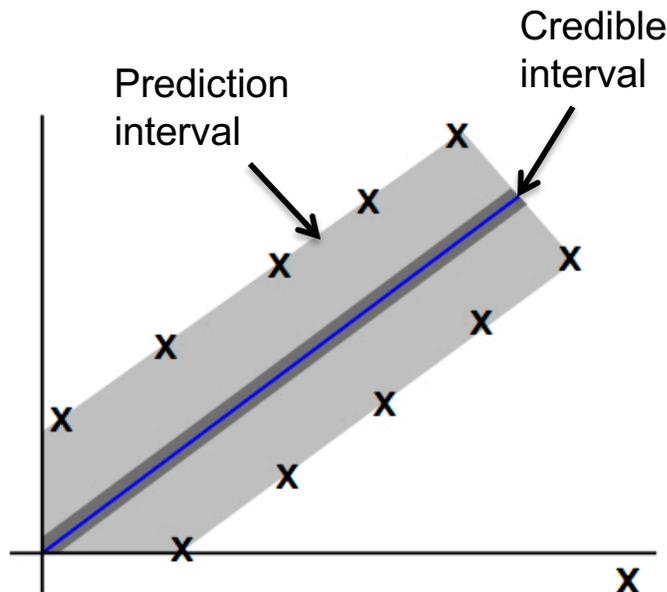
Confidence, Credible and Prediction Intervals

Data: $\Upsilon = [\Upsilon_1, \dots, \Upsilon_n]$ of iid random observations

Prediction Interval: A $100 \times (1 - \alpha)\%$ prediction interval for a future observable Υ_{n+1} is a random interval $[L_c(\Upsilon), U_c(\Upsilon)]$ having probability at least $1 - \alpha$ of containing Υ_{n+1} under the joint distribution of $(\Upsilon, \Upsilon_{n+1})$.

Example: Consider linear model

$$\Upsilon_i = q_0 + q_1 x_i + \varepsilon_i, \quad i = 1, \dots, n$$



Example: HIV Model

Model: $\dot{T}_1 = \lambda_1 - d_1 T_1 - (1 - \varepsilon)k_1 VT_1$

$$\dot{T}_2 = \lambda_2 - d_2 T_2 - (1 - f\varepsilon)k_2 VT_2$$

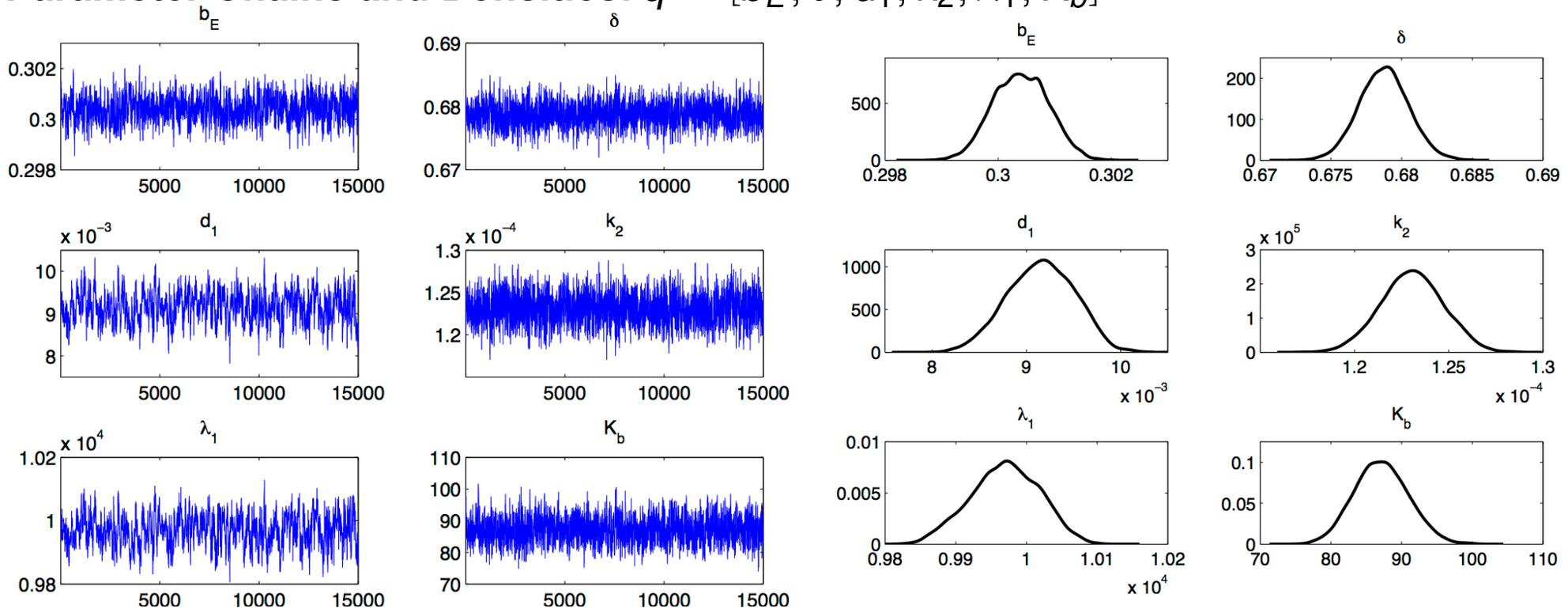
$$\dot{T}_1^* = (1 - \varepsilon)k_1 VT_1 - \delta T_1^* - m_1 ET_1^*$$

$$\dot{T}_2^* = (1 - f\varepsilon)k_2 VT_2 - \delta T_2^* - m_2 ET_2^*$$

$$\dot{V} = N_T \delta (T_1^* + T_2^*) - cV - [(1 - \varepsilon)\rho_1 k_1 T_1 + (1 - f\varepsilon)\rho_2 k_2 T_2] V$$

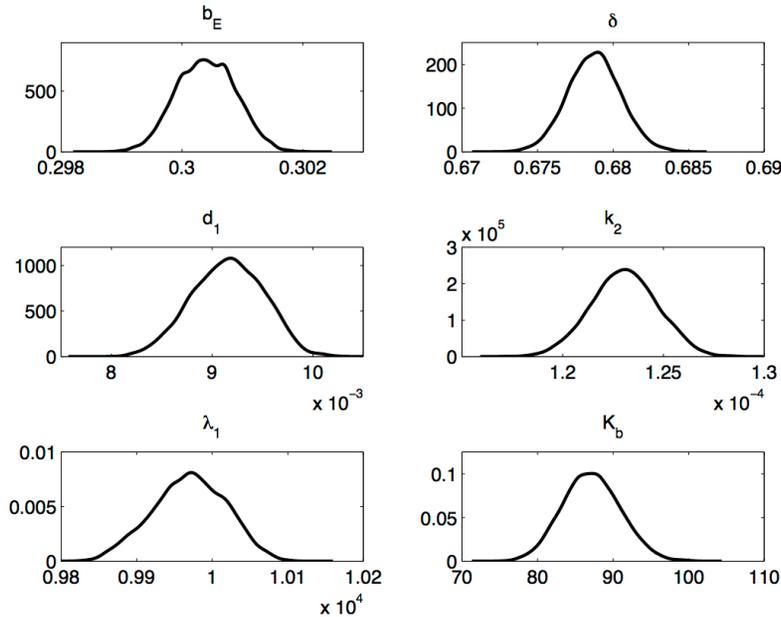
$$\dot{E} = \lambda_E + \frac{b_E (T_1^* + T_2^*)}{T_1^* + T_2^* + K_b} E - \frac{d_E (T_1^* + T_2^*)}{T_1^* + T_2^* + K_d} E - \delta_E E$$

Parameter Chains and Densities: $q = [b_E, \delta, d_1, k_2, \lambda_1, K_b]$



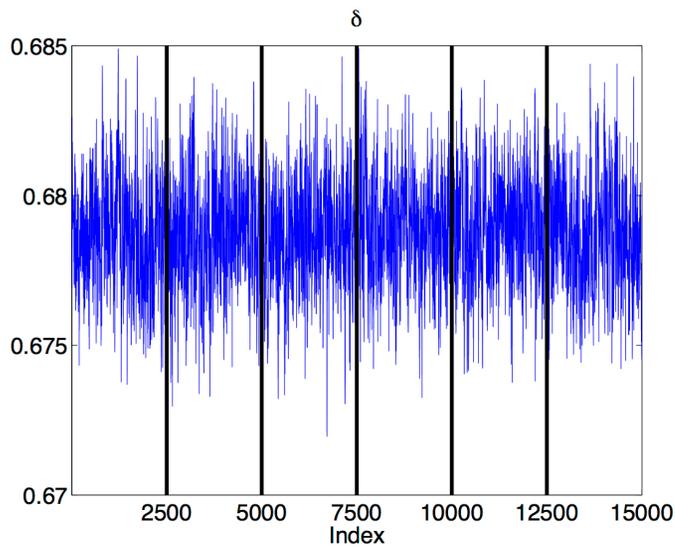
Propagation of Uncertainty – HIV Example

Parameter Densities:

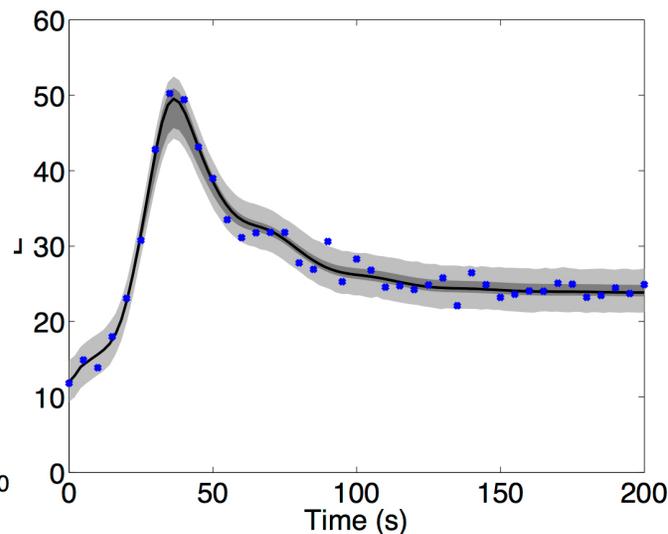


Techniques:

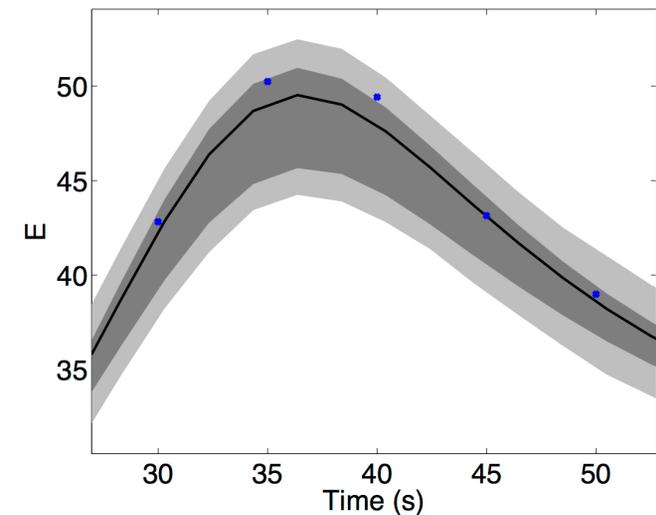
- Sample from parameter and observation error densities to construct mean response, credible intervals, and prediction intervals for QoI.
- Slow convergence rate $\mathcal{O}(1/\sqrt{M})$



Samples from Chain



Data, Credible Intervals and Prediction Intervals



Non-Gaussian Credible and Prediction Intervals

Use of Prediction Intervals: Nuclear Power Plant Design

Subchannel Code (COBRA-TF): numerous closure relations, ~70 parameters

e.g., Dittus—Boelter Relation

$$Nu = 0.023 Re^{0.8} Pr^{0.4}$$

Nu : Nusselt number

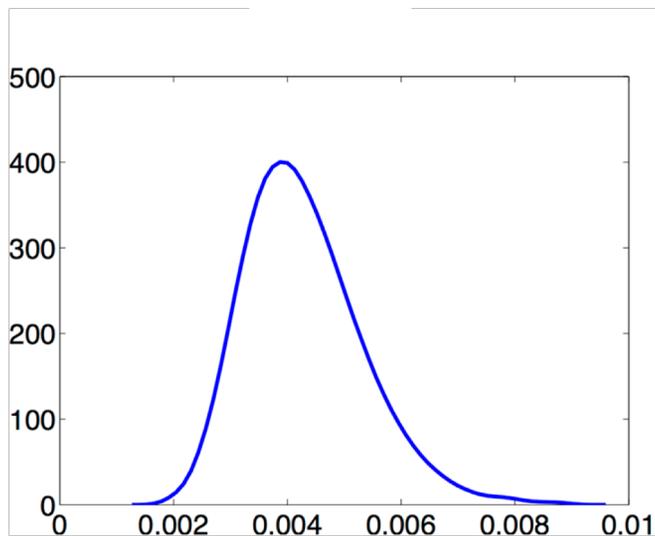
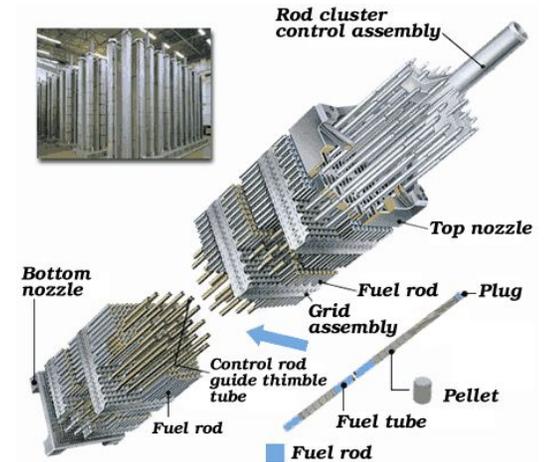
Re : Reynolds number

Pr : Prandtl number

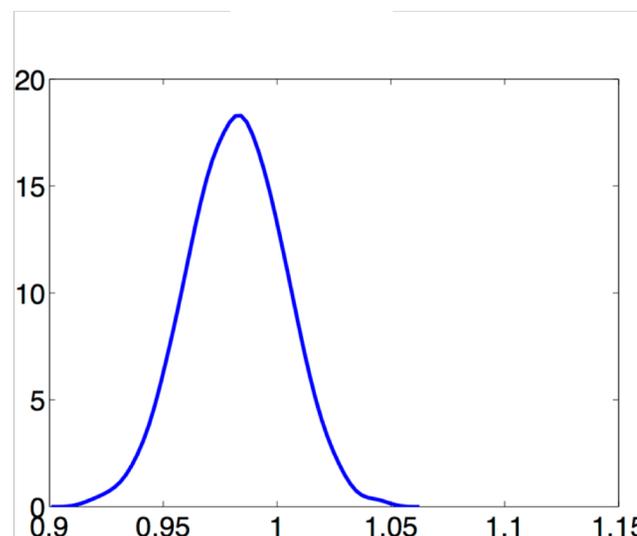
Industry Standard: Employ conservative, uniform, bounds

i.e., [0, 0.046], [0, 1.6], [0,0.8]

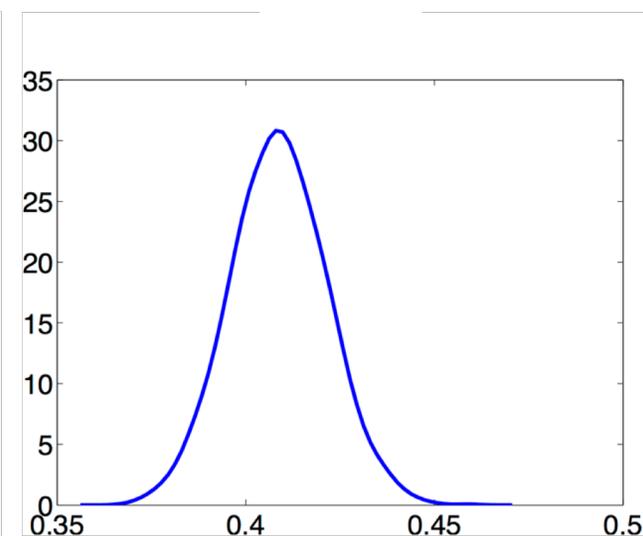
Bayesian Analysis: Employ conservative bounds as priors



$2\sigma \approx 0.0035$



$2\sigma \approx 0.06$

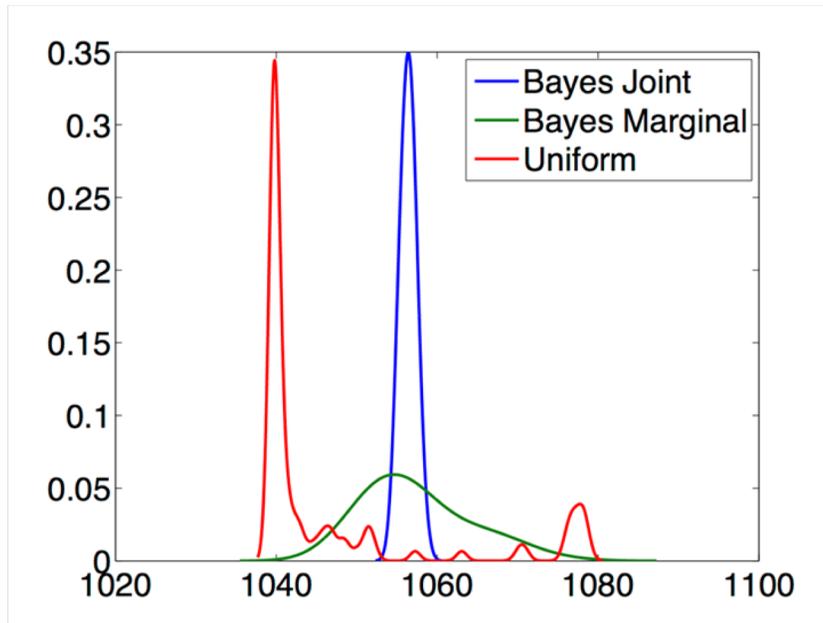


$2\sigma \approx 0.03$

Note: Substantial reduction in parameter uncertainty

Use of Prediction Intervals: Nuclear Power Plant Design

Strategy: Propagate parameter uncertainties through COBRA-TF to determine uncertainty in maximum fuel temperature



Notes:

- Temperature uncertainty reduced from 40 degrees to 5 degrees
- Can run plant 20 degrees hotter, which significantly improves efficiency

Ramification: Savings of **10 billion dollars per year** for US power plants

Issues:

- We considered only one of many closure relations
- Nuclear regulatory commission takes years to change requirements and codes

Good News: We are now working with Westinghouse to reduce uncertainties.

MATLAB Example

SIR Model:

$$\frac{dS}{dt} = \delta N - \delta S - \gamma IS \quad , \quad S(0) = S_0 \quad \text{Susceptible}$$

$$\frac{dI}{dt} = \gamma IS - (r + \delta)I \quad , \quad I(0) = I_0 \quad \text{Infectious}$$

$$\frac{dR}{dt} = rI - \delta R \quad , \quad R(0) = R_0 \quad \text{Recovered}$$

Note:

- Run either the 3 or 4 parameter model and compute the prediction intervals.

Website:

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